

Gestion de production à EDF et symétries structurées en PLNE

Cécile Rottner

EDF R&D - Département OSIRIS

MAOA - 8 janvier 2019



Outline

1 The Unit Commitment Problem

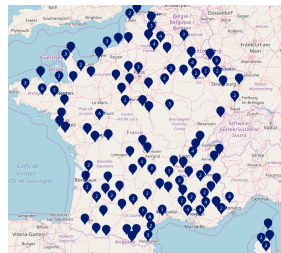
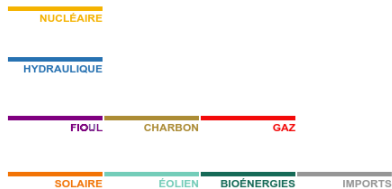
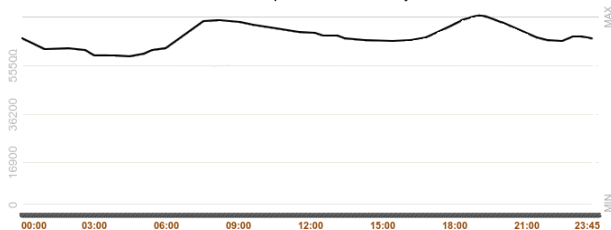
- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- Restrictions to representatives
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

The Unit Commitment Problem (UCP)

Demand for electric power on a one-day horizon

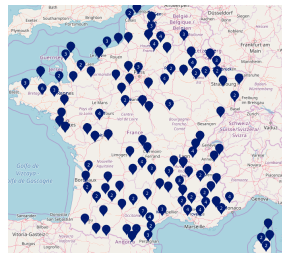
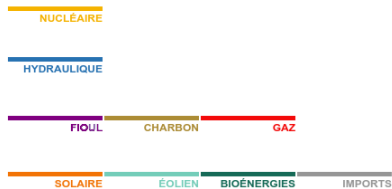
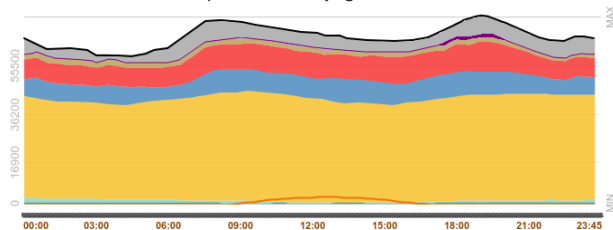


EDF power production units in France, including:

- 58 **nuclear** reactors
- 500 **hydro-power** plants dispatched in 50 valleys
- ■ ■ 20 **fossil-fuel** power plants
fuel oil/gas turbines
combined gas cycle
coal-fired power plants

The Unit Commitment Problem (UCP)

Power production satisfying the demand



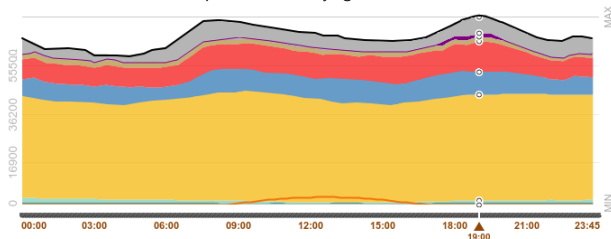
EDF power production units in France, including:

- 58 **nuclear** reactors
- 500 **hydro-power** plants dispatched in 50 valleys
- ■ ■ 20 **fossil-fuel** power plants
fuel oil/gas turbines
combined gas cycle
coal-fired power plants

→ Each production unit features technical constraints.

The Unit Commitment Problem (UCP)

Power production satisfying the demand



42135^{MW}
NUCLÉAIRE

5145^{MW}
HYDRAULIQUE

1598^{MW}
FIOUL

1753^{MW}
CHARBON

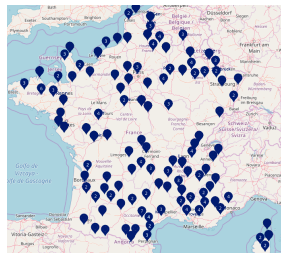
7890^{MW}
GAZ

0^{MW}
SOLAIRE

832^{MW}
ÉOLIEN

1048^{MW}
BIOÉNERGIES

6444^{MW}
IMPORTS



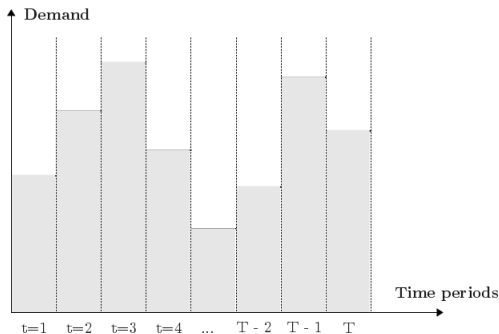
EDF power production units in France, including:

- 58 **nuclear** reactors
- 500 **hydro-power** plants dispatched in 50 valleys
- ■ ■ 20 **fossil-fuel** power plants
fuel oil/gas turbines
combined gas cycle
coal-fired power plants

→ Each production unit features technical constraints.

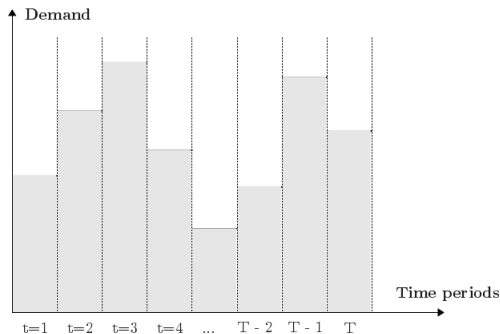
The Unit Commitment Problem (UCP)

- **Discretized** time horizon T
- **Demand** for electric power D_t at time t



The Unit Commitment Problem (UCP)

- **Discretized** time horizon T
- **Demand** for electric power D_t at time t

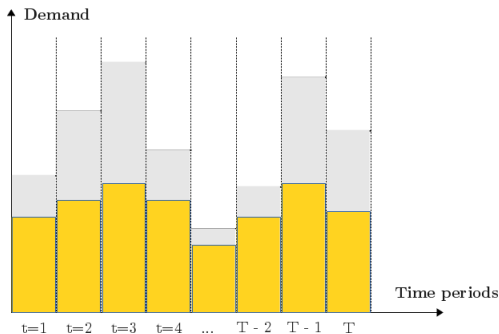


n production units



The Unit Commitment Problem (UCP)

- **Discretized** time horizon T
- **Demand** for electric power D_t at time t

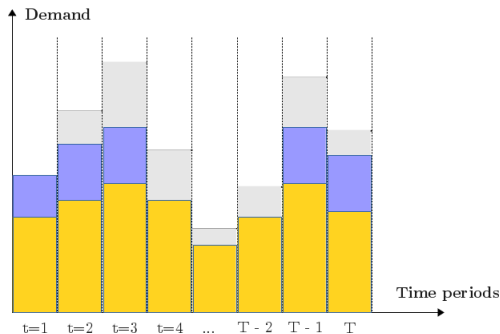


n production units



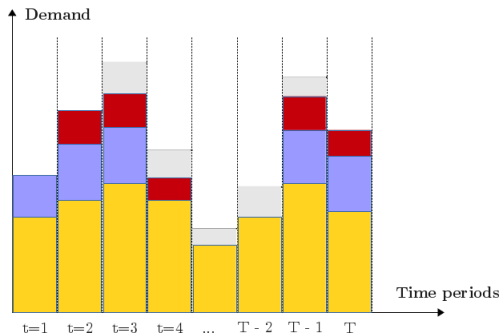
The Unit Commitment Problem (UCP)

- **Discretized** time horizon T
- **Demand** for electric power D_t at time t



The Unit Commitment Problem (UCP)

- **Discretized** time horizon T
- **Demand** for electric power D_t at time t

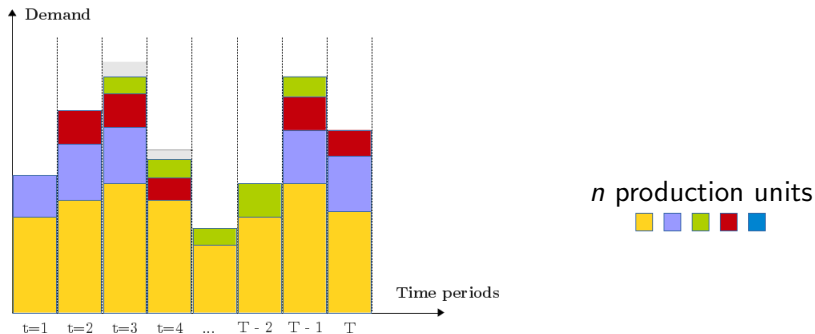


n production units



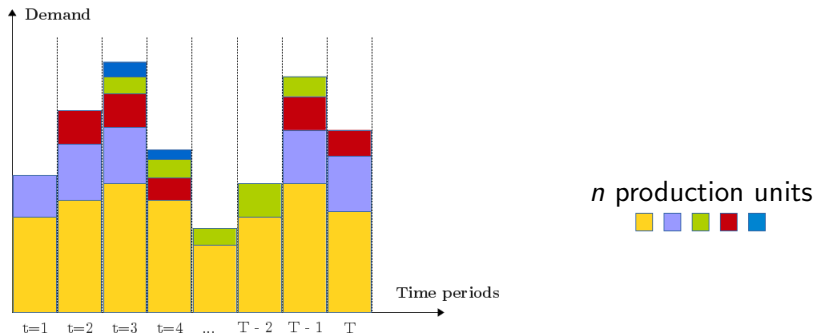
The Unit Commitment Problem (UCP)

- **Discretized** time horizon T
- **Demand** for electric power D_t at time t



The Unit Commitment Problem (UCP)

- **Discretized** time horizon T
- **Demand** for electric power D_t at time t



The Unit Commitment Problem (UCP)

Production units must satisfy various technical constraints:

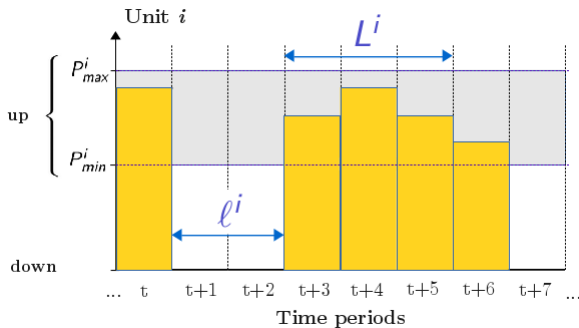
Thermal units (nuclear, gas, fuel oil, coal) :

- Minimum up and down times
- Production limits
- Ramp constraints, *i.e.*, production variation limits
- ...

Example: constraints of thermal units

Each thermal unit i must satisfy:

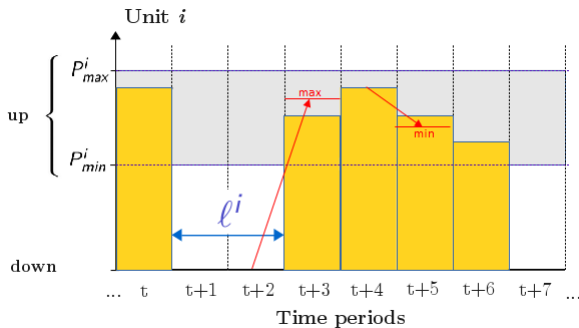
- Production limits P_{min}^i, P_{max}^i
- Minimum up time L^i
- Minimum down time ℓ^i
- Ramp constraints



Example: constraints of thermal units

Each thermal unit i must satisfy:

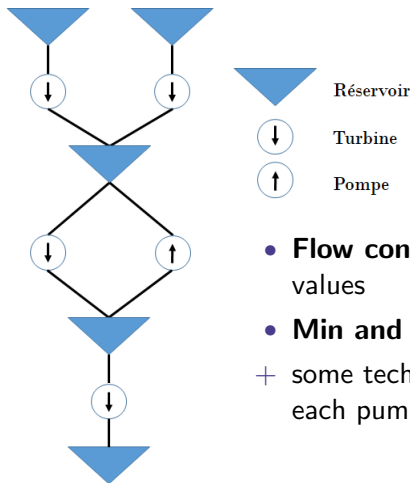
- Production limits P_{min}^i, P_{max}^i
- Minimum up time L^i
- Minimum down time ℓ^i
- Ramp constraints



The Unit Commitment Problem (UCP)

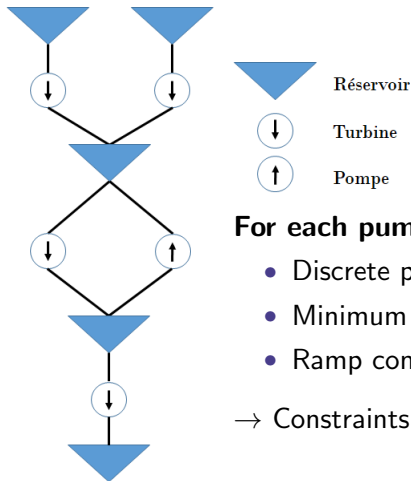
Constraints in hydro-valleys :

Hydro-valley = Network of turbines, pumps and reservoirs



- **Flow constraints** : conservation and min/max values
- **Min and max volume** in each reservoir
- + some technical constraints for each turbine and each pump

Technical constraints of pumps and turbines



For each pump and each turbine:

- Discrete power levels
- Minimum time on each power level
- Ramp constraints...

→ Constraints similar to thermal units.

Production costs

- **Costs** for each unit i :
 - **proportional** production cost c_p^i
 - **fixed** production cost c_f^i
 - **start-up** cost c_0^i

Unit Commitment Problem (UCP)

Find a production plan that

- satisfies technical constraints of all units
- meets the **demand** at each time
- minimizes the total production cost

UCP resolutions at EDF

At EDF :

The UCP is solved for various time horizons :

- Mid-term horizons (from one year ahead to one week ahead)
- Day to day (for the next day)
→ **DAY-AHEAD UCP**
- Hour to hour (for the next hour to the end of the day)
→ **INTRA-DAY UCP**

The UCP is solved for various areas :

- Metropolitan France
- Insular regions (Corse, Guadeloupe, Réunion...)
→ **INSULAR UCP**

UCP resolutions at EDF

DAY-AHEAD UCP : Lagrangian relaxation of demand constraints

- **Decomposition**

Each production unit (nuclear, coal, gas, fuel-oil, hydro-valley) corresponds to a subproblem:

- **Thermal** subproblems solved by **dynamic programming**
- **Hydro-valley** subproblems solved by **IP techniques**

- **Coordination** of the subproblems

→ *Historic resolution technique at EDF*

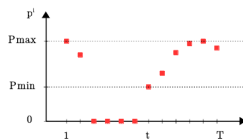
→ *Solves large scale instances with heterogeneous units on a daily basis*

INTRA-DAY UCP and **INSULAR SYSTEMS UCP** : **Branch&Bound**

ILP formulation

For each unit $i \in \{1, \dots, n\}$ and each time $t \in \{1, \dots, T\}$

- **production** variables $p_t^i \in \mathbb{R}$



$$\min_p \sum_{i=1}^n \text{cost}(p^i)$$

$$\text{s. t. } p^i \in \Pi^i \quad \forall i \in \{1, \dots, n\} \quad (1)$$

$$\sum_{i=1}^n p_t^i \geq D_t \quad \forall t \in \{1, \dots, T\} \quad (2)$$

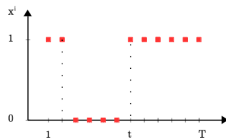
$$p_t^i \in \mathbb{R} \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}$$

- Operating domain of unit i : Π^i

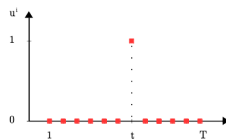
Example of an operating domain (thermal unit)

For each unit $i \in \{1, \dots, n\}$ and each time $t \in \{1, \dots, T\}$

- **up/down status** variables $x_t^i \in \{0, 1\}$



- **start-up** variables $u_t^i \in \{0, 1\}$



Example of an operating domain (thermal unit)

$$\Pi^i = \left\{ p \mid \begin{array}{ll}
 \sum_{t'=t-L^i+1}^t u_{t'}^i \leq x_t^i & \forall i \in \{1, \dots, n\}, \forall t \in \{L^i, \dots, T\} \\
 \sum_{t'=t-\ell^i+1}^t u_{t'}^i \leq 1 - x_{t-\ell^i}^i & \forall i \in \{1, \dots, n\}, \forall t \in \{\ell^i + 1, \dots, T\} \\
 u_t^i \geq x_t^i - x_{t-1}^i & \forall i \in \{1, \dots, n\}, \forall t \in \{2, \dots, T\} \\
 P_{\min}^i x_t^i \leq p_t^i \leq P_{\max}^i x_t^i & \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\} \\
 \tilde{x}_{t,J}, \tilde{u}_{t,J} \in \{0, 1, \dots, |J|\}, \tilde{p}_{t,J} \in \mathbb{R} & \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}
 \end{array} \right.$$

Lagrangian decomposition

$$\min_p \sum_{i=1}^n \text{cost}(p^i)$$

$$\text{s. t. } p^i \in \Pi^i \quad \forall i \in \{1, \dots, n\}$$

$$\sum_{i=1}^n p_t^i \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$p_t^i \in \mathbb{R} \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}$$



$$\min_p \sum_{i=1}^n \text{cost}(p^i) + \sum_{t=1}^T \lambda_t (D_t - \sum_{i=1}^n p_t^i)$$

$$\text{s. t. } p^i \in \Pi^i \quad \forall i \in \{1, \dots, n\}$$

$$p_t^i \in \mathbb{R} \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}$$

Lagrangian decomposition

$$\min_p \sum_{i=1}^n \text{cost}(p^i)$$

$$\text{s. t. } p^i \in \Pi^i \quad \forall i \in \{1, \dots, n\}$$

$$\sum_{i=1}^n p_t^i \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$p_t^i \in \mathbb{R} \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}$$



$$\min_p \sum_{i=1}^n \left(\text{cost}(p^i) - \sum_{t=1}^T \lambda_t p_t^i \right)$$

$$\text{s. t. } p^i \in \Pi^i \quad \forall i \in \{1, \dots, n\}$$

$$p_t^i \in \mathbb{R} \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}$$

Decomposition in subproblems

$$\begin{aligned} \min_p \quad & \sum_{i=1}^n \left(\text{cost}(p^i) - \sum_{t=1}^T \lambda_t p_t^i \right) \\ \text{s. t.} \quad & p^i \in \Pi^i \quad \forall i \in \{1, \dots, n\} \\ & p_t^i \in \mathbb{R} \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\} \end{aligned}$$

↓

...

↓

$$\begin{aligned} \min_p \quad & \left(\text{cost}(p^1) - \sum_{t=1}^T \lambda_t p_t^1 \right) \\ \text{s. t.} \quad & p^1 \in \Pi^1 \\ & p_t^1 \in \mathbb{R} \quad \forall t \in \{1, \dots, T\} \end{aligned}$$

$$\begin{aligned} \min_p \quad & \left(\text{cost}(p^n) - \sum_{t=1}^T \lambda_t p_t^n \right) \\ \text{s. t.} \quad & p^n \in \Pi^n \\ & p_t^n \in \mathbb{R} \quad \forall t \in \{1, \dots, T\} \end{aligned}$$

→ n subproblems : 1 per unit

Dantzig-Wolfe reformulation

For each unit i , Π^i set of feasible production plans.

New variable space : for each $\pi \in \Pi^i$,

$\lambda_\pi = 1$ iff **plan π chosen for unit i**

$$\begin{aligned}
 (DW_{UCP}) \quad & \min_{\lambda} \sum_{i=1}^n \sum_{\pi \in \Pi^i} c^\pi \lambda^\pi \\
 \text{s. t.} \quad & \sum_{\pi \in \Pi^i} \lambda^\pi = 1 && \forall i \in \{1, \dots, n\} \\
 & \sum_{i=1}^n \sum_{\pi \in \Pi^i} p_t^\pi \lambda^\pi \geq D_t && \forall t \in \{1, \dots, T\} \\
 & \lambda^\pi \in \{0, 1\} && \forall i \in \{1, \dots, n\} \quad \forall \pi \in \Pi^i
 \end{aligned}$$

p_t^π : power produced by unit i at time t in plan $\pi \in \Pi^i$

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

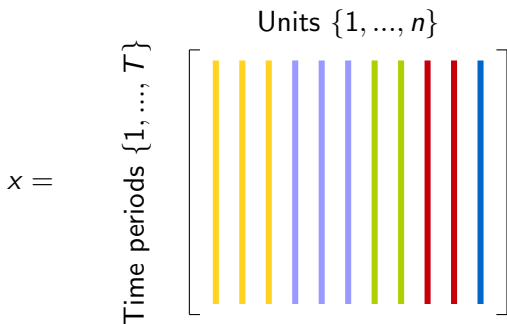
- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- Restrictions to representatives
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

Symmetries in the UCP

→ **Symmetries in the UCP** come from the existence of **identical units**.

- Variables $x_t^i \in \{0, 1\}$: unit i up at time t .
→ matrix $x = (x_t^i)$

- **Groups of identical units**, *i.e.*, units with same characteristics & costs



Example : 3 identical units with horizon $T = 3$

→ given one solution $x_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$

→ 5 symmetric solutions :

$$x_2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$x_3 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$x_4 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$x_5 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$x_6 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

Symmetry in integer programming - Definitions

$$\min \left\{ c(x) \mid x \in \mathcal{X} \right\} \quad (ILP)$$

\mathcal{X} subset of $m \times n$ binary matrices

- A **symmetry** is a permutation π of the variables s.t.

$$\forall x \in \mathcal{X}, \pi(x) \in \mathcal{X} \text{ and } c(x) = c(\pi(x))$$

$$x = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \quad x' = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

- The **symmetry group** \mathcal{G} of (ILP) is the set of all symmetries.
- Symmetry group \mathcal{G} partitions \mathcal{X} into **orbits**.

In this presentation...

We consider problems with **structured symmetries**, *i.e.*

any column permutation is a symmetry.

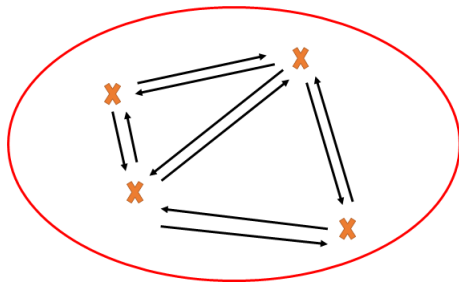
Thus, the symmetry group \mathcal{G} is the set of all column permutations.

In the UCP, not exactly **all** column permutations but:

$$x = \begin{array}{c} \text{Units } \{1, \dots, n\} \\ \left[\begin{array}{cccccccccccc} \color{yellow}{|} & \color{yellow}{|} & \color{yellow}{|} & \color{blue}{|} & \color{blue}{|} & \color{blue}{|} & \color{green}{|} & \color{green}{|} & \color{green}{|} & \color{red}{|} & \color{red}{|} & \color{blue}{|} \end{array} \right] \end{array}$$

→ everything we do in the "all column permutation" case will also apply to this more general case.

Orbits



Orbits : for any solution x , the orbit of x contains :

every solution obtained by arbitrarily permuting x 's columns

Example : 3 identical units with horizon $T = 3$

→ given one solution $x_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$

→ 5 symmetric solutions :

$$x_2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$x_3 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$x_4 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$x_5 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$x_6 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

→ **orbit of $x_1 = \text{orbit of } x_2 = \dots = \text{orbit of } x_6 = \{x_1, x_2, x_3, x_4, x_5, x_6\}$**

Example : 3 identical units with horizon $T = 3$

→ for another solution $y_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$

→ 2 symmetric solutions :

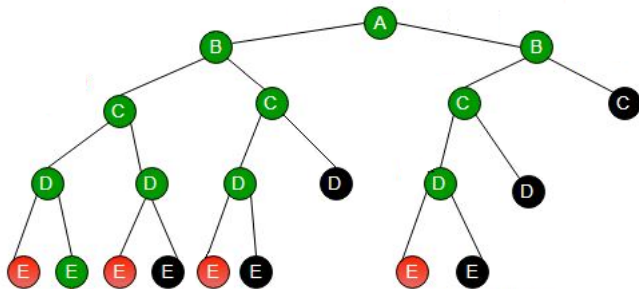
$$y_2 = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$y_3 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix}$$

→ **orbit of $y_1 = \text{orbit of } y_2 = \text{orbit of } y_3 = \{y_1, y_2, y_3\}$**

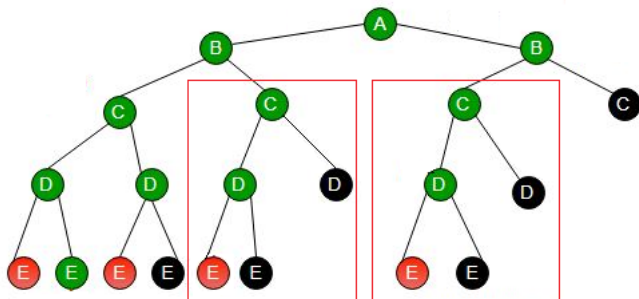
Symmetries in ILP

Many symmetric solutions lead to many symmetric branches in the B&B tree that cannot be pruned.



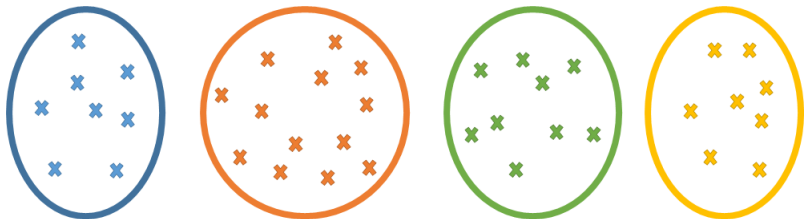
Symmetries in ILP

Many symmetric solutions lead to many symmetric branches in the B&B tree that cannot be pruned.



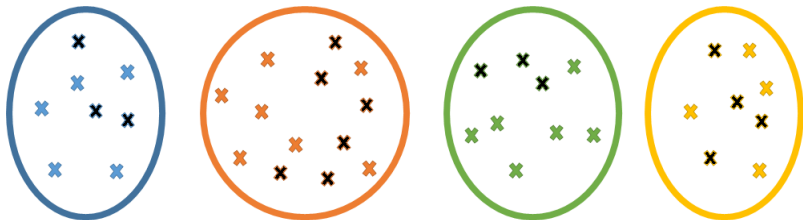
→ the B&B tree might get very big !

How to break symmetries?



How to restrict the search space to non-symmetric solutions only ?

How to break symmetries?

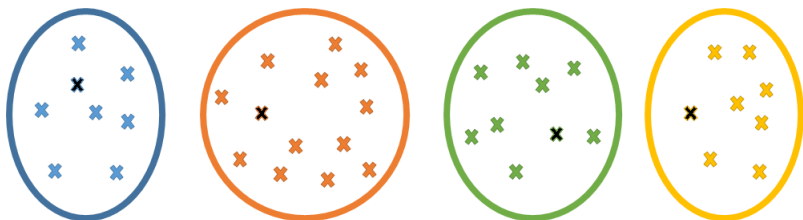


How to restrict the search space to non-symmetric solutions only ?

- Use symmetry-breaking **heuristics** removing some symmetric solutions (but not all)

NB : black crosses = solutions not removed

How to break symmetries?



How to restrict the search space to non-symmetric solutions only ?

- Use symmetry-breaking **heuristics** removing some symmetric solutions (but not all)
- **Choose one representative** per orbit and **restrict** the search to the representative set

How to break symmetries?



How to restrict the search space to non-symmetric solutions only ?

- Use symmetry-breaking **heuristics** removing some symmetric solutions (but not all)
- **Choose one representative** per orbit and **restrict** the search to the representative set
- **Reformulate** (i.e., change variable space)
→ indeed, symmetries depend on how the problem is formulated

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- Restrictions to representatives
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- Restrictions to representatives
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

1-counting inequalities

Idea : restrict the search to solutions such that :

number of 1's in column $j \geq$ number of 1's in column $j + 1$

$$\sum_{i=1}^m x_{i,j} \geq \sum_{i=1}^m x_{i,j+1}, \quad \forall j \in \{1, \dots, n-1\}$$

(Lima and Novais, 2016)

Example : 3 identical units with horizon $T = 3$

→ 6 symmetric solutions :

$$x_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \quad x_2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \quad \rightarrow \text{these solutions remain}$$

$$x_3 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \quad x_4 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \quad \rightarrow \text{these solutions are removed}$$

$$x_5 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} \quad x_6 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \quad \rightarrow \text{these solutions are removed}$$

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- **Symmetry-breaking heuristics**
 - 1-counting inequalities
 - **Orbital branching**
- Restrictions to representatives
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

Orbital branching

At node a of the B&B tree: instead of branching on $x_{i,j} = 0 \vee x_{i,j} = 1$

- look for variables symmetric to $x_{i,j}$ at node a

At node a , some variables are fixed:

$$\begin{bmatrix} 1 & \times & 1 & 1 & 1 \\ \times & 0 & \times & \times & \times \\ \times & 1 & \times & \times & \times \\ 0 & 1 & \times & 0 & 0 \end{bmatrix}$$

(Ostrowski, Anjos and Vannelli, 2015)

Orbital branching

At node a of the B&B tree: instead of branching on $x_{i,j} = 0 \vee x_{i,j} = 1$

- look for variables symmetric to $x_{i,j}$ at node a

At node a , some variables are fixed:

$$\begin{bmatrix} 1 & \times & 1 & 1 & 1 \\ \times & 0 & \times & \times & \times \\ \times & 1 & \times & \times & \times \\ 0 & 1 & \times & 0 & 0 \end{bmatrix}$$

Set of symmetric variables $O = \{x_{i,j_1}, x_{i,j_2}, \dots, x_{i,j_k}\}$

- branch on :

at least α variables of O are equal to 1

\vee

at most $\alpha - 1$ variables of O are equal to 1

(Ostrowski, Anjos and Vannelli, 2015)

Orbital branching

at least α variables of O are equal to 1

∨

at most $\alpha - 1$ variables of O are equal to 1

↓

at least α variables of O are equal to 1

∨

at least $k - \alpha$ var. of O equal 0

↓

(By symmetry)

first α variables of O are equal to 1

∨

last $k - \alpha$ variables of O are equal to 0

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- **Restrictions to representatives**
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

Lexicographic order

→ **Order on the columns.**

Consider two columns $X, Y \in \{0, 1\}^m$.

Lexicographic order

Y is **lexicographically greater than** X (denoted $Y \succeq X$) if :

$\exists i \in \{1, \dots, m-1\}$ s. t.

- $\forall i' \leq i, Y_{i'} = X_{i'}$
- $Y_{i+1} = 1$ and $X_{i+1} = 0$

Example

$$Y = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \succeq X = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

Full Orbitopes

- **When the symmetry group is the set of all column permutations:**

$x \in \mathcal{X}$ lex-order representative $\iff x(1) \succeq \dots \succeq x(n)$

\iff **Columns of x are in non-increasing lexicographic order**

Example

$x_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$ is a lex-order representative.

Full Orbitope

$\mathcal{P}_0 = \text{Conv} \left\{ \text{binary matrices } x \mid x(1) \succeq \dots \succeq x(n) \right\}$

Solving on $\mathcal{X} \iff$ Solving on $\mathcal{X} \cap \mathcal{P}_0$

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- **Restrictions to representatives**
 - **Full orbitope inequalities**
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

First idea to enforce that each x is in the full orbitope:

add new constraints in the model

→ For a given matrix $x = (x_{i,j}) = [x(1), x(2), \dots, x(n)]$,
where $x(1), x(2), \dots, x(n)$ are x 's columns.

Find linear inequalities enforcing that : $x(1) \succeq x(2) \succeq \dots \succeq x(n)$

First idea to enforce that each x is in the full orbitope:

add new constraints in the model

→ For a given matrix $x = (x_{i,j}) = [x(1), x(2), \dots, x(n)]$, where $x(1), x(2), \dots, x(n)$ are x 's columns.

Find linear inequalities enforcing that : $x(1) \succeq x(2) \succeq \dots \succeq x(n)$

One option : for each pair of columns $j, j + 1$, add inequalities

$$2^{m-1}x_{1,j} + 2^{m-2}x_{2,j} + \dots + x_{m,j} \geq 2^{m-1}x_{1,j+1} + 2^{m-2}x_{2,j+1} + \dots + x_{m,j+1}$$

j	$j + 1$	
$\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$	→ weight 2^{m-1}
		→ weight 2^{m-2}
		...
		→ weight 2^0

→ **numerical difficulties** (exponential coefficients)

Full orbitope inequalities

Find linear inequalities enforcing that : $x(1) \succeq x(2) \succeq \dots \succeq x(n)$

Other option: add new variables

$$y_{i,j} = 1 \quad \text{iff} \quad \text{column } j \text{ and } j + 1 \text{ are equal from row } 1 \text{ to } i$$

Example

	j	$j + 1$	
$i = 1$	$\begin{bmatrix} 1 \end{bmatrix}$	$\begin{bmatrix} 1 \end{bmatrix}$	$y_{1,j} = 1$
$i = 2$	$\begin{bmatrix} 0 \end{bmatrix}$	$\begin{bmatrix} 0 \end{bmatrix}$	$y_{2,j} = 1$
$i = 3$	$\begin{bmatrix} 1 \end{bmatrix}$	$\begin{bmatrix} 0 \end{bmatrix}$	$y_{3,j} = 0$
$i = 4$	$\begin{bmatrix} 0 \end{bmatrix}$	$\begin{bmatrix} 1 \end{bmatrix}$	$y_{4,j} = 0$
$i = 5$	$\begin{bmatrix} 0 \end{bmatrix}$	$\begin{bmatrix} 0 \end{bmatrix}$	$y_{5,j} = 0$

(Loos, 2011)

(Bendotti, Fouilhoux and R., 2019)

Full orbitope inequalities

$y_{i,j} = 1$ iff column j and $j + 1$ are equal from row 1 to i

New constraints :

- $y_{i,j} = 1 \iff \begin{cases} y_{i-1,j} = 1 \\ x_{i,j} = x_{i,j+1} \end{cases}$
- If $\begin{cases} y_{i-1,j} = 1 \\ y_{i,j} = 0 \end{cases}$ then $\begin{cases} x_{i,j} = 1 \\ x_{i,j+1} = 0 \end{cases}$

Example

	j	$j + 1$	
$i = 1$	$\begin{bmatrix} 1 \end{bmatrix}$	$\begin{bmatrix} 1 \end{bmatrix}$	$y_{1,j} = 1$
$i = 2$	$\begin{bmatrix} 0 \end{bmatrix}$	$\begin{bmatrix} 0 \end{bmatrix}$	$y_{2,j} = 1$
$i = 3$	$\begin{bmatrix} 1 \end{bmatrix}$	$\begin{bmatrix} 0 \end{bmatrix}$	$y_{3,j} = 0$
$i = 4$	$\begin{bmatrix} 0 \end{bmatrix}$	$\begin{bmatrix} 1 \end{bmatrix}$	$y_{4,j} = 0$
$i = 5$	$\begin{bmatrix} 0 \end{bmatrix}$	$\begin{bmatrix} 0 \end{bmatrix}$	$y_{5,j} = 0$

Full orbitope inequalities

$y_{i,j} = 1$ iff column j and $j + 1$ are equal from row 1 to i

Constraints :

$$1 - y_{1,j-1} = x_{1,j-1} - x_{1,j} \quad \forall j \in \{2, \dots, n\}$$

$$y_{i-1,j-1} \leq y_{i,j-1} + x_{i,j-1} \quad \forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

$$y_{i-1,j-1} + x_{i,j} \leq 1 + y_{i,j-1} \quad \forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

$$x_{i,j-1} \leq 1 - y_{i,j-1} + x_{i,j} \quad \forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

$$y_{i,j-1} \leq y_{i-1,j-1} \quad \forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

$$x_{i,j} \leq (1 - 2y_{i-1,j} - y_{i,j}) + x_{i,j-1}$$

$$\forall j \in \{2, \dots, n\}$$

$$\forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

$$\forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

$$\forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

$$\forall i \in \{2, \dots, m\}, j \in \{2, \dots, n\}$$

→ complete linear description in variable space (x, y)
of the 2-column full orbitope

(Loos, 2011)

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- **Restrictions to representatives**
 - Full orbitope inequalities
 - **Fixing in the full orbitope**
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

Fixing in the full orbitope

Another idea to enforce that each x is in the full orbitope:

**fix variables during the B&B search
to ensure columns are in lex order**

- At each node a of the B&B tree, some variables are already fixed to 0 (variables I_0^a) or already fixed to 1 (variables I_1^a)
→ defines a set

$$F = \{ \text{matrices } x \mid x_{i,j} = 1 \forall (i,j) \in I_1^a \quad x_{i,j} = 0 \forall (i,j) \in I_0^a \}$$

- At node a , we want to enumerate solutions x such that

$$x \in F \cap P \cap \{0, 1\}^{(m,n)}$$

where P is the full orbitope.

→ **it may be possible to fix more variables to 0 or to 1 at node a**

Example

At node a , there are some fixed variables :

("×" stands for free variables i.e. variables not fixed yet)

$$x = \begin{bmatrix} \times & 1 \\ \times & 1 \\ 0 & \times \end{bmatrix}$$

We want x 's columns to be in lexicographic order.

Example

At node a , there are some fixed variables :

("×" stands for free variables i.e. variables not fixed yet)

$$x = \begin{bmatrix} 1 & 1 \\ \times & 1 \\ 0 & \times \end{bmatrix}$$

We want x 's columns to be in lexicographic order.

Example

At node a , there are some fixed variables :

("×" stands for free variables i.e. variables not fixed yet)

$$x = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & \times \end{bmatrix}$$

We want x 's columns to be in lexicographic order.

Example

At node a , there are some fixed variables :

("x" stands for free variables i.e. variables not fixed yet)

$$x = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 0 \end{bmatrix}$$

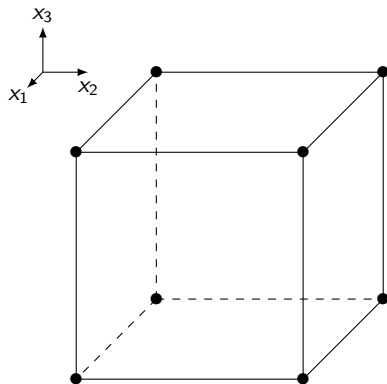
We want x 's columns to be in lexicographic order.

Variable fixing - Intersection with a cube face

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbitopal fixing*, Proc. IPCO, 2007.

- Let $C = \text{Conv} \{ m \times n \text{ binary matrices} \}$
- A non-empty face F of C is given by two index sets I_0, I_1 :

$$F = \{x \in C \mid x_{i,j} = 0 \forall (i,j) \in I_0, \quad x_{i,j} = 1 \forall (i,j) \in I_1\}.$$

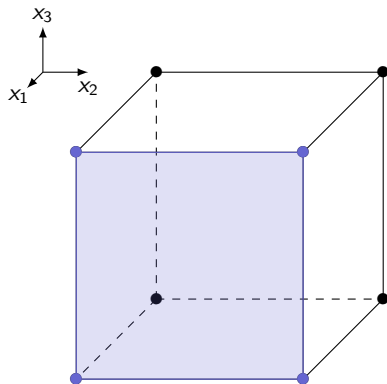


Variable fixing - Intersection with a cube face

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbital fixing*, Proc. IPCO, 2007.

- Let $C = \text{Conv} \{ m \times n \text{ binary matrices} \}$
- A non-empty face F of C is given by two index sets I_0, I_1 :

$$F = \{x \in C \mid x_{i,j} = 0 \forall (i,j) \in I_0, \quad x_{i,j} = 1 \forall (i,j) \in I_1\}.$$



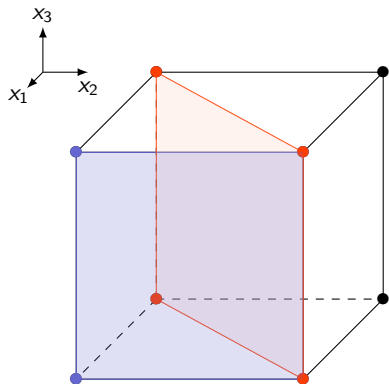
- For a given face F of C
 $F = \{x \in [0, 1]^3 \mid x_1 = 1\}$
 $I_1 = \{1\}, I_0 = \emptyset$

Variable fixing - Intersection with a cube face

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbital fixing*, Proc. IPCO, 2007.

- Let $C = \text{Conv} \{ m \times n \text{ binary matrices} \}$
- A non-empty face F of C is given by two index sets I_0, I_1 :

$$F = \{x \in C \mid x_{i,j} = 0 \forall (i,j) \in I_0, \quad x_{i,j} = 1 \forall (i,j) \in I_1\}.$$



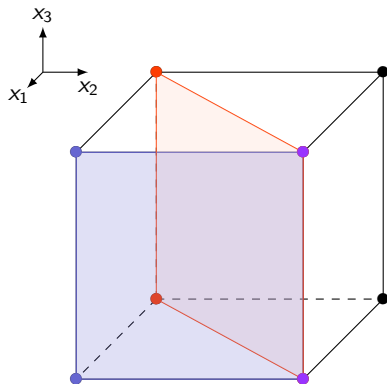
- For a given face F of C
- For a given polytope $P \subset C$

Variable fixing - Intersection with a cube face

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbitopal fixing*, Proc. IPCO, 2007.

- Let $C = \text{Conv} \{ m \times n \text{ binary matrices} \}$
- A non-empty face F of C is given by two index sets I_0, I_1 :

$$F = \{x \in C \mid x_{i,j} = 0 \forall (i,j) \in I_0, \quad x_{i,j} = 1 \forall (i,j) \in I_1\}.$$



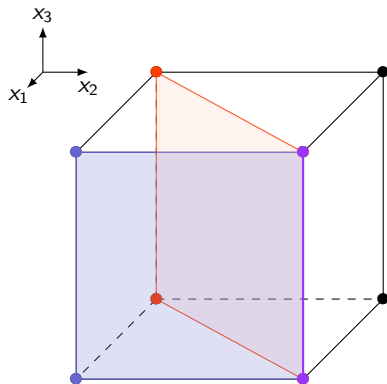
- For a given face F of C
 - For a given polytope $P \subset C$
- Solution set S
- $$S = P \cap F \cap \{0, 1\}^{(m,n)}$$

Variable fixing - Intersection with a cube face

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbitopal fixing*, Proc. IPCO, 2007.

- Let $C = \text{Conv} \{ m \times n \text{ binary matrices} \}$
- A non-empty face F of C is given by two index sets I_0, I_1 :

$$F = \{x \in C \mid x_{i,j} = 0 \forall (i,j) \in I_0, \quad x_{i,j} = 1 \forall (i,j) \in I_1\}.$$



- For a given face F of C
 - For a given polytope $P \subset C$
- Solution set S
- $$S = P \cap F \cap \{0, 1\}^{(m,n)}$$

Fixing of P at F

$\text{Fix}_F(P)$ = the smallest face of C that contains S

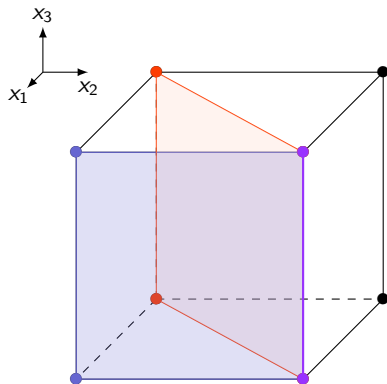
I_0^* and I_1^* : index sets defining $\text{Fix}_F(P)$ (if non-empty)

Variable fixing - Intersection with a cube face

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbitopal fixing*, Proc. IPCO, 2007.

- Let $C = \text{Conv} \{ m \times n \text{ binary matrices} \}$
- A non-empty face F of C is given by two index sets I_0, I_1 :

$$F = \{x \in C \mid x_{i,j} = 0 \forall (i,j) \in I_0, \quad x_{i,j} = 1 \forall (i,j) \in I_1\}.$$



- For a given face F of C
 - For a given polytope $P \subset C$
- Solution set S
- $$S = P \cap F \cap \{0, 1\}^{(m,n)}$$

Fixing of P at F

$\text{Fix}_F(P)$ = the smallest face of C that contains S

Fixing $\text{Fix}_F(P)$: $I_0^* = \emptyset$,
 $I_1^* = \{1, 2\}$, i.e., $x_1 = x_2 = 1$

Orbitopal fixing in the B&B tree

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbitopal fixing*, Proc. IPCO, 2007.

We want to restrict the solution set \mathcal{X} to a polytope P ,
 → **we want to enumerate only solutions in $\mathcal{X} \cap P$.**

Orbitopal fixing algorithm

At each node a of the B&B tree:

- (INPUT) I_0^a : variables set to 0, I_1^a : variables set to 1
 → F cube face defined by I_0^a, I_1^a
- **Compute** I_0^* and I_1^* : index sets defining $\text{Fix}_F(P)$
- (OUTPUT) Fixed variables:
 → **Fix** to 0 variables in I_0^* and to 1 variables in I_1^*

Orbitopal fixing in the B&B tree

V. Kaibel, M. Peinhardt, M. Pfetsch. *Orbitopal fixing*, Proc. IPCO, 2007.

We want to restrict the solution set \mathcal{X} to a polytope P ,
→ **we want to enumerate only solutions in $\mathcal{X} \cap P$.**

Orbitopal fixing algorithm

At each node a of the B&B tree:

- (INPUT) I_0^a : variables set to 0, I_1^a : variables set to 1
→ F cube face defined by I_0^a, I_1^a
- **Compute I_0^* and I_1^* : index sets defining $\text{Fix}_F(P)$**
- (OUTPUT) Fixed variables:
→ **Fix** to 0 variables in I_0^* and to 1 variables in I_1^*

Orbitopal fixing for the full orbitope

Let $P = \mathcal{P}_0$ (the full orbitope).

For a given face F :

- $\text{Fix}_F(P)$: cube face containing the intersection $F \cap P$.
- I_0^* and I_1^* : index sets defining $\text{Fix}_F(P)$

Theorem

$\forall F, I_0^$ and I_1^* can be computed in linear time.*

Idea:

Find binary matrices M_{min} and M_{max} in $F \cap P$ s.t.

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$:

$$i.e. \quad \forall \text{ column } j, \quad M_{min}(j) \preceq x(j) \preceq M_{max}(j)$$

(Bendotti, Fouilhoux and R., 2018)

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix}$$

M_F

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{\text{I}_1}{=} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{\text{I}_0}{=} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{\text{IL}}{\simeq} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{\text{IL}}{\simeq} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} & \stackrel{\cong}{=} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{\cong}{=} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{c}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} \\
 M_{min}
 \end{array}
 \quad \stackrel{\cong}{=} \quad
 \begin{array}{c}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_F
 \end{array}
 \quad \stackrel{\cong}{=} \quad
 \begin{array}{c}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{max}
 \end{array}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & \times & \color{red}{1} & \color{blue}{1} \\ 1 & 1 & \color{red}{1} & \color{blue}{1} \\ \times & \times & 0 & \color{blue}{0} \\ 1 & 0 & 1 & \color{blue}{0} \\ \times & 1 & 0 & \color{blue}{0} \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{c}
 \begin{bmatrix} 1 & \times & 1 & 1 \\ 1 & 1 & 1 & 1 \\ \times & \times & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} \\
 M_{min}
 \end{array}
 \quad \simeq \quad
 \begin{array}{c}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_F
 \end{array}
 \quad \simeq \quad
 \begin{array}{c}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{max}
 \end{array}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{c}
 \begin{bmatrix} 1 & \times & 1 & 1 \\ 1 & 1 & 1 & 1 \\ \times & \times & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} \\
 M_{min}
 \end{array}
 \quad \simeq \quad
 \begin{array}{c}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_F
 \end{array}
 \quad \simeq \quad
 \begin{array}{c}
 \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{max}
 \end{array}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & \times & 1 & 1 \\ 1 & 1 & 1 & 1 \\ \times & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ \times & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ \times & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ \times & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \times & 1 & 0 & 0 \end{bmatrix} & \stackrel{\text{IL}}{\sim} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{\text{IL}}{\sim} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \stackrel{||}{\sim} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{||}{\sim} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \color{red}{1} & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \color{red}{1} & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and
 $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \color{red}1 & \times & 1 \\ 1 & 1 & \times & 1 \\ 1 & \color{red}1 & 0 & \times \\ 1 & 0 & 1 & \times \\ 1 & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \stackrel{||\sphericalangle}{=} & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{||\sphericalangle}{=} & \begin{bmatrix} 1 & 1 & \color{red}1 & 1 \\ 1 & 1 & \color{red}1 & 1 \\ 1 & 1 & 0 & \times \\ 1 & 0 & 1 & \times \\ 1 & 1 & 0 & \times \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \preceq & \begin{bmatrix} 1 & \times & \times & 1 \\ 1 & 1 & \times & 1 \\ \times & \times & 0 & \times \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \preceq & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

$\implies I_0^*$ and I_1^*

Computing I_0^* and I_1^* - Example

Example: face F defined by $I_0 = \{(4, 2), (3, 3), (5, 3)\}$ and $I_1 = \{(1, 1), (2, 1), (4, 1), (2, 2), (5, 2), (4, 3), (1, 4), (2, 4)\}$

$\forall x \in F \cap P \cap \{0, 1\}^{(m,n)}$, x of the form

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & \stackrel{|\gamma|}{=} & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & \times \\ \times & 1 & 0 & \times \end{bmatrix} & \stackrel{|\gamma|}{=} & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \end{bmatrix} \\
 M_{min} & & M_F & & M_{max}
 \end{array}$$

$\implies I_0^*$ and I_1^*

Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- Restrictions to representatives
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

Dantzig-Wolfe reformulation: UCP example

For each unit i , Π^i set of feasible production plans.

New variable space : for each $\pi \in \Pi^i$,

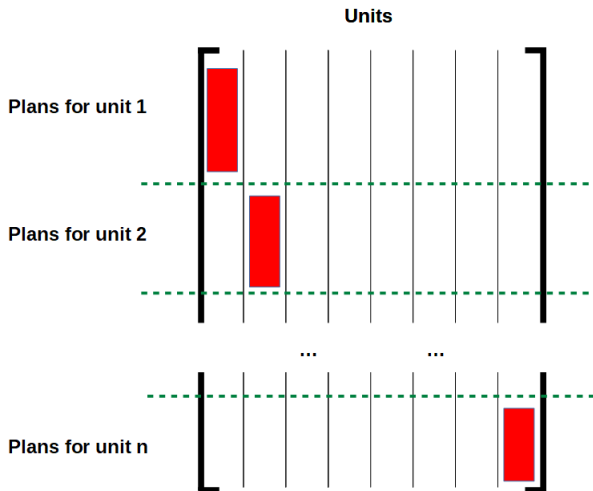
$\lambda_\pi = 1$ iff **plan π chosen for unit i**

$$\begin{aligned}
 (DW_{UCP}) \quad & \min_{\lambda} \quad \sum_{i=1}^n \sum_{\pi \in \Pi^i} c^\pi \lambda^\pi \\
 \text{s. t.} \quad & \sum_{\pi \in \Pi^i} \lambda^\pi = 1 \quad \forall i \in \{1, \dots, n\} \\
 & \sum_{i=1}^n \sum_{\pi \in \Pi^i} p_t^\pi \lambda^\pi \geq D_t \quad \forall t \in \{1, \dots, T\} \\
 & \lambda^\pi \in \{0, 1\} \quad \forall i \in \{1, \dots, n\} \quad \forall \pi \in \Pi^i
 \end{aligned}$$

p_t^π : power produced by unit i at time t in plan $\pi \in \Pi^i$

Dantzig-Wolfe reformulation with identical units

→ non-symmetric solution space!



Outline

1 The Unit Commitment Problem

- Definition
- Resolution at EDF
- ILP formulation for the UCP
- Lagrangian decomposition

2 Structured symmetries in Integer Linear Programs

- Definitions
- Symmetry-breaking heuristics
 - 1-counting inequalities
 - Orbital branching
- Restrictions to representatives
 - Full orbitope inequalities
 - Fixing in the full orbitope
- Reformulations
 - Dantzig-Wolfe reformulation
 - Aggregation of symmetric variables

Aggregation of symmetric variables

$$x = \begin{bmatrix} \color{yellow}{|} & \color{yellow}{|} & \color{yellow}{|} & \color{yellow}{|} & \color{blue}{|} & \color{blue}{|} & \color{blue}{|} & \color{blue}{|} & \color{green}{|} & \color{green}{|} & \color{green}{|} & \color{green}{|} & \color{red}{|} & \color{red}{|} & \color{red}{|} & \color{red}{|} & \color{blue}{|} & \color{blue}{|} \end{bmatrix}$$

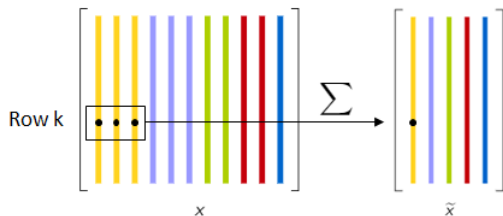
For set J of “permutable” columns, each row k , **define aggregated variables** :

$$\tilde{x}_{k,J} = \sum_{j \in J} x_{k,j}$$

$\tilde{x}_{k,J}$ = number of variables to 1 among variables $x_{k,j}$, $j \in J$

(Fischetti, Liberti, Salvagnin and Walsh, 2017)

Aggregation of symmetric variables



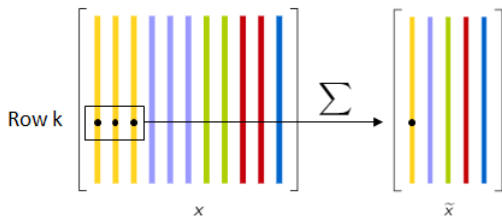
For set J of “permutable” columns, each row k , **define aggregated variables** :

$$\tilde{x}_{k,J} = \sum_{j \in J} x_{k,j}$$

$\tilde{x}_{k,J}$ = number of variables to 1 among variables $x_{k,j}$, $j \in J$

(Fischetti, Liberti, Salvagnin and Walsh, 2017)

Aggregation of symmetric variables



For set J of “permutable” columns, each row k , **define aggregated variables** :

$$\tilde{x}_{k,J} = \sum_{j \in J} x_{k,j}$$

$\tilde{x}_{k,J}$ = number of variables to 1 among variables $x_{k,j}$, $j \in J$

Replace every occurrence of variable $x_{k,j}$ **by** $\frac{\tilde{x}_{k,J}}{|J|}$
in the integer program, for each $j \in J$.

(Fischetti, Liberti, Salvagnin and Walsh, 2017)

$PC = \{ \text{set of permutable columns} \}$

Original ILP

$$\begin{aligned}
 (P) \quad v = \min_x \quad & \sum_{k=1}^m \sum_{j=1}^n c_{k,j} x_{k,j} \\
 \text{s. t.} \quad & Ax \leq b \\
 & x_{k,j} \in \{0, 1\} \quad \forall j \in \{1, \dots, n\}, \forall k \in \{1, \dots, m\}
 \end{aligned}$$

↓ (relaxation)

Aggregated ILP

$$\begin{aligned}
 (\tilde{P}) \quad \tilde{v} = \min_{\tilde{x}} \quad & \sum_{k=1}^m \sum_{J \in PC} \tilde{c}_{k,J} \tilde{x}_{k,J} \\
 \text{s. t.} \quad & \tilde{A} \tilde{x} \leq b \\
 & \tilde{x}_{k,J} \in \{0, 1, \dots, |J|\} \quad \forall J \in PC, \forall k \in \{1, \dots, m\}
 \end{aligned}$$

(Fischetti, Liberti, Salvagnin and Walsh, 2017)

$PC = \{ \text{set of permutable columns} \}$

Original ILP

$$\begin{aligned}
 (P) \quad v = \min_x \quad & \sum_{k=1}^m \sum_{j=1}^n c_{k,j} x_{k,j} \\
 \text{s. t.} \quad & Ax \leq b \\
 & x_{k,j} \in \{0, 1\} \quad \forall j \in \{1, \dots, n\}, \forall k \in \{1, \dots, m\}
 \end{aligned}$$

↓ (relaxation)

Agregated ILP

$$\begin{aligned}
 (\tilde{P}) \quad \tilde{v} = \min_{\tilde{x}} \quad & \sum_{k=1}^m \sum_{J \in PC} \tilde{c}_{k,J} \tilde{x}_{k,J} \\
 \text{s. t.} \quad & \tilde{A}\tilde{x} \leq b \\
 & \tilde{x}_{k,J} \in \{0, 1, \dots, |J|\} \quad \forall J \in PC, \forall k \in \{1, \dots, m\}
 \end{aligned}$$

Reduces the number of variables

But replaces binary variables by integer variables

(Fischetti, Liberti, Salvagnin and Walsh, 2017)

General case

In general: (\tilde{P}) is a **relaxation of** (P) , *i.e.* $\tilde{v} \leq v$.

Indeed, for a given solution \tilde{x} , there may not exist x such that $Ax \leq b$, $x_{kj} \in 0, 1$ and $\tilde{x}_{k,J} = \sum_{j \in J} x_{k,j}$ for each J and k .

But: **in some particular cases** $\tilde{v} = v$

→ **it is the case for what we call the Min-up/min-down Unit Commitment Problem (MUCP)**

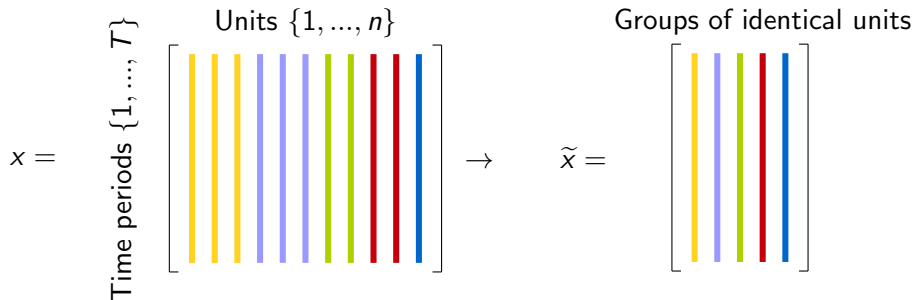
i.e. a restriction of the UCP with only the following constraints:

- Demand satisfaction at each time t
- Power limits P_{min} and P_{max} for each unit
- Minimum up and down time constraints

(B. Knueven, J. Ostrowski, J.P. Watson, 2017)

Example: the MUCP

$\tilde{x}_{t,J}$ = number of units of J up at time t



$$x_{t,i} \in \{0, 1\}$$

$$\tilde{x}_{t,J} \in \{0, 1, \dots, |J|\}$$

(B. Knueven, J. Ostrowski, J.P. Watson, 2017)

MUCP formulation

$$\begin{aligned}
 v = \min_{x,u,p} \quad & \sum_{t=1}^T \sum_{i=1}^n c_f^i x_t^i + c_p^i p_t^i + c_0^i u_t^i \\
 \text{s. t.} \quad & \sum_{t'=t-L^i+1}^t u_{t'}^i \leq x_t^i && \forall i \in \{1, \dots, n\}, \forall t \in \{L^i, \dots, T\} \\
 & \sum_{t'=t-\ell^i+1}^t u_{t'}^i \leq 1 - x_{t-\ell^i}^i && \forall i \in \{1, \dots, n\}, \forall t \in \{\ell^i + 1, \dots, T\} \\
 & u_t^i \geq x_t^i - x_{t-1}^i && \forall i \in \{1, \dots, n\}, \forall t \in \{2, \dots, T\} \\
 & \sum_{i=1}^n p_t^i \geq D_t && \forall t \in \{1, \dots, T\} \\
 & P_{\min}^i x_t^i \leq p_t^i \leq P_{\max}^i x_t^i && \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\} \\
 & u_t^i, x_t^i \in \{0, 1\}, p_t^i \in \mathbb{R} && \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}
 \end{aligned}$$

Construction of aggregated MUCP formulation

$$\tilde{x}_{t,J} = \sum_{i \in J} x_t^i$$

$$\tilde{u}_{t,J} = \sum_{i \in J} u_t^i$$

$$\tilde{p}_{t,J} = \sum_{i \in J} p_t^i$$

First step: $\sum_{i=1}^n$ replaced by $\sum_{J \in PC} \sum_{i \in J}$

$$v = \min_{x,u,p} \sum_{t=1}^T \sum_{i=1}^n c_f^i x_t^i + c_p^i p_t^i + c_0^i u_t^i$$

$$\text{s. t.} \quad \sum_{t'=t-L^i+1}^t u_{t'}^i \leq x_t^i \quad \forall i \in \{1, \dots, n\}, \forall t \in \{L^i, \dots, T\}$$

$$\sum_{t'=t-l^i+1}^t u_{t'}^i \leq 1 - x_{t-l^i}^i \quad \forall i \in \{1, \dots, n\}, \forall t \in \{l^i + 1, \dots, T\}$$

$$u_t^i \geq x_t^i - x_{t-1}^i \quad \forall i \in \{1, \dots, n\}, \forall t \in \{2, \dots, T\}$$

$$\sum_{i=1}^n p_t^i \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$P_{\min}^i x_t^i \leq p_t^i \leq P_{\max}^i x_t^i \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}$$

$$u_t^i, x_t^i \in \{0, 1\}, p_t^i \in \mathbb{R} \quad \forall i \in \{1, \dots, n\}, \forall t \in \{1, \dots, T\}$$

Construction of aggregated MUCP formulation

$$\tilde{x}_{t,J} = \sum_{i \in J} x_t^i$$

$$\tilde{u}_{t,J} = \sum_{i \in J} u_t^i$$

$$\tilde{p}_{t,J} = \sum_{i \in J} p_t^i$$

First step: $\sum_{i=1}^n$ replaced by $\sum_{J \in PC} \sum_{i \in J}$

$$\tilde{v} = \min_{\tilde{x}, \tilde{u}, \tilde{p}} \sum_{t=1}^T \sum_{J \in PC} \sum_{i \in J} c_f^i x_t^i + c_p^i p_t^i + c_0 u_t^i$$

$$\text{s. t.} \quad \sum_{t'=t-L^i+1}^t u_{t'}^i \leq x_t^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{L^i, \dots, T\}$$

$$\sum_{t'=t-\ell^i+1}^t u_{t'}^i \leq 1 - x_{t-\ell^i}^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{\ell^i + 1, \dots, T\}$$

$$u_t^i \geq x_t^i - x_{t-1}^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{2, \dots, T\}$$

$$\sum_{J \in PC} \sum_{i \in J} p_t^i \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$P_{\min}^i x_t^i \leq p_t^i \leq P_{\max}^i x_t^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$u_t^i, x_t^i \in \{0, 1\}, p_t^i \in \mathbb{R} \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$\tilde{x}_{t,J} = \sum_{i \in J} x_t^i$$

$$\tilde{u}_{t,J} = \sum_{i \in J} u_t^i$$

$$\tilde{p}_{t,J} = \sum_{i \in J} p_t^i$$

Second step: x_t^i , u_t^i , p_t^i replaced by $\frac{\tilde{x}_{t,J}}{|J|}$, $\frac{\tilde{u}_{t,J}}{|J|}$, $\frac{\tilde{p}_{t,J}}{|J|}$

$$\tilde{v} = \min_{\tilde{x}, \tilde{u}, \tilde{p}} \sum_{t=1}^T \sum_{J \in PC} \sum_{i \in J} c_f^i x_t^i + c_p^i p_t^i + c_0^i u_t^i$$

$$\text{s. t.} \quad \sum_{t'=t-L^i+1}^t u_{t'}^i \leq x_t^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{L^i, \dots, T\}$$

$$\sum_{t'=t-\ell^i+1}^t u_{t'}^i \leq 1 - x_{t-\ell^i}^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{\ell^i + 1, \dots, T\}$$

$$u_t^i \geq x_t^i - x_{t-1}^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{2, \dots, T\}$$

$$\sum_{J \in PC} \sum_{i \in J} p_t^i \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$P_{min}^i x_t^i \leq p_t^i \leq P_{max}^i x_t^i \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$u_t^i, x_t^i \in \{0, 1\}, p_t^i \in \mathbb{R} \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$\tilde{x}_{t,J} = \sum_{i \in J} x_t^i$$

$$\tilde{u}_{t,J} = \sum_{i \in J} u_t^i$$

$$\tilde{p}_{t,J} = \sum_{i \in J} p_t^i$$

Second step: x_t^i , u_t^i , p_t^i replaced by $\frac{\tilde{x}_{t,J}}{|J|}$, $\frac{\tilde{u}_{t,J}}{|J|}$, $\frac{\tilde{p}_{t,J}}{|J|}$

$$\tilde{v} = \min_{\tilde{x}, \tilde{u}, \tilde{p}} \sum_{t=1}^T \sum_{J \in PC} \sum_{i \in J} c_f^i \frac{\tilde{x}_{t,J}}{|J|} + c_p^i \frac{\tilde{p}_{t,J}}{|J|} + c_0^i \frac{\tilde{u}_{t,J}}{|J|}$$

$$\text{s. t.} \quad \sum_{t'=t-L^J+1}^t \frac{\tilde{u}_{t',J}}{|J|} \leq \frac{\tilde{x}_{t,J}}{|J|} \quad \forall i \in J, \forall J \in PC, \forall t \in \{L^J, \dots, T\}$$

$$\sum_{t'=t-\ell^J+1}^t \frac{\tilde{u}_{t',J}}{|J|} \leq 1 - \frac{\tilde{x}_{t-\ell^J,J}}{|J|} \quad \forall i \in J, \forall J \in PC, \forall t \in \{\ell^J + 1, \dots, T\}$$

$$\frac{\tilde{u}_{t,J}}{|J|} \geq \frac{\tilde{x}_{t,J}}{|J|} - \frac{\tilde{x}_{t-1,J}}{|J|} \quad \forall j \in J, \forall J \in PC, \forall t \in \{2, \dots, T\}$$

$$\sum_{J \in PC} \sum_{i \in J} \frac{\tilde{p}_{t,J}}{|J|} \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$P_{\min}^i \frac{\tilde{x}_{t,J}}{|J|} \leq \frac{\tilde{p}_{t,J}}{|J|} \leq P_{\max}^i \frac{\tilde{x}_{t,J}}{|J|} \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$\tilde{x}_{t,J}, \tilde{u}_{t,J} \in \{0, 1, \dots, |J|\}, \tilde{p}_{t,J} \in \mathbb{R} \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$\tilde{x}_{t,J} = \sum_{i \in J} x_t^i$$

$$\tilde{u}_{t,J} = \sum_{i \in J} u_t^i$$

$$\tilde{p}_{t,J} = \sum_{i \in J} p_t^i$$

Simplify with $|J|$

$$\tilde{v} = \min_{\tilde{x}, \tilde{u}, \tilde{p}} \sum_{t=1}^T \sum_{J \in PC} \sum_{i \in J} c_f^i \frac{\tilde{x}_{t,J}}{|J|} + c_p^i \frac{\tilde{p}_{t,J}}{|J|} + c_0^i \frac{\tilde{u}_{t,J}}{|J|}$$

$$\text{s. t.} \quad \sum_{t'=t-L^J+1}^t \frac{\tilde{u}_{t',J}}{|J|} \leq \frac{\tilde{x}_{t,J}}{|J|} \quad \forall i \in J, \forall J \in PC, \forall t \in \{L^J, \dots, T\}$$

$$\sum_{t'=t-\ell^J+1}^t \frac{\tilde{u}_{t',J}}{|J|} \leq 1 - \frac{\tilde{x}_{t-\ell^J,J}}{|J|} \quad \forall i \in J, \forall J \in PC, \forall t \in \{\ell^J + 1, \dots, T\}$$

$$\frac{\tilde{u}_{t,J}}{|J|} \geq \frac{\tilde{x}_{t,J}}{|J|} - \frac{\tilde{x}_{t-1,J}}{|J|} \quad \forall i \in J, \forall J \in PC, \forall t \in \{2, \dots, T\}$$

$$\sum_{J \in PC} \sum_{i \in J} \frac{\tilde{p}_{t,J}}{|J|} \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$P_{\min}^i \frac{\tilde{x}_{t,J}}{|J|} \leq \frac{\tilde{p}_{t,J}}{|J|} \leq P_{\max}^i \frac{\tilde{x}_{t,J}}{|J|} \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$\tilde{x}_{t,J}, \tilde{u}_{t,J} \in \{0, 1, \dots, |J|\}, \tilde{p}_{t,J} \in \mathbb{R} \quad \forall i \in J, \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$\tilde{x}_{t,J} = \sum_{i \in J} x_t^i$$

$$\tilde{u}_{t,J} = \sum_{i \in J} u_t^i$$

$$\tilde{p}_{t,J} = \sum_{i \in J} p_t^i$$

Simplify with $|J|$

$$\tilde{v} = \min_{\tilde{x}, \tilde{u}, \tilde{p}} \sum_{t=1}^T \sum_{J \in PC} c_f^i \tilde{x}_{t,J} + c_p^i \tilde{p}_{t,J} + c_0^i \tilde{u}_{t,J}$$

$$\text{s. t.} \quad \sum_{t'=t-L^J+1}^t \tilde{u}_{t',J} \leq \tilde{x}_{t,J} \quad \forall J \in PC, \forall t \in \{L^J, \dots, T\}$$

$$\sum_{t'=t-\ell^J+1}^t \tilde{u}_{t',J} \leq |J| - \tilde{x}_{t-\ell^J,J} \quad \forall J \in PC, \forall t \in \{\ell^J + 1, \dots, T\}$$

$$\tilde{u}_{t,J} \geq \tilde{x}_{t,J} - \tilde{x}_{t-1,J} \quad \forall J \in PC, \forall t \in \{2, \dots, T\}$$

$$\sum_{J \in PC} \tilde{p}_{t,J} \geq D_t \quad \forall t \in \{1, \dots, T\}$$

$$P_{\min}^i \tilde{x}_{t,J} \leq \tilde{p}_{t,J} \leq P_{\max}^i \tilde{x}_{t,J} \quad \forall J \in PC, \forall t \in \{1, \dots, T\}$$

$$\tilde{x}_{t,J}, \tilde{u}_{t,J} \in \{0, 1, \dots, |J|\}, \tilde{p}_{t,J} \in \mathbb{R} \quad \forall J \in PC, \forall t \in \{1, \dots, T\}$$

Aggregated MUCP formulation

$$\begin{aligned}
 \tilde{v} = \min_{\tilde{x}, \tilde{u}, \tilde{p}} & \sum_{t=1}^T \sum_{J \in PC} c_f^i \tilde{x}_{t,J} + c_p^i \tilde{p}_{t,J} + c_0^i \tilde{u}_{t,J} \\
 \text{s. t.} & \sum_{t'=t-L^J+1}^t \tilde{u}_{t',J} \leq \tilde{x}_{t,J} && \forall J \in PC, \forall t \in \{L^J, \dots, T\} \\
 & \sum_{t'=t-\ell^J+1}^t \tilde{u}_{t',J} \leq |J| - \tilde{x}_{t-\ell^J,J} && \forall J \in PC, \forall t \in \{\ell^J + 1, \dots, T\} \\
 & \tilde{u}_{t,J} \geq \tilde{x}_{t,J} - \tilde{x}_{t-1,J} && \forall J \in PC, \forall t \in \{2, \dots, T\} \\
 & \sum_{J \in PC} \tilde{p}_{t,J} \geq D_t && \forall t \in \{1, \dots, T\} \\
 & P_{\min}^i \tilde{x}_{t,J} \leq \tilde{p}_{t,J} \leq P_{\max}^i \tilde{x}_{t,J} && \forall J \in PC, \forall t \in \{1, \dots, T\} \\
 & \tilde{x}_{t,J}, \tilde{u}_{t,J} \in \{0, 1, \dots, |J|\}, \tilde{p}_{t,J} \in \mathbb{R} && \forall J \in PC, \forall t \in \{1, \dots, T\}
 \end{aligned}$$

Here $\tilde{v} = v$: linked to the **total unimodularity** of **blue constraints matrix**.

(Baum and Trotter, 1979)

Aggregation in practice

For the MUCP:

- **Aggregate** variables corresponding to identical units
- **Solve** the aggregated ILP
- **Disaggregate** the obtained aggregated solution
(a simple algorithm exists)

Very efficient in practice!

But as soon as **ramp constraints** are taken into account:

→ **disaggregation no longer possible.**

→ other symmetry-breaking techniques must be used

- ▷ **Lima, R.M., Novais, A.Q.:** Symmetry breaking in MILP formulations for Unit Commitment problems. *Computers & Chemical Engineering* 85, 162176 (2016)
- ▷ **Ostrowski, J., Anjos, M., Vannelli, A.:** Modified orbital branching for structured symmetry with an application to unit commitment. *Mathematical Programming* 150(1), 99 – 129 (2015)
- ▷ **Kaibel, V., Loos, A.:** Branched polyhedral systems. *In: Proceedings of IPCO 2010. Springer-Verlag* (2010)
- ▷ **Kaibel, V., Pfetsch, M.:** Packing and partitioning orbitopes. *Mathematical Programming* 114(1), 1–36 (2008)
- ▷ **Kaibel, V., Peinhardt, M., Pfetsch, M.E.:** Orbitopal fixing. *Discrete Optimization* 8(4), 595–610 (2011)
- ▷ **Bendotti, P., Fouilhoux, P., Rottner, C.:** Sub-symmetry-breaking inequalities for ILP with structured symmetry. *In proceedings of IPCO 2019, LNCS, volume 11480, pp. 57–71* (2019)
- ▷ **Bendotti, P., Fouilhoux, P., Rottner, C.:** Orbitopal Fixing for the full (sub-)orbitope and application to the unit commitment problem. *Optimization Online* (2018)
- ▷ **Fischetti, M., Liberti, L., Salvagnin, D., Walsh, T.:** Orbital shrinking: Theory and applications. *Discrete Applied Mathematics*, 222, pp. 109–123. (2017)
- ▷ **Baum, S., Trotter, L.E.:** Integer rounding and polyhedral decomposition for totally unimodular systems. *Optimization and Operations Research*, pp. 15–23 (1978)
- ▷ **Knueven, B., Ostrowski, J., Watson, J.P.:** Exploiting identical generators in unit commitment. *IEEE Transactions on Power Systems* (2017)