

Brun expansions of stepped surfaces

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Porquerolles, June 12, 2007

main result:

Action of dual maps of *free group morphisms* over stepped planes and surfaces (extends the substitutive case). Hidden tool: *flip*.

Application 1 (now):

Define Brun expansions of stepped planes and surfaces.

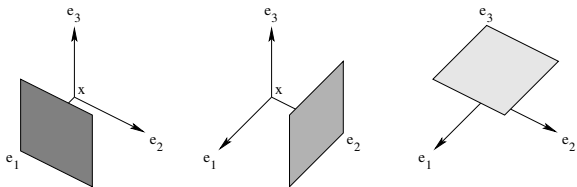
Application 2 (ask for details later):

Decide whether a given stepped surface is a stepped plane or not (and for patches too).

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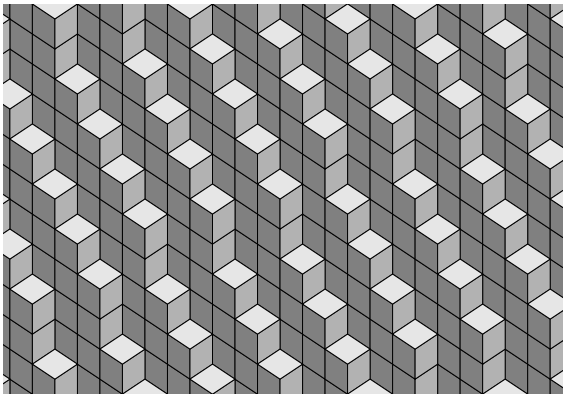
$(\vec{e}_1, \dots, \vec{e}_d)$ basis of \mathbb{R}^d . $\vec{x} \in \mathbb{Z}^d$, $i \in \{1, \dots, d\} \rightsquigarrow \text{face}(\vec{x}, i^*)$:



Definition

Stepped plane of normal vector $\vec{\alpha} \in \mathbb{R}_+^d \setminus \{0\}$:

$$\mathcal{P}_{\vec{\alpha}} = \{(\vec{x}, i^*) \mid \langle \vec{x}, \vec{\alpha} \rangle \leq 0 < \langle \vec{x} + \vec{e}_i, \vec{\alpha} \rangle\}.$$



A stepped plane.

Let π be the orthogonal projection along $\vec{u} = \vec{e}_1 + \dots + \vec{e}_d$.

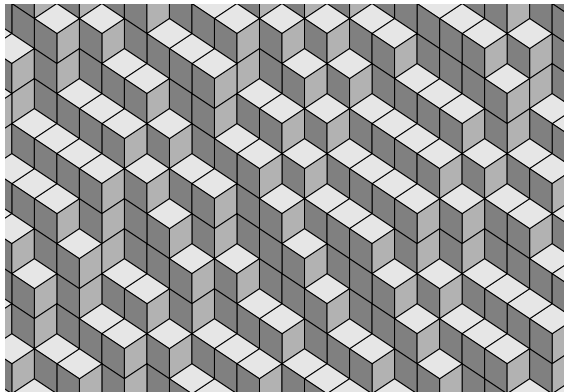
Proposition

Stepped planes are homeomorphic to \vec{u}^\perp by π .

By extension:

Definition [Jamet]

Stepped surfaces : any set of faces homeomorphic to \vec{u}^\perp by π .



A stepped surface.

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Morphism of the free group over $\{1, \dots, d\}$ (here, $d = 3$):

$$\sigma : \begin{cases} 1 \mapsto 3 \\ 2 \mapsto 3^{-1}1 \\ 3 \mapsto 3^{-1}2 \end{cases}$$

For example: $\sigma(1^{-1}312) = \sigma(1)^{-1}\sigma(3)\sigma(1)\sigma(2) = 3^{-2}21$.

Incidence matrix: $(M_\sigma)_{ij} = |\sigma(i)|_j - |\sigma(i)|_{j-1}$. Here:

$$M_\sigma = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & -1 \end{pmatrix}.$$

σ unimodular f. g. morph. \rightsquigarrow dual map $E_1^*(\sigma)$ over *weighted faces*.

For σ previously defined:

$$E_1^*(\sigma) : \begin{cases} (\vec{0}, 1^*) \mapsto (\vec{e}_1, 2^*) \\ (\vec{0}, 2^*) \mapsto (\vec{e}_1, 3^*) \\ (\vec{0}, 3^*) \mapsto (\vec{0}, 1^*) - (\vec{e}_1, 2^*) - (\vec{e}_1, 3^*). \end{cases}$$

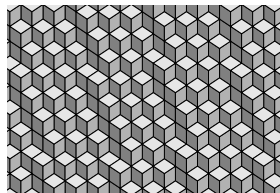
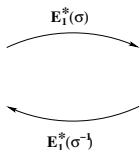
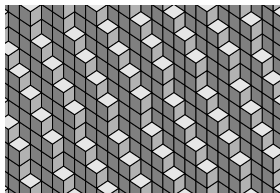
and, for $\lambda \in \mathbb{Z}$, $\vec{x} \in \mathbb{Z}^d$:

$$E_1^*(\sigma)(\lambda.(\vec{x}, i^*)) = M_\sigma^{-1}\vec{x} + \lambda.E_1^*(\sigma)(\vec{0}, i^*).$$

Theorem (B. F. 2007)

For σ unimodular free group morphism and $\vec{\alpha} \in \mathbb{R}_+^d \setminus \vec{0}$:

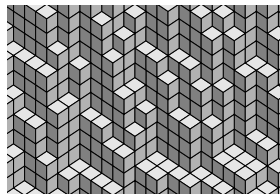
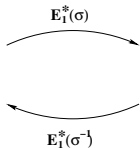
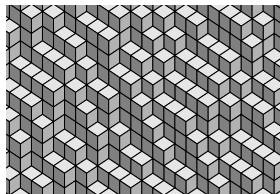
$$M_\sigma^\top \vec{\alpha} \in \mathbb{R}_+^d \Rightarrow E_1^*(\sigma)(\mathcal{P}_{\vec{\alpha}}) = \mathcal{P}_{M_\sigma^\top \vec{\alpha}}$$



Note: the action of $E_1^*(\sigma)$ depends only on M_σ (but not on σ).

Theorem (B. F. 2007)

For σ unimodular free group morphism: if the image by $E_1^(\sigma)$ of a stepped surface has faces with weights in $\{0, 1\}$, then it is a stepped surface. This holds, in particular, when $M_\sigma \geq 0$.*



Note: the action of $E_1^*(\sigma)$ depends only on M_σ (but not on σ).

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Brun map T , defined for $\vec{\alpha} = (\alpha_1, \dots, \alpha_d) \in \mathbb{R}^d \setminus \{0\}$:

$$T(\alpha_1, \dots, \alpha_d) = \left(\frac{\alpha_1}{\alpha_i}, \dots, \frac{\alpha_{i-1}}{\alpha_i}, \frac{1}{\alpha_i} - \left\lfloor \frac{1}{\alpha_i} \right\rfloor, \frac{\alpha_{i+1}}{\alpha_i}, \dots, \frac{\alpha_d}{\alpha_i} \right),$$

where $i = \min\{j \mid \alpha_j = \|\vec{\alpha}\|_\infty\}$. Matrix viewpoint:

$$(1, T(\vec{\alpha}))^\top \propto \begin{pmatrix} 0 & & & & 1 \\ & I_{i-1} & & & \\ 1 & & & & \\ & & & -a & \\ & & & & I_{d-i} \end{pmatrix} (1, \vec{\alpha})^\top$$

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Brun expansion $(a_n, i_n)_{n \geq 0}$ of $\vec{\alpha}$:

$$a_n = \lfloor \|T^n(\vec{\alpha})\|_\infty^{-1} \rfloor \quad \text{and} \quad i_n = \min\{j \mid \langle T^n(\vec{\alpha}) | \vec{e}_j \rangle = \|T^n(\vec{\alpha})\|_\infty\}.$$

How to define Brun exp. of given stepped planes (unknown normal vectors) so that $\mathcal{P}_{(1, \vec{\alpha})}$ will have the Brun exp. of $\vec{\alpha}$?

Note: if $i = \min\{j \mid \alpha_j = \|\vec{\alpha}\|_\infty\}$ and $a = \lfloor 1/\alpha_i \rfloor$ are known:

$$E_1^*(\beta_{a,i})(\mathcal{P}_{(1, \vec{\alpha})}) = \mathcal{P}_{(1, T(\vec{\alpha}))},$$

where $\beta_{a,i}$ has incidence matrix $B_{a,i}$ s.t. $B_{a,i}(1, \vec{\alpha}) = (1, T(\vec{\alpha}))$.

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Determining $(a, i) \rightsquigarrow$ *entries comparisons and floor computation.*

entries comparisons:

$(\vec{x}, (i+1)^*), (\vec{x} + \vec{e}_{j+1}, (i+1)^*) \triangleleft \mathcal{P}_{(1, \vec{\alpha})}$ for some \vec{x} yields $\alpha_i > \alpha_j$.

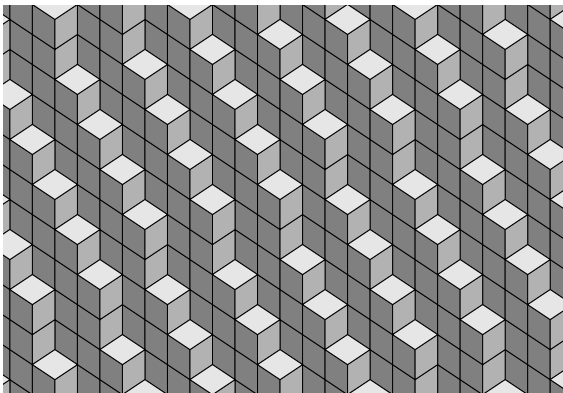
floor computation:

Let us introduce:

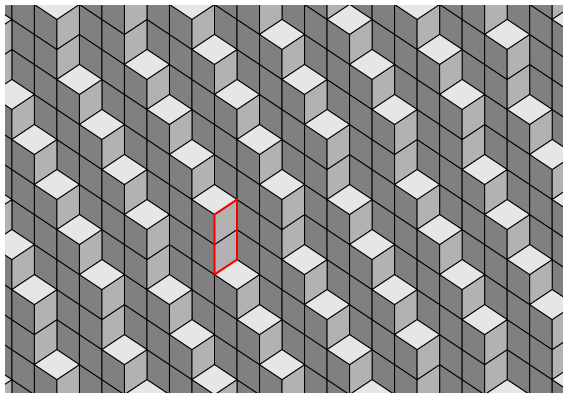
$$a_i(\mathcal{P}) = \max\{a \in \mathbb{N} \mid (\vec{x}, (i+1)^*) \triangleleft \mathcal{P} \Rightarrow (\vec{x} - k\vec{e}_{i+1}, 1^*)_{0 \leq k < a} \triangleleft \mathcal{P}\}.$$

One shows:

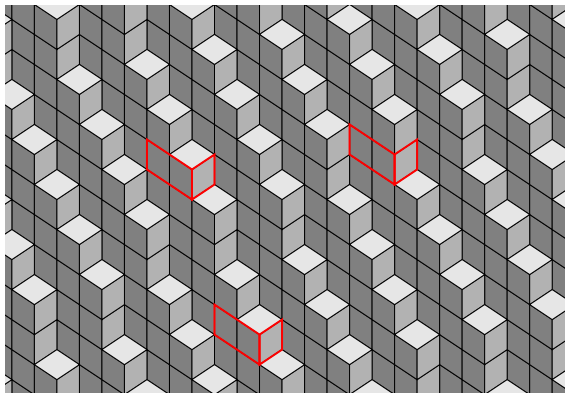
$$a_i(\mathcal{P}_{(1, \vec{\alpha})}) = \left\lfloor \frac{1}{\alpha_i} \right\rfloor.$$



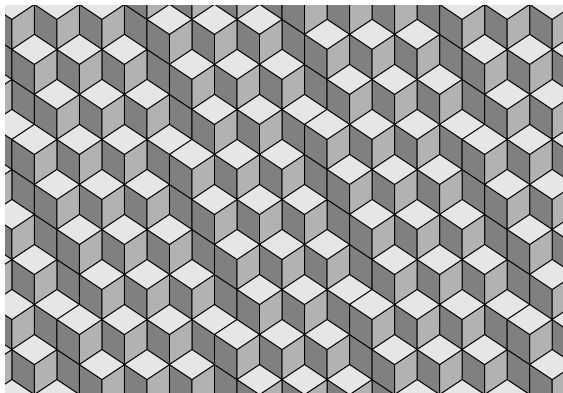
Stepped plane $\mathcal{P}_{(1, \vec{\alpha})}$, with unknown $\vec{\alpha} = (\alpha_1, \alpha_2) \in [0, 1]^2 \setminus \{0\}$.



$(\vec{0}, 2^*), (\vec{e}_3, 2^*) \triangleleft \mathcal{P}_{(1, \vec{\alpha})}$. Thus, $\alpha_1 > \alpha_2$.



$$(\vec{x}, 2^*) \triangleleft \mathcal{P}_{(1, \vec{\alpha})} \Rightarrow (\vec{x}, 1^*), (\vec{x} - \vec{e}_2, 1^*) \triangleleft \mathcal{P}_{(1, \vec{\alpha})}. \text{ Thus, } [1/\alpha_1] = 2.$$



$$\text{Finally: } \mathcal{P}_{(1, T(\vec{\alpha}))} = E_1^*(\beta_{2,1})(\mathcal{P}_{(1, \vec{\alpha})}).$$

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Dual maps and “information grabbing” defined for stepped surfaces

↪ natural extension of Brun expansions for stepped surfaces.

Dual maps and “information grabbing” defined for stepped surfaces

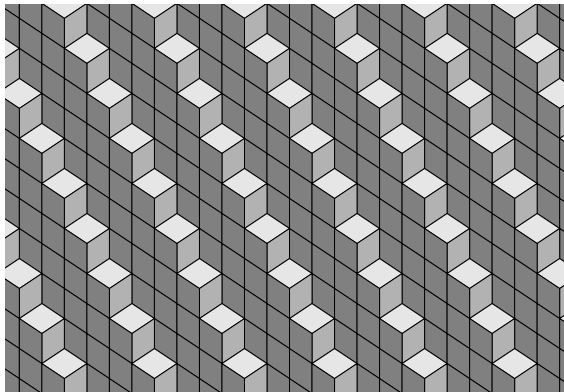
↪ natural extension of Brun expansions for stepped surfaces.

Theorem (B. F. 2007)

Stepped surfaces having the Brun expansion of $\vec{\alpha} \in \mathbb{R}_+^d \setminus \{0\}$ are:

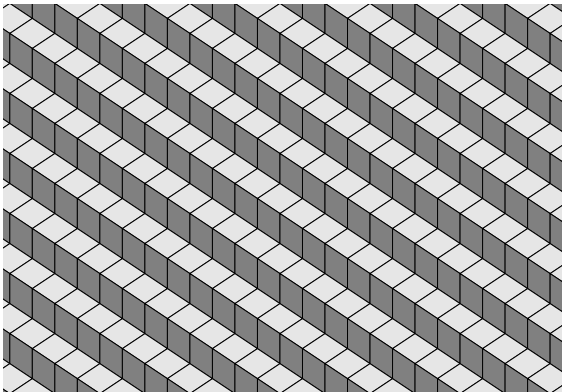
- *the stepped plane $\mathcal{P}_{(1, \vec{\alpha})}$ (finite or infinite expansion);*
- *some stepped surfaces almost equal to $\mathcal{P}_{(1, \vec{\alpha})}$ (idem);*
- *some non-plane stepped surfaces (only finite expansion).*

The stepped plane case (finite or infinite expansion)



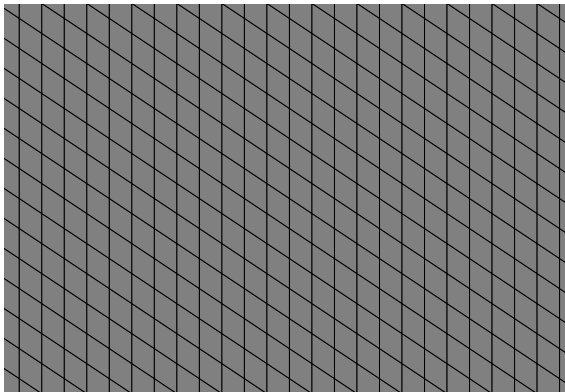
$$(a, i) = (4, 1)$$

The stepped plane case (finite or infinite expansion)



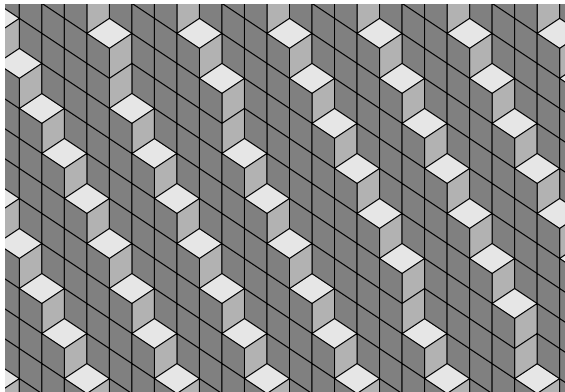
$$(a, i) = (1, 2)$$

The stepped plane case (finite or infinite expansion)



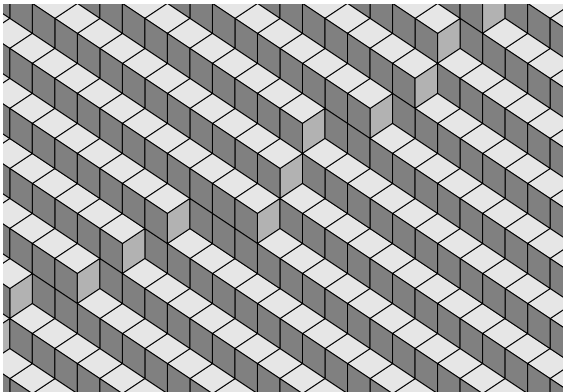
$a = \infty$. Stepped plane recognized.

The stepped quasi-plane case (finite or infinite expansion)



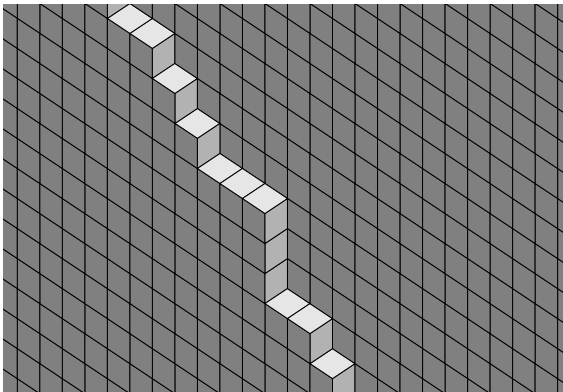
$$(a, i) = (4, 1)$$

The stepped quasi-plane case (finite or infinite expansion)



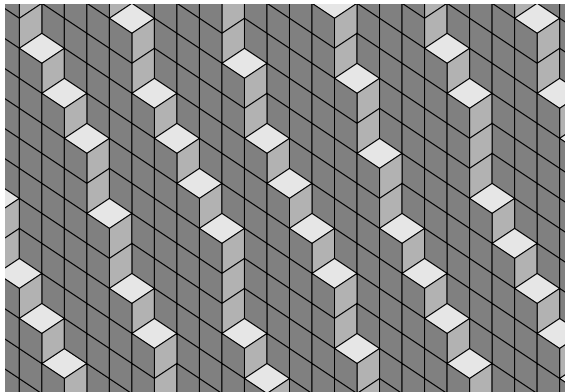
$$(a, i) = (1, 2)$$

The stepped quasi-plane case (finite or infinite expansion)



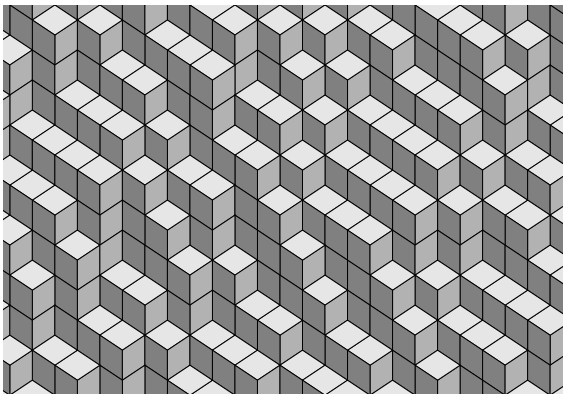
$a = \infty$. Not a stepped plane... but almost.

The stepped surface case (only finite expansion)



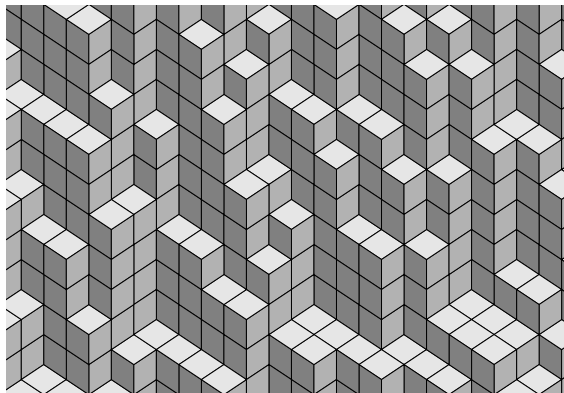
$$(a, i) = (4, 1)$$

The stepped surface case (only finite expansion)



$$(a, i) = (1, 2)$$

The stepped surface case (only finite expansion)



a undefined. Not at all a stepped plane.

Where is “digital plane recognition”?

Finite expansions \rightsquigarrow stepped planes recognized from the last obtained stepped surface.

Patches (finite subset of stepped surfaces) \rightsquigarrow finite expansions. . .