

LICS 2024

# $\partial$ is for Dialectica

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What this talk is about

## Joining *Dialectica* and Differentiation

*September 2015 in Paris, about Pédrot's thesis:  
"that's (just) differential lambda-calculus"*

What this talk is about

## Joining **Dialectica** and Reverse Differentiation

*June 2019 in Nantes, about "λ the ultimate backpropagator":  
"That's (just) Dialectica"*

What this talk is about

Joining **Dialectica** and **Differential  $\lambda$ -calculus**  
through  
**Reverse Differentiation**

*June 2024 in Tallinn*

# What this talk is not about

- ▶ Joining **Dialectica** and **Differential Linear Logic** through **Reverse Differentiation**
  
- ▶ Joining **Dialectica** and **Differential Categories** through **Reverse Differentiation**

# Gödel's Dialectica Transformation

1.  $(F \wedge G)' = (\exists yv) (zw) [A(y, z, x) \wedge B(v, w, u)].$
2.  $(F \vee G)' = (\exists yvt) (zw) [t=0 \wedge A(y, z, x) \vee t=1 \wedge B(v, w, u)].$
3.  $[(s)F]' = (\exists Y) (sz) A(Y(s), z, x).$
4.  $[(\exists s)F]' = (\exists sy) (z) A(y, z, x).$
5.  $(F \supset G)' = (\exists VZ) (yw) [A(y, Z(yw), x) \supset B(V(y), w, u)].$
6.  $(\neg F)' = (\exists \bar{Z}) (y) \neg A(y, \bar{Z}(y), x).$



*Kurt Gödel (1958). Über eine bisher noch nicht benützte Erweiterung des finiten Standpunktes. Dialectica.*

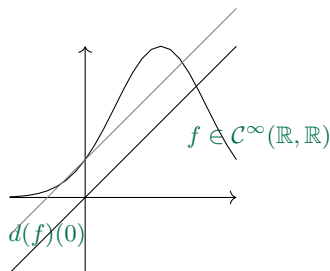
- ▶ Validates semi-classical axioms:
  - ▶ Markov's principle :  $\neg\neg\exists xA \rightarrow \exists xA$  when  $A$  is decidable.
- ▶ Numerous applications :
  - ▶ Soundness results
  - ▶ **Proof mining**: applying Dialectica to theorems in analysis extract quantitative information.
- ▶ Reformulated through Linear logic, or Dialectica Categories



*V. de Paiva. 1989. A Dialectica-like Model of Linear Logic.,*

# Differentiation

- **Differentiation** is finding the best linear approximation to a function at a point.



$$\text{For } f : \mathbb{R} \rightarrow \mathbb{R}, x \in \mathbb{R}$$
$$D_x f : v \in \mathbb{R} \mapsto f'(x) \cdot v \in \mathbb{R}$$

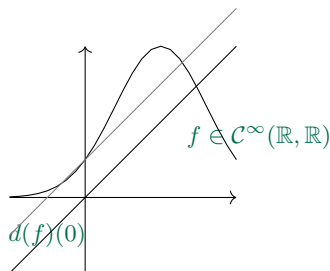
$$\text{For } f : E \rightarrow F, x \in E$$
$$D_x f : v \in E \mapsto D_x f(v) \in F$$

$$\text{Chain Rule : } D_x(f \circ g) = D_{g(x)}f \circ D_xg$$

- **Differentiation** is a mathematical operation which needs to be fitted to logical and computer science use.
  - **Algorithmic Differentiation** : differentiating sequences of many-valued functions efficiently.
  - **Differential Linear Logic and Differential  $\lambda$ -calculus** : Differentiating proofs and  $\lambda$ -terms.

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# A peek into Dialectica interpretation of functions

$$(A \rightarrow B)_D = \exists f g \forall xy (A_D(x, gxy) \rightarrow B_D(fx, y))$$

**Question:**  $(A \Rightarrow B)_D; (B \Rightarrow C)_D \rightsquigarrow (A \Rightarrow C)_D?$

**Usual explanation :** least unconstructive prenexation.

**Dynamic behaviour :** agrees to a **chain rule**.

- ▶ Variables  $f$  agree to the usual composition rule.
- ▶ Variables  $g$  agree to a chain rule:  $g_3(x, y) = g_1(x, g_2(f_1x, y))$

Mathematical meaning : it's some kind of approximation.

# Algorithmic Differentiation

How does one compute the differentiation of an algebraic expression, computed as a sequence of elementary operations ?

$$\begin{array}{l} \text{E.g. : } z = y + \cos(x^2) \\ x_1 = x_0^2 \quad x'_1 = 2x_0x'_0 \\ x_2 = \cos(x_1) \quad x'_2 = -x'_0 \sin(x_0) \\ z = y + x_2 \quad z' = y' + 2x_2x'_2 \end{array}$$

**Derivative of a sequence of instruction**



**sequence of instruction × sequence of derivatives**

**Forward Mode differentiation** [Wengert, 1964]

$$(x_1, x'_1) \rightarrow (x_2, x'_2) \rightarrow (z, z').$$

**Reverse Mode differentiation:** [Speelmaning, Rall, 1980s]

$x_1 \rightarrow x_2 \rightarrow z \rightarrow z' \rightarrow x'_2 \rightarrow x'_1$  while keeping formal the unknown derivative.

# Typing Algorithmic Differentiation

## Algorithmic differentiation:

making a choice when computing the chain rule:  $D_u(f \circ g) = D_{g(u)}f \circ D_u(g)$

## Typing Forward Mode differentiation :

$$g : E \Rightarrow F \rightsquigarrow \overrightarrow{D}g : E \Rightarrow E \multimap F.$$

The Linear negation:  $A^\perp \equiv A \multimap \perp \equiv \mathcal{L}(A, \mathbb{R}) \equiv A'$

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*Brunel, Mazza, Pagani. Backpropagation in the simply typed  $\lambda$ -calc. with linear negation.*

Reverse differentiation :  $(g, \overleftarrow{D}(g)) : (E \Rightarrow F) \times (E \Rightarrow F^\perp \multimap E^\perp)$

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# Types !

Programs and variable are **typed**  
by logical formulas which describe their behavior

$$A \rightsquigarrow \exists x : \overbrace{\mathbb{W}(A)}^{\text{witness}}, \forall u : \underbrace{\mathbb{C}(A)}_{\text{opponent}}, A_D[x, u]$$

**Witness and counter types :**

$$\begin{aligned} \mathbb{C}(A \Rightarrow B) &= \mathbb{C}(A) \times \mathbb{C}(B) \\ \mathbb{W}(A \Rightarrow B) &= (\mathbb{W}(A) \Rightarrow \mathbb{W}(B)) \times (\mathbb{W}(A) \Rightarrow \mathbb{C}(B) \Rightarrow \mathbb{C}(A)) \end{aligned}$$

**Reverse Mode differentiation:**

$$\text{Functorial} : (h, \overleftarrow{D}h) : (A \Rightarrow B) \times (A \Rightarrow B^\perp \multimap A^\perp)$$

However:

- ▶ Having the same type does not mean you're the same program.
- ▶ Some french (linear) logicians have a strong opinion on what proof/program differentiation should be.

# Types !

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$$A \rightsquigarrow \exists \overbrace{x : \mathbb{W}(A)}^{\text{global witness}}, \forall \underbrace{u : \mathbb{C}(A)}_{\text{local opponent}}, A_D[x, u]$$

**Witness and counter for implication types :**

$$\mathbb{C}(A \Rightarrow B) = \mathbb{C}(A) \times \mathbb{C}(B)$$
$$\mathbb{W}(A \Rightarrow B) = \overbrace{(\mathbb{W}(A) \Rightarrow \mathbb{W}(B))}^{\text{function}} \times \left( \mathbb{W}(A) \Rightarrow \underbrace{\mathbb{C}(B) \Rightarrow \mathbb{C}(A)}_{\text{reverse derivative}} \right)$$

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Let's say  $x, u, f, g$  are  $\lambda$ -terms.

The computational Dialectica : a reverse Differential  $\lambda$ -calculus

"Behind every successful proof there is an exhausted program"



# Pédrot's Dialectica Transformation

Making Dialectica act on  $\lambda$ -terms instead of formulas.

## Soundness [Ped14]

If  $\Gamma \vdash t : A$  in the source then we have in the target

- ▶  $\mathbb{W}(\Gamma) \vdash t^\bullet : \mathbb{W}(A)$
- ▶  $\mathbb{W}(\Gamma) \vdash t_x : \mathbb{C}(A) \Rightarrow \mathfrak{M} \mathbb{C}(X)$  provided  $x : X \in \Gamma$ .

## A global and a local transformation

$$\begin{array}{ll} x^\bullet & := x & (\lambda x. t)^\bullet & := (\lambda x. t^\bullet, \lambda \pi x. t_x \pi) \\ x_x & := \lambda \pi. \{\pi\} & (\lambda x. t)_y & := \lambda \pi. (\lambda x. t_y) \pi.1 \pi.2 \\ x_y & := \lambda \pi. \emptyset \text{ if } x \neq y & (t u)^\bullet & := (t^\bullet.1) u^\bullet \end{array}$$

$$(t u)_y := \lambda \pi. (t_y (u^\bullet, \pi)) \circledast ((t^\bullet.2) \pi u^\bullet \ggg u_y)$$

# Differential $\lambda$ -calculus

Inspired by denotational models of Linear Logic in vector spaces of sequences, it introduces a differentiation of  $\lambda$ -terms.

$D(\lambda x.t)$  is the **linearization** of  $\lambda x.t$ , it substitute  $x$  linearly, and then it remains a term  $t'$  where  $x$  is free.

**Syntax:**

$$\begin{aligned}\Lambda^d &: S, T, U, V ::= 0 \mid s \mid s+T \\ \Lambda^s &: s, t, u, v ::= x \mid \lambda x.s \mid sT \mid \mathbf{D}s \cdot t\end{aligned}$$

**Operational Semantics:**

$$\begin{aligned}(\lambda x.s)T &\rightarrow_{\beta} s[T/x] \\ \mathbf{D}(\lambda x.s) \cdot t &\rightarrow_{\beta_D} \lambda x. \frac{\partial s}{\partial x} \cdot t\end{aligned}$$

where  $\frac{\partial s}{\partial x} \cdot t$  is the **linear substitution** of  $x$  by  $t$  in  $s$ .



*T. Ehrhard, L. Regnier. The differential lambda-calculus. TCS, 2004*  
*See the Alonzo Church award' talk on Wednesday !*

## The linear substitution ...

... which is not exactly a substitution

$$\frac{\partial y}{\partial x} \cdot t = \begin{cases} t & \text{if } x = y \\ 0 & \text{otherwise} \end{cases} \quad \frac{\partial}{\partial x}(tu) \cdot s = \left(\frac{\partial t}{\partial x} \cdot s\right)u + (Dt \cdot \left(\frac{\partial u}{\partial x} \cdot s\right))u$$

$$\frac{\partial}{\partial x}(\lambda y \cdot s) \cdot t = \lambda y \cdot \frac{\partial s}{\partial x} \cdot t \quad \frac{\partial}{\partial x}(Ds \cdot u) \cdot t = D\left(\frac{\partial s}{\partial x} \cdot t\right) \cdot u + Ds \cdot \left(\frac{\partial u}{\partial x} \cdot t\right)$$

$$\frac{\partial 0}{\partial x} \cdot t = 0 \quad \frac{\partial}{\partial x}(s + u) \cdot t = \frac{\partial s}{\partial x} \cdot t + \frac{\partial u}{\partial x} \cdot t$$

$\frac{\partial s}{\partial x} \cdot t$  represents  $s$  where  $x$  is linearly (i.e. one time) substituted by  $t$ .

# The linear substitution ...

## The computational Dialectica

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$$x_y \cdot \pi = \begin{cases} \pi & \text{if } x = y \\ \emptyset & \text{otherwise} \end{cases} \quad (t u)_y := \lambda \pi. (t_y (u^\bullet, \pi)) \otimes ((t^\bullet \cdot 2) \pi u^\bullet \gg= u_y)$$

$$\frac{\partial}{\partial x}(\lambda y. s) \cdot t = \lambda y. \frac{\partial s}{\partial x} \cdot t \quad \frac{\partial}{\partial x}(Ds \cdot u) \cdot t = D\left(\frac{\partial s}{\partial x} \cdot t\right) \cdot u + Ds \cdot \left(\frac{\partial u}{\partial x} \cdot t\right)$$

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# Tracking differentiation in Dialectica

## Soundness [Ped14]

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## That's reverse differentiation [KP24]

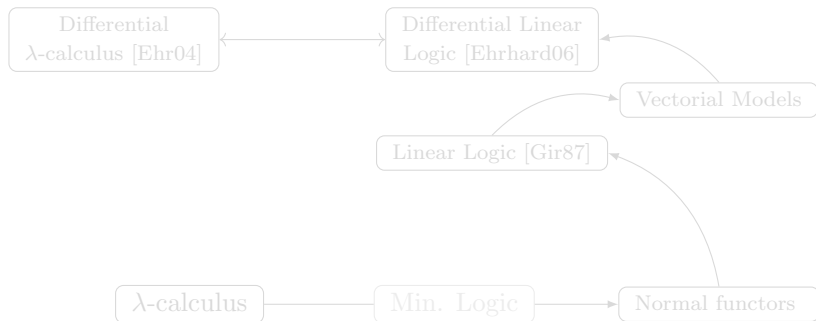
- ▶  $(-)^{\bullet.2}$  obeys the chain rule,  $(-)^{\bullet}$  is the functorial differentiation.
- ▶  $t_x$  is contravariant in  $x$ , representing a reverse linear substitution.

## Other formulations:

- ▶ The [Linear Dialectica](#) and Differential Linear Logic
- ▶ [Dialectica Categories](#) and Differential Categories

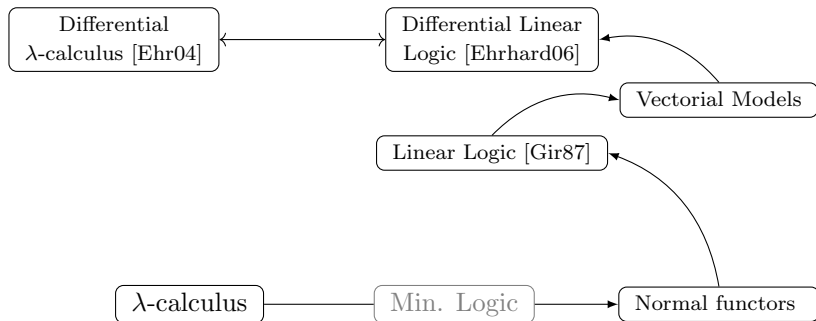
# Recap

<b>Programs</b>	<b>Logic</b>	<b>Semantics</b>
$\text{fun } (x:A) \rightarrow (t:B)$	Proof of $A \vdash B$	$f : A \rightarrow B.$
Types	Formulas	Objects
Execution	Cut-elimination	Equality



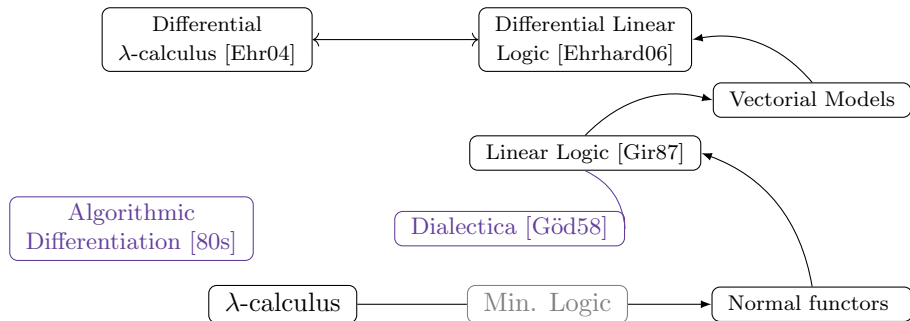
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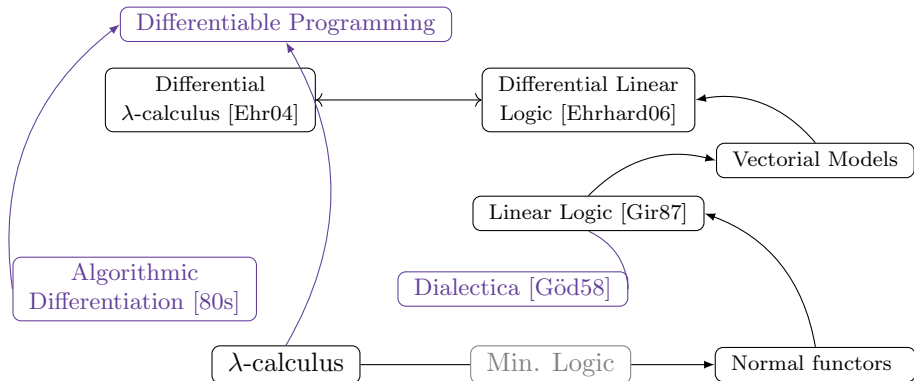
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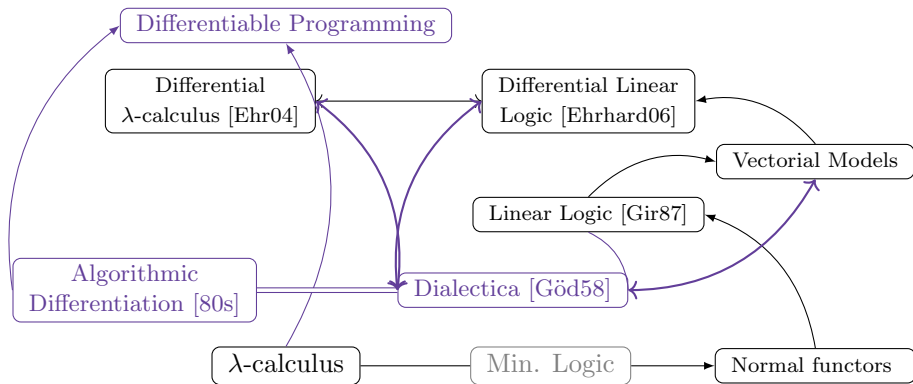
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*A good point for logicians : Gödel invented Dialectica 40 years before reverse differentiation was put to light*

## Conclusion and applications

## Take home message:

**Dialectica computes higher-order functorial reverse differentiation,**  
extracting ~~intensional~~ local content from proofs.

A new semantical correspondence between computations and mathematics :  
~~intentional meaning~~ of program is **local behavior** of functions.

Is this result obvious? Maybe, and I'm happy if it is.

## Related work and potential applications:

- ▶ **Markov's principle** and delimited continuations on positive formulas.
- ▶ **Proof mining** and backpropagation.
- ▶ **Bar Induction** and Taylor Exponentiation.

# Dialectica is differentiation ...

... We knew it already !

*The codereliction of differential proof nets:* In terms of polarity in linear logic [23], the  $\forall\text{-}\rightarrow$ -free constraint characterizes the formulas of intuitionistic logic that can be built only from positive connectives ( $\oplus$ ,  $\otimes$ ,  $0$ ,  $1$ ,  $!$ ) and the why-not connective (“?”). In this framework, Markov’s principle expresses that from such a  $\forall\text{-}\rightarrow$ -free formula  $A$  (e.g.  $? \oplus_x (?A(x) \otimes ?B(x))$ ) where the presence of “?” indicates that the proof possibly used weakening (efq or throw) or contraction (catch), a linear proof of  $A$  purged from the occurrences of its “?” connective can be extracted (meaning for the example above a proof of  $\oplus_x (A(x) \otimes B(x))$ ). Interestingly, the removal of the “?”, i.e. the steps from  $?P$  to  $P$ , correspond to applying the codereliction rule of differential proof nets [24].

**Differentiation :**  $(?P = (P \multimap \perp) \Rightarrow \perp) \rightarrow ((P \multimap \perp) \multimap \perp) \equiv P$



Hugo Herbelin, “An intuitionistic logic that proves Markov’s principle”, LICS ’10 .

Are mathematical transformation realizing the axioms they need ?