

Lecture

Solving combinatorial optimization problems using mathematical programming

Section 0 : Introduction

Pierre Fouilhoux

Université Sorbonne Paris Nord - LIPN CNRS

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1. Definition and complexity
2. List of OC problems

1. Definition and complexity

1.1 Two first problems

1.2 Combinatorial explosion

1.3 Problem complexity

1.4 \mathcal{NP} -hard

1.5 Strongly or weakly \mathcal{NP} -hard

2. List of OC problems

A Combinatorial Optimization Problem

is to

find a greatest (smallest) element
within a valuated finite set.

Combinatorial Optimization Problem

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To find a greatest (smallest) element within a valuated finite set.

Given :

- a finite subset of elements $E = \{e_1, \dots, e_n\}$
- a **solution set** \mathcal{F} of subsets of E
- a weight $c = (c(e_1), \dots, c(e_n))$

a **Combinatorial Optimization Problem** is to find a solution $F \in \mathcal{F}$ whose weight $c(F) = \sum_{e \in F} c(e)$ is maximum (or min.),

$$\text{i.e. } \max \{c(F) \mid F \in \mathcal{F}\}.$$

└ Definition and complexity

└ Two first problems

1. Definition and complexity

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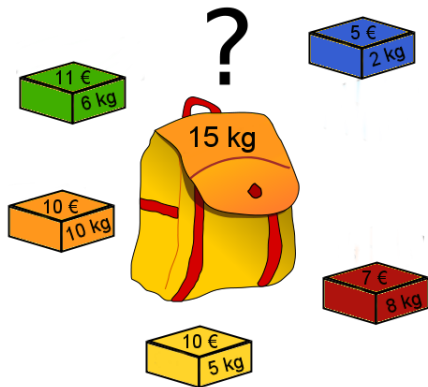
1.4 \mathcal{NP} -hard

1.5 Strongly or weakly \mathcal{NP} -hard

2. List of OC problems

The knapsack problem

Which boxes to chose
to maximize the profit
without exceeding 15kg ?



Définition

Let us consider n **objects**.

Each object $i \in \{1, \dots, n\}$

- with a **profit** g_i

- with a **weight** p_i

to be put inside a knapsack of **maximum total weight** P .

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its weight $\sum_{i \in S} p_i$ is non-greater than P (*Knapsack Constraint*)

its profit $\sum_{i \in S} g_i$ is maximum. (*Objective function*)

How to incode a knapsack solution ?

An instance is given by :

i	1	2	3	4	5	
g_i	5	7	10	11	10	
p_i	2	8	10	6	5	≤ 15

A solution $S \subset \{1, \dots, n\}$

is corresponding to

an incidence vector χ^S

such that

$$\chi^S[i] = \begin{cases} 1 & \text{if } i \in S \\ 0 & \text{otherwise.} \end{cases}$$

$$S_1 = \{1, 2, 5\}$$

$$\chi^{S_1} = \begin{array}{|c|c|c|c|c|} \hline 1 & 1 & 0 & 0 & 1 \\ \hline \end{array}$$

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$$\begin{array}{rcl} \text{profit :} & 5 & 7 & & 10 & = & 22 \\ \text{weight :} & 2 & 8 & & 5 & = & 15 \end{array}$$

└ Definition and complexity

└ Two first problems

How to test whether a vector is a solution ?

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Recognition Algorithm :

$pds \leftarrow 0$

For i from 1 to n

$pds \leftarrow pds + p_i * \chi^S[i]$

EndFor

If $pds \leq P$ **Then** True

Else False

$$S_2 = \{1, 4, 5\}$$

$$\chi^{S_2} = \begin{array}{|c|c|c|c|c|} \hline 1 & 0 & 0 & 1 & 1 \\ \hline \end{array}$$

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$$\text{weight : } \quad 2 \quad \quad \quad 6 \quad 5 \quad = 13$$

Solution of profit 26

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$$\text{weight : } \quad 2 \quad 8 \quad \quad 6 \quad \quad = 16$$

Not a solution.

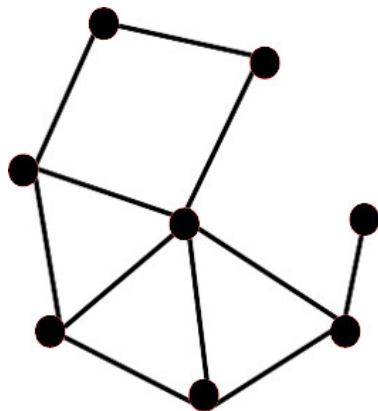
└ Definition and complexity

└ Two first problems

Huge knapsacks...



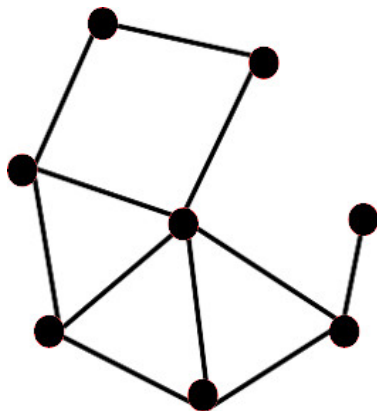
Graph



A **graph** $G = (V, E)$ is a pair where

- V is the node set
- $E \subseteq V \times V$ is the edge set.

Graph

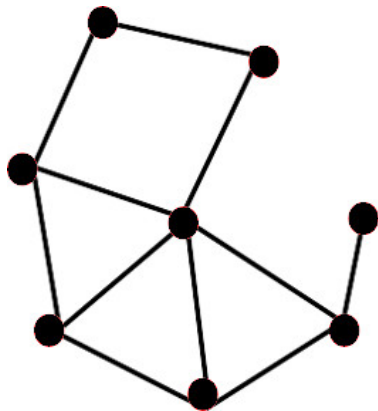


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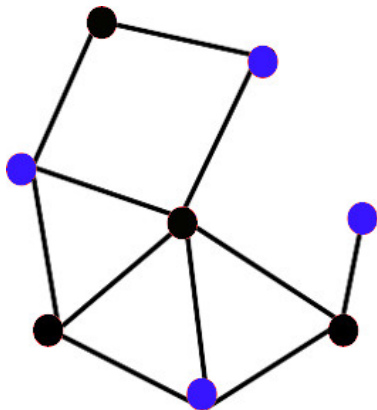
Two nodes are **adjacent** if they are linked by an edge.

Stable Set problem



A **stable set**
(or independent set)
is a pairwise non-adjacent node
subset.

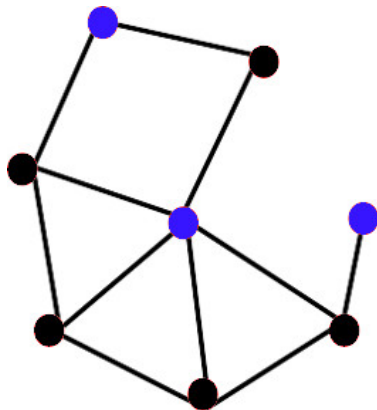
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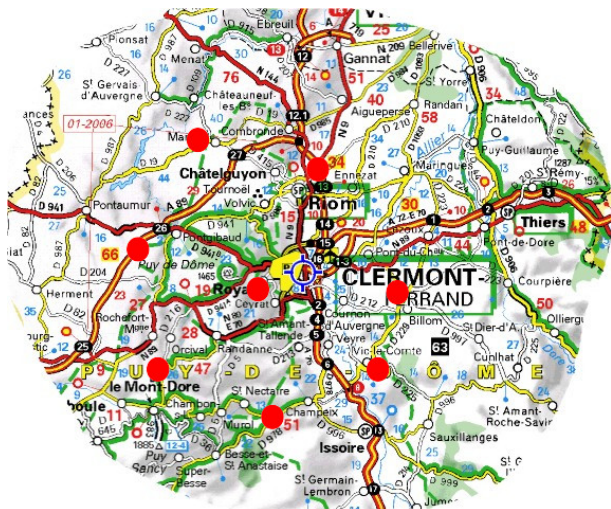
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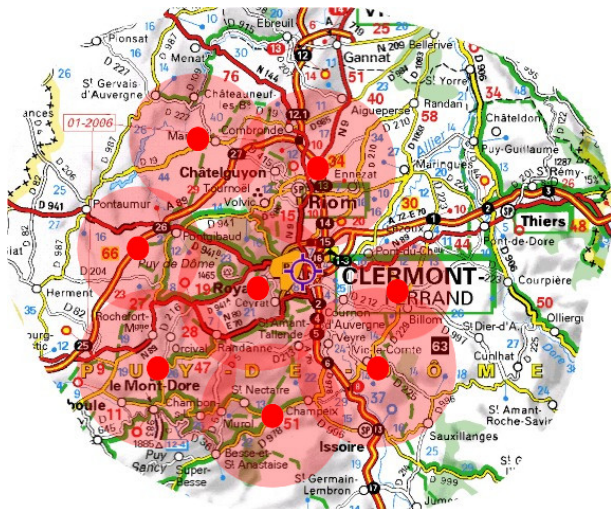
└ Definition and complexity

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A set of antennas

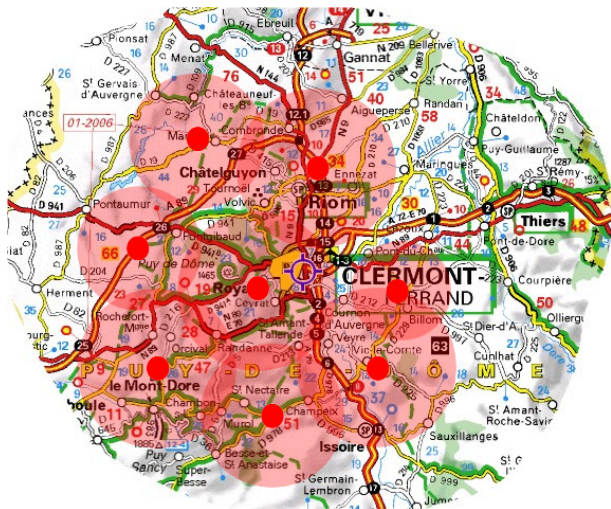


A set of antennas with their interference disks

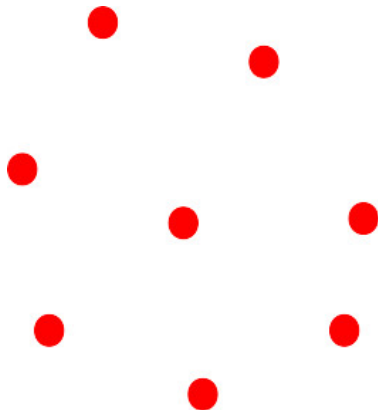


- └ Definition and complexity
- └ Two first problems

How to find a subset of antennas with no interference?



A model graph



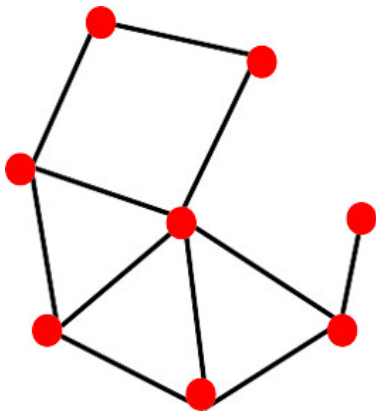
Un graphe $G = (S, V)$

avec

- V : a node by antenna
- E : an edge between two antennas if their interference disks are in conflict.

Finding a subset of antennas with no interference reduces to the stable set problem.

A model graph



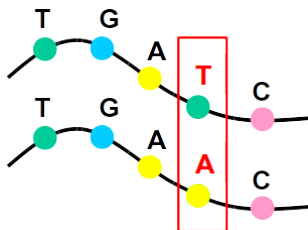
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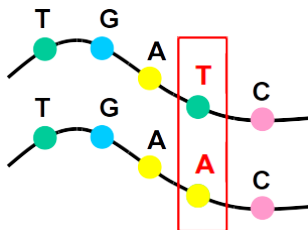
Combinatorics within genomic



Genome sequencing involves sorting through small fragments of DNA (called SNPs) that have been sequenced using bio-mechanical processes. In the process, false SNPs are created.

We want to sort the fragments, omitting as few SNPs as possible.

Combinatorics within genomic

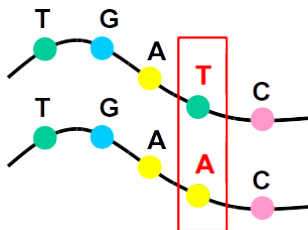


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Its a **Combinatorial optimisation problem**

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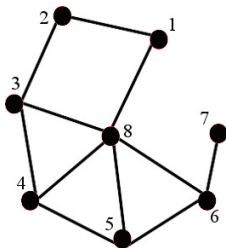
Its a **Combinatorial optimisation problem**

which also reduces to the **stable set problem** !.

Lippert, R., Schwartz, R., Lancia, G., Istrail, S. : Algorithmic strategies for the single nucleotide polymorphism haplotype assembly problem. *Brief. Bioinform* 3, 23–31 (2002)

How to incode a stable set solution ??

Instance given by
a graph with
 n nodes.



A solution $S \subset \{1, \dots, n\}$
is corresponding to an

vecteur d'incidence χ^S

such that

$$\chi^S[i] = \begin{cases} 1 & \text{si } i \in S \\ 0 & \text{sinon.} \end{cases}$$

$$S_1 = \{1, 7, 8\}$$

$$\chi^{S_1} = \begin{array}{c|cccccccc} i & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{array}$$

How to test whether a vector is a solution ?

Recognition Algorithm :

For i from 1 to n

For j from 1 to n

If $\{i, j\}$ is an edge

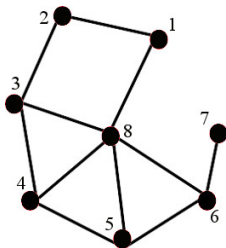
and if $\chi^S[i] = 1$ and $\chi^S[j] = 1$

Then STOP : False

EndFor

EndFor

STOP : True



$$S_1 = \{2, 7, 8\}$$

$$\chi^{S_1} = \begin{array}{c} i \\ \begin{array}{|c|c|c|c|c|c|c|c|} \hline 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 0 & 1 & 0 & 0 & 0 & 0 & 1 & 1 \\ \hline \end{array} \end{array}$$

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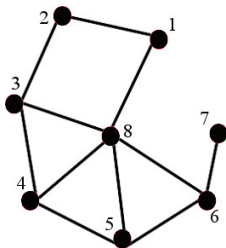
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Solution (with 3 nodes

- └ Definition and complexity
- └ Combinatorial explosion

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1.4 \mathcal{NP} -hard

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2. List of OC problems

- └ Definition and complexity
- └ Combinatorial explosion

Recognition algorithms

Knapsack

$pds \leftarrow 0$

For i from 1 to n

$pds \leftarrow pds + p_i * \chi^S[i]$

EndFor

If $pds \leq P$ **Then** True

Else False

Execution time
proportionnal to n .

- └ Definition and complexity
- └ Combinatorial explosion

Recognition algorithms

Knapsack

```

pds ← 0
For i from 1 to n
    pds ← pds + pi *  $\chi^S[i]$ 
EndFor
If pds ≤ P Then True
    Else False
  
```

Execution time
proportionnal to n .

Stable set

```

For i from 1 to n
    For j from 1 to n
        If {i, j} is an edge
            and if  $\chi^S[i] = 1$ 
            and  $\chi^S[j] = 1$ 
                Then
                    STOP : False
        EndFor
    EndFor
    STOP : True
  
```

Execution time
proportionnal to n^2 .

- └ Definition and complexity
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Polynomial Algorithms

which can be fast ($\leq n^4$ for instance).

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Solving algorithms

- └ Definition and complexity
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Solving algorithms

Which is the complexity of the best known “Generic Algorithm” so find the optimal solution of combinatorial optimization problems?

- └ Definition and complexity
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Recognition algorithms

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Execution time
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Polynomial Algorithms

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Solving algorithms

Which is the complexity of the best known “Generic Algorithm” so find the optimal solution of combinatorial optimization problems?

Only **very very slow** algorithms with an execution time proportional to $2^n, 3^n, !n$

Exponential algorithms.

- └ Definition and complexity
- └ Combinatorial explosion

Enumerate ?

Consider an optimization problem with n elements.

Assuming that we know a **polynomial** (and. fast) algorithm for recognizing a solution,
can we find the best solution through enumeration ?

- └ Definition and complexity
- └ Combinatorial explosion

Enumerate ?

Consider an optimization problem with n elements.

Assuming that we know a **polynomial** (and. fast) algorithm for recognizing a solution,
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For each subset S of elements

$\chi^S \leftarrow$ the incidence vector of S .

Recognition algorithm for χ^S .

If χ^S is a solution

Stock S as the best known solution encountered yet.

EndFor

STOP : the stocked solution.

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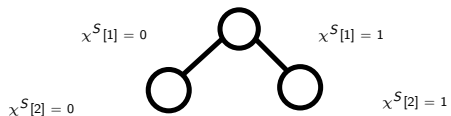
EndFor

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There are 2^n **subsets** : **exponential** execution time !

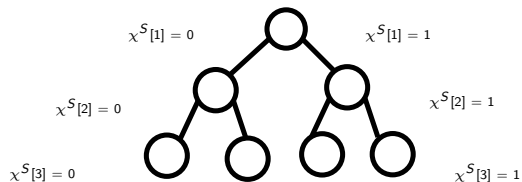
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Combinatorial explosion



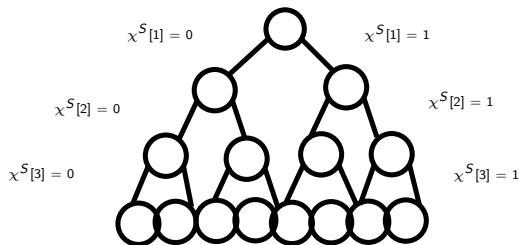
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Combinatorial explosion



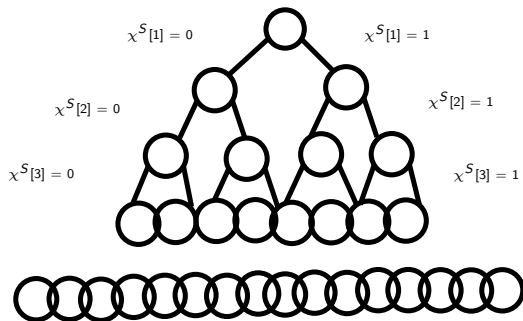
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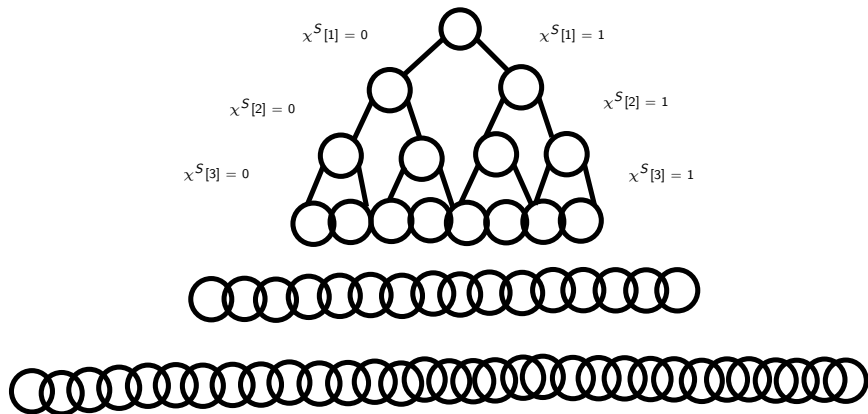
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Combinatorial explosion

Let's take one of the most powerful computers in 2015

Tianhe-2 (China)

33.86 petaflops where 1 petaflop represents the processing of 10^{15} operations per second (one million billion).

Assume that the recognition algorithm takes $100n$ elementary operations. For $n = 10$, we can process 33 860 billion subsets in 1 second !

n	Tianhe-2			Futuristic Computer
	n^3	n^5	$100n2^n$	$100n2^n$
10	0,00...001 sec	0,00...001 sec		
20	0,00...001 sec	0,00...001 sec		
50	0,00...001 sec	0,00...001 sec		
60	0,00...001 sec	0,00000002 sec		
80	0,00...001 sec	0,0000009 sec		
100	0,00...001 sec	0,0000003 sec		
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50	0,00...001 sec	0,00...001 sec	168,9 sec	
60	0,00...001 sec	0,00000002 sec	57,6 h	
80	0,00...001 sec	0,0000009 sec	9200 years	
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100	0,00...001 sec	0,0000003 sec	$1,21 \cdot 10^{10}$ years	
1000	0,00000003 sec	0,03 sec	$1 \cdot 10^{282}$ years	

Age of the universe $13,7 \cdot 10^9$ years

- └ Definition and complexity
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Combinatorial explosion

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Tianhe-2 (China)

33.86 petaflops where 1 petaflop represents the processing of 10^{15} operations per second (one million billion).

Assume that the recognition algorithm takes $100n$ elementary operations. For $n = 10$, we can process 33 860 billion subsets in 1 second !

n	Tianhe-2			Futuristic Computer
	n^3	n^5	$100n2^n$	$100n2^n$
10	0,00...001 sec	0,00...001 sec	0,00...001 sec	0,00...001 sec
20	0,00...001 sec	0,00...001 sec	0,00000006 sec	0,00...001 sec
50	0,00...001 sec	0,00...001 sec	168,9 sec	0,000001 sec
60	0,00...001 sec	0,00000002 sec	57,6 h	0,0001 sec
80	0,00...001 sec	0,0000009 sec	9200 years	100 years
100	0,00...001 sec	0,0000003 sec	$1,21 \cdot 10^{10}$ years	$1,21 \cdot 10^9$ years
1000	0,00000003 sec	0,03 sec	$1 \cdot 10^{282}$ years	...

Age of the universe $13,7 \cdot 10^9$ years

- └ Definition and complexity
- └ Combinatorial explosion

Combinatorial Explosion

Enumerating 2^n solutions is not a technical problem that very powerful computers could sweep away.

It's necessary to **circumvent the combinatorial explosion** with mathematical and algorithmic tools.

└ Definition and complexity

└ Problem complexity

1. Definition and complexity

1.1 Two first problems

1.2 Combinatorial explosion

1.3 Problem complexity

1.4 \mathcal{NP} -hard

1.5 Strongly or weakly \mathcal{NP} -hard

2. List of OC problems

└ Definition and complexity

└ Problem complexity

Problem complexity

Just because we know an exponential algorithm for solving a problem doesn't mean it's difficult !

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We're looking for the **fastest** algorithm to solve a problem !

└ Definition and complexity

└ Problem complexity

Problem Complexity

A problem is **of exponential complexity**
if an exponential algorithm exists to solve it.
⇒ the problem class \mathcal{EXP} .

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Question : In what complexity classes are Combinatorial Optimization problems ?

\mathcal{NP} problems

A particular classe have been created...

Combinatorial optimization problems for which we know **how to recognize a solution** with a polynomial algorithm

⇒ the problem class \mathcal{NP} “Nondeterministic polynomial time”

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\mathcal{NP} problems

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Combinatorial optimization problems for which we know **how to recognize a solution** with a polynomial algorithm

⇒ the problem class \mathcal{NP} “Nondeterministic polynomial time”

Under this assumption, we've seen that it's possible to use an exponential enumeration algorithm, then

⇒ $\mathcal{NP} \subset \mathcal{EXP}$

In addition, a polynomial problem is in \mathcal{NP}

⇒ $\mathcal{P} \subset \mathcal{NP} \subset \mathcal{EXP}$

And then ?

Is \mathcal{P} equal to \mathcal{NP} ?

i.e.

“Is there a polynomial algorithm for solving combinatorial optimization problems?”

Answer :

And then ?

Is \mathcal{P} equal to \mathcal{NP} ?

i.e.

“Is there a polynomial algorithm for solving combinatorial optimization problems?”

Answer : We don't know !

On a human scale, we only know this enumeration algorithm !

It's one of the 7 problems in the Clay Mathematics Institute of Cambridge's million-dollar Millennium Prize Problems !

└ Definition and complexity

└ \mathcal{NP} -hard

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a knapsack with all objects of the same weight.

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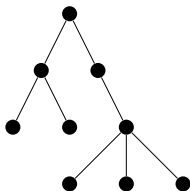
A **greedy** algorithm :

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This algorithm is polynomial (of the order of n^2).

A very simple stable set subcase

Let's look at a very simple stable set instance :
finding a maximum cardinality stable set over a **tree**.



Tree property :

Given a leaf v , there exists a maximum cardinality stable set containing v .

(Proof : Let v a leaf and u its unique neighbour. Let S be a maximum stable set. Either $u \notin S$, then $S \cup \{v\}$; or $u \in S$, then $S \cup \{u\} \setminus \{v\}$ is another maximum stable set).

A very simple stable set subcase

A **greedy** algorithm :

$S \leftarrow \emptyset$

While G has at least one edge

 Let v be a leaf and u its neighbour

$S \leftarrow S \cup \{v\}$

 Delete from G nodes u and v and all their incident edges

EndWhile

Add to S all the remaining nodes.

STOP : S

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This algorithm is polynomial (of the order of n).

\mathcal{NP} -hard

In the current state of scientific knowledge, it is not known whether or not there is a polynomial algorithm for solving the knapsack or the stable set problem in general !

\mathcal{NP} -hard

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In fact, we were able to prove that knapsack or the stable set problems are just as difficult as all the problems in the \mathcal{NP} class !

A problem is said to be **\mathcal{NP} -hard**
if it is as difficult as any problem in the \mathcal{NP} class.
⇒ the problem class \mathcal{NP} -hard.

\mathcal{NP} -hardness



Boss, I can't find a polynomial algorithm for the stable set problem

Figure from "The Garey et Johnson"

\mathcal{NP} -hardness



But if you think I'm just an ungifted searcher

Figure from "The Garey et Johnson"

\mathcal{NP} -hardness



...neither are all the others!

- └ Definition and complexity
 - └ Strongly or weakly \mathcal{NP} -hard

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- 1.1 Two first problems
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2. List of OC problems

- └ Definition and complexity
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Strongly or weakly \mathcal{NP} -hard

A computational problem may have numerical parameters : like the weight of a knapsack.

A \mathcal{NP} -hard problem is said to be **weakly \mathcal{NP} -hard** if there is an algorithm for the problem whose running time is polynomial in the dimension of the problem and magnitudes of its data.

And otherwise, it is called **strongly \mathcal{NP} -hard**.

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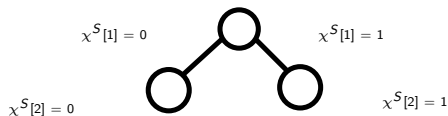
And otherwise, it is called **strongly \mathcal{NP} -hard**.

For weakly \mathcal{NP} -hard, it's often the case, that there exists a **dynamizing programming scheme** whose complexity depends on the magnitudes of the data.

- └ Definition and complexity
- └ Strongly or weakly \mathcal{NP} -hard

Dynamic Programming scheme

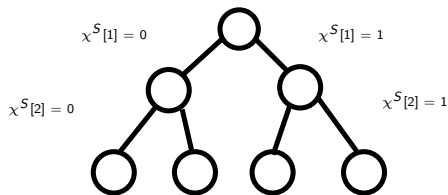
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this puts the brakes on the combinatorial explosion.



- └ Definition and complexity
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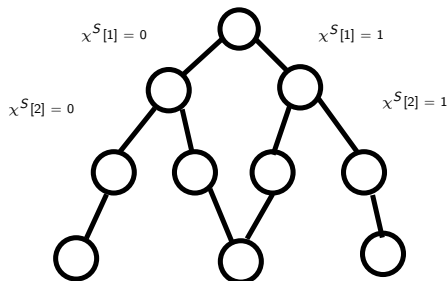
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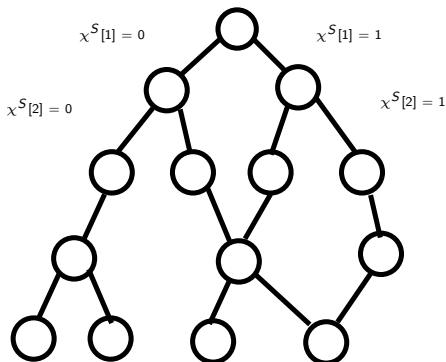
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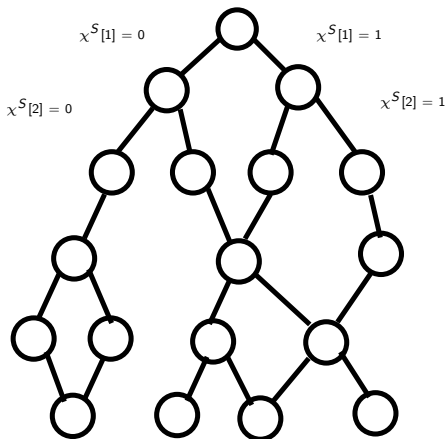
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Dynamic Programming scheme

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1. Definition and complexity

2. List of OC problems

Knapsack problem

Input : n objects
 profit $g_i \forall i \in \{1, \dots, n\}$
 weight $p_i \forall i \in \{1, \dots, n\}$
 maximum total weight P .

Output : Subset $S \subseteq \{1, \dots, n\}$
 s.t. $\sum_{i \in S} p_i \leq P$

Objective : Max $\sum_{i \in S} w_i$

Knapsack MIP

$$\text{Max } \sum_{i=1}^n w_i x_i$$

$$\sum_{i=1}^n p_i x_i \leq P,$$

$0 \leq x_i \leq 1$, pour tout objet $i = 1, \dots, n$,

$x_i \in \mathbf{N}$, pour tout objet $i = 1, \dots, n$.

Maximum weight stable set problem

Input : Undirected graph $G = (V, E)$
cost $w_u \forall u \in V$

Output : Subset $S \subseteq V$ of non-adjacent nodes

Objective : Max $\sum_{i \in S} w_i$

Complexity : Strongly NP-hard

Polynomial cases : perfect graphs (tree, planar, interval graphs...)

Difficulty : With MIP solver $n = 1000$ in often more than 1 hour
Some dedicated methodes (russian doll algo)

Shortest path problem

Input : Undirected (or directed) graph $G = (V, E)$
Two nodes $u_0, u_1 \in V$
Lengths $l_e \forall e \in E$

Output : Path μ of G from u_0 to u_1

Objective : $\text{Min} \sum_{e \in \mu} l_e$

Complexity : Polynomial

Difficulty : With Dijkstra algorithm up to thousand of nodes in a few sec

With A* algorithm, up to billions !

Shortest path problem



To quickly go from a point to another

The Traveling Salesman Problem (TSP)

Input : Undirected (or directed) graph $G = (V, E)$
length $l_e \forall e \in E$

Output : An hamiltonian cycle C of G (i.e. C goes once through each node)

Objective : Min $\sum_{e \in C} l_e$

Complexity : Strongly NP-hard

Polynomial cases : ?

Difficulty : Before 2003 : 200 nodes within several hours

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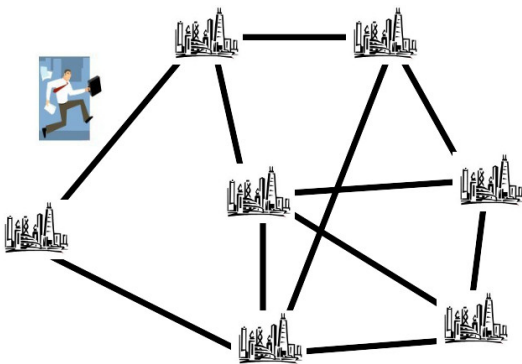
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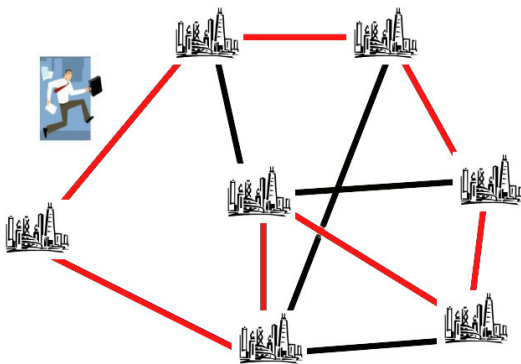
Concorde : a Branch-and-Cut algorithm and polyhedral results solves up to 200000 cities within one day !

The Traveling Salesman Problem (TSP)



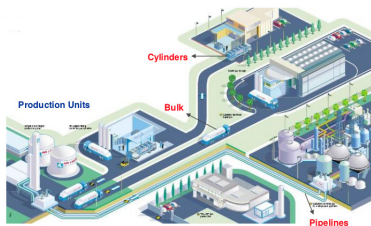
Starting from a city and going back to it going once through all the other cities with a shortest cycle.

The Traveling Salesman Problem (TSP)



Starting from a city and going back to it going once through all the other cities with a shortest cycle.

Real-world Operations Research problem



The **inventory routing problem** introduced by **Air Liquide** company with real daily data and questions to answer :

Determine routes for liquid oxygen trucks to deliver hospitals so that

- hospital tanks are never empty (remote monitoring)
- rounds are feasible within the driver's working day
- costs are minimized !

Source : ROADEF Challenge 2016

How to solve Combinatorial Optimization Problem ?

- If the instances are very large and the problem very hard to solve or if you do not have much time to spend on solving method

→ There exist methods to obtain “good” solutions (heuristics, meta-heuristics, machine learning...)

- If the problem is really important with a highly cost associated to solution and if you have some time (several hours...)

The optimal solution is to be computed !

→ We will see in this lecture **how to circumvent the combinatorial explosion using mathematical programming !**

The Traveling salesman problem has been solved till 200 000 cities !