

# Computational Complexity and Logical Definability

or

« How logic can help  
to *discover efficient generic algorithms*  
or to *understand complexity classes* »

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# A natural question

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- What relationships exist between
  - **Algorithmic complexity**
    - How a problem PB is difficult to solve?
  - and
  - **Descriptive complexity**
    - How the problem PB is difficult to define?



# Two kinds of results

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- **Algorithmic meta theorems**
  - Or « generic algorithms of small complexity for solving a class of problems definable in some logic »
- **Logical characterizations of complexity classes**
  - Or « complexity class = logically definable class »



# The logics involved

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- First-order logic: **FO**
- Second-order logic: **SO**
  - And its restrictions
    - Existential second-order: **ESO**
    - Monadic second-order: **MSO**
    - Existential monadic second-order: **EMSO**



# Examples: First-Order Logic

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- The fact that a graph  $G = (V, E)$  satisfies the First-Order (FO) sentence

$$\exists x \exists y \exists z E(x, y) \wedge E(y, z) \wedge E(z, x)$$

means that

$G$  contains a triangle

- We say that the problem TRIANGLE is defined in First-Order logic and denote
  - $\text{TRIANGLE} \in \text{FO}$
- *Notice:* each problem defined in FO is computable in PTIME. Why?



# Examples: Second-Order Logic

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- The fact that a graph  $G = (V, E)$  satisfies the Second-Order (SO) sentence

$\forall U$

« Any set  $U$  of vertices »

$( [\exists x U(x) \wedge \forall x \forall y ((U(x) \wedge E(x, y)) \rightarrow U(y)) ]$

« that is nonempty and closed for neighbours »

$\rightarrow \forall x U(x) )$

« contains all the vertices of  $G$  »

means that  $G$  is connex

- We say that problem CONNEX is defined in SO (and MSO) logic, denoted  $\text{CONNEX} \in \text{SO}$  and  $\text{CONNEX} \in \text{MSO}$
- At the opposite:  $\text{CONNEX} \notin \text{FO}$



# More examples in SO

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- **Problem 3-COL**
  - *Input:* a graph  $G=(V,E)$
  - *Question:* Can  $G$  be coloured with 3 colours?
- Problem 3-COL is defined by the Existential Second-Order (ESO) sentence

$\exists C1 \exists C2 \exists C3$

$[ \forall x (C1(x) \vee C2(x) \vee C3(x)) \wedge \text{the } C_i\text{'s are pairwise disjoint}$

$\wedge \forall x \forall y \bigwedge_i (C_i(x) \wedge E(x,y)) \rightarrow \neg C_i(y) ]$

Therefore  $3\text{-COL} \in \text{ESO}$

and  $3\text{-COL} \in \text{EMSO}$  (Existential Monadic Second-Order)



# More examples in ESO

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- **Problem HAMILTON**
  - *Input:* a graph  $G=(V,E)$
  - *Question:* has  $G$  a Hamiltonian path?
- Problem HAMILTON is defined by the Existential Second-Order (ESO) sentence
  - **$\exists$  binary relation  $<$** 
    - [  $<$  is a linear order (of the vertices)
    - $\wedge (\forall x \forall y (y \text{ is the successor of } x \text{ for } <) \rightarrow E(x,y))$  ]
- Therefore **HAMILTON  $\in$  ESO**
- Notice: HAMILTON and 3-COL are NP-complete, hence are hard problems





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# Two kinds of results

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## Algorithmic meta theorems using logic

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- They are results of the form
  - « Each problem **definable** in a certain logic on a certain class of structures **is solved efficiently** » (Martin Grohe, 2007)

## Algorithmic meta theorems using logic

A preliminary example:

the TRIANGLE problem in a cubic graph

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- *Algorithm*

- *Input:* a cubic graph  $G=(V,E)$   
(each vertex of  $G$  has degree 3, i.e. 3 neighbours)
- For each vertex  $a$  of  $G$  do
  - For each neighbour  $b$  of  $a$  do
    - For each neighbour  $c$  of  $b$  except  $a$  do
      - If  $c$  is a neighbour of  $a$  then  
Output «  $G$  has a triangle »
- Output «  $G$  has no triangle ».

- *Complexity*

- The internal test is performed in constant time and is repeated  $6|V|$  times
- Hence, the whole algorithm runs in **linear time**



# An algorithmic meta theorem using logic

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- *Seese's Theorem (1996)*: Each graph problem definable in FO is solved in linear time on any class of graphs of bounded degree
- *Application*: the TRIANGLE problem is defined by an FO sentence
$$\exists x \exists y \exists z E(x,y) \wedge E(y,z) \wedge E(z,x)$$
and hence, is solved on a cubic graph  $G$  in time  $O(|G|)$



# Another algorithmic meta theorem using logic

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- *Courcelle's Theorem (1990)*: Each graph problem definable in MSO is solved in linear time on any class of graphs of bounded tree-width

- *An application*: the KERNEL problem in a directed graph  $G = (V, E)$ , defined by the MSO (even EMSO) sentence

$$\exists K [ \forall x \forall y ((K(x) \wedge K(y)) \rightarrow \neg E(x,y)) \\ \wedge \forall x (\neg K(x) \rightarrow \exists y (K(y) \wedge E(x,y))) ]$$

is solved in time  $O(|G|)$  if the graph  $G$  has tree-width bounded by some fixed  $k$ .

This is not trivial even for  $k = 1$  !



# Meta theorems using logic

## Why are they interesting ?

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- **They are general:** they allow to establish that some large class of problems are solved efficiently; typically, in linear time
- **They allow to establish that some specific problem is solved by an efficient algorithm** by defining it in some logic (FO, MSO, etc.)
  - *Examples:* Problems TRIANGLE in a cubic graph or KERNEL in a tree-like graph can both be solved in linear time by Seese's and Courcelle's Theorems, respectively



## Do the converse of meta theorems hold?

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- In general, No !
  - For example, there are graph problems solved in linear time in cubic graphs that are not definable in FO
  - Both converses of Seese's and Courcelle's Theorems fail !





# Are meta theorems optimal?

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Courcelle's Theorem is **optimal** in the following sense

*Theorem (Grohe, 1999):* Let  $C$  be a class of graphs (or, more generally, of structures).

The following three assertions are equivalent (under the assumption  $P \neq NP$ )

- $C$  is of **bounded tree-width**, i.e. there is some  $k$  such that the tree-width of each structure  $G$  of  $C$  is at most  $k$
- Each problem **definable in MSO** is solved in **linear time** on each structure of  $C$
- Each problem **definable in MSO** is solved in **polynomial time** on each structure of  $C$
- *Notice:* here, linear time is equivalent to polynomial time!



Can we exactly characterize a complexity class in logic ?

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Some results of the form

Complexity class = Logically definable class



## Existential Second-Order Logic is very expressive

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- ESO logic allows to define NP-complete problems such as HAMILTON by

**$\exists$  binary relation  $<$**

[  $<$  is a linear order (of the vertices)

$\wedge (\forall x \forall y (y \text{ is the successor of } x \text{ for } <) \rightarrow E(x,y)) ]$

- An ESO sentence is a formula of the form

**$\exists R_1 \dots \exists R_k \psi$**

where each  $R_i$  is a **relation variable** of fixed arity and  $\psi$  is an FO sentence



# ESO logic exactly characterizes NP

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*Fagin's Theorem (1974):* **NP = ESO**

That means:

A problem is NP  
*if and only if*  
it is definable in ESO



## Proof of $ESO \leq NP$

Let **PB** be a problem, e.g. a graph problem, defined by an ESO sentence  $\exists R_1 \dots \exists R_k \psi$

Here is a nondeterministic algorithm that decides whether a graph  $G = (V, E)$  belongs to **PB**, i.e. satisfies  $\exists R_1 \dots \exists R_k \psi$

*Algorithm*

- **Guess some relations**  $R_1, \dots, R_k$  (in time  $O(|V|^r)$  where  $r$  is the maximal arity of the  $R_i$ 's)
- **Check** whether the « expanded » structure  $(G, R_1, \dots, R_k)$  **satisfies the FO sentence**  $\psi$ : this is performed in **deterministic polynomial time**

So, this **nondeterministic algorithm** decides problem **PB** in **polynomial time**: hence, problem **PB** is **NP**



## Sketch of proof of the converse: $NP \leq ESO$

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- Let  $PB$  be an NP problem
- An input  $G$  belongs to  $PB$  *iff* it has an accepting computation  $C$  of polynomial time and then **of polynomial size**
- Such an accepting computation can be encoded by a list of relations  $R_1 \dots R_k$
- There is an **FO sentence**  $\psi$  that **exactly defines** the **correct accepting computations** of input  $G$
- In other words, the list of relations  $R_1 \dots R_k$  **encodes a correct accepting computation** of  $G$  *if and only if*  $(G, R_1 \dots R_k)$  **satisfies**  $\psi$
- In other words,  $G$  **has an accepting computation** *if and only if*  $G$  **satisfies the ESO sentence**  $\exists R_1 \dots \exists R_k \psi$
- That means  $PB$  **is defined by this ESO sentence**



# The central rôle of Second-Order logic

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- The SO logic and its restrictions
  - Existential Second-Order Logic (ESO)
  - Monadic Second-Order Logic (MSO)

play a key rôle in describing computations and complexity classes

Here are analogues of Fagin's Theorem for some classical complexity classes included in NP

*Theorem (Grädel, 1992)*

- **PTIME** = ESO(Horn-clauses) = SO(Horn-clauses)
- **NLOGSPACE** = ESO(2-clauses) = SO(2-clauses)

*Idea:* A deterministic computation is easily described by Horn clauses

Similarly, an NLOGSPACE computation is described by 2-clauses (clauses of 2 literals)



## A striking refinement of Fagin's Theorem

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Fagin's Theorem can be also refined for **precise nondeterministic time bounds**

- using the **RAM model of computation**
- and the **ESOF logic (Existential Second-Order logic with Functions)**, i.e. sentences of the form

$$\exists f_1 \dots \exists f_k \psi$$

- where the  $f_i$ 's are **function variables** (of any arity) instead of (or in complement of) relation variables
- and  $\psi$  is an FO sentence





## A striking refinement of Fagin's Theorem

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*Theorem (Grandjean, 1990, and Grandjean, Olive, 2004)*

- $\text{NLINTIME} = \text{ESOF}(1 \text{ var}) = \text{ESOF}(\forall^1) = \text{ESOF}(\forall^1, \text{arity } 1)$
- And more generally, for each integer  $d \geq 1$ ,  
 $\text{NTIME}(n^d) = \text{ESOF}(d \text{ var}) = \text{ESOF}(\forall^d) = \text{ESOF}(\forall^d, \text{arity } d)$

Here,  $\text{ESOF}(d \text{ var})$  denotes the class of ESOF sentences with at most  $d$  distinct first-order variables.  $\text{ESO}(\forall^d)$  and  $\text{ESOF}(\forall^d, \text{arity } d)$  are defined similarly.

In simplified words,

the **degree** of the nondeterministic polynomial time

**is exactly**

the **number of first-order variables**



## Why those results are interesting?

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- They yield straightforward (or almost straightforward) **completeness results in complexity** for natural problems, typically for problems in **propositional logic**:
  - Fagin's Theorem immediately implies Cook and Levin's Theorem
    - **SAT is NP-complete**
  - Grädel's Theorem immediately implies that
    - **HORN-SAT is PTIME-complete**
    - **2-SAT is NLOGSPACE-complete**

*Hint (for proving Cook's Theorem from Fagin's Theorem):*

- **Unfold** the FO subformula  $\psi$  of the ESO formula  $\exists R_1 \dots \exists R_k \psi$  as a conjunction over all the possible assignments of its (first-order) variables
- This gives a **propositional formula of polynomial size**



## Why those results are interesting?

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Even for **nondeterministic linear time (NLINTIME)**

The characterization

$$\text{NLINTIME} = \text{ESOF}(\forall^1, \text{arity } 1)$$

also implies by a (sophisticated) unfolding of the **unique first-order variable  $x$**  of any  $\text{ESOF}(\forall^1, \text{arity } 1)$  sentence

$$\exists f_1 \dots \exists f_k \forall x \psi \text{ (where } \psi \text{ is quantifier-free)}$$

that the classical problem

**RISA (Reduction of Incompletely Specified finite state Automata)**  
**is NLINTIME-complete**

*Remark:* Since the linear time complexity class  $\text{DTIME}(n)$  (for Turing machines) is *strictly included in* NLINTIME, this implies a complexity lower bound:

**RISA  $\notin$  DTIME( $n$ )**, i.e. RISA cannot be solved in linear time on any Turing machine



## Why those results are interesting? Robustness and machine independence

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- Those characterizations show how the complexity classes involved, **NP**, **P**TIME, **NLOGSPACE**, **NL**INTIME are **robust**,
  - not only from a computational point of view (they have many equivalent definitions)
  - but also from a logical point of view
- They are in fact **machine independent**:
  - **NP** is the set of problems definable in **ESO**
  - **NL**INTIME is the set of problems definable in **ESO** (with function variables) **using only 1 first-order variable**
- As their machine counterparts, the **logical classes involved are robust**, i.e. their ability to define problems does not change for a number of extensions and restrictions (normalizations), typically
$$\text{ESOF}(1 \text{ var}) = \text{ESOF}(\forall^1) = \text{ESOF}(\forall^1, \text{arity } 1)$$



# Conclusion

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We have presented two kinds of results that involve logic in algorithmics and complexity theory:

- **Algorithmic meta theorems**
  - Or « generic algorithms of small complexity for solving a class of problems definable in some logic »
- **Logical characterizations of complexity classes**
  - Or « complexity class = logically definable class »



## Conclusion: the state of art

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Our initial question: What relationships exist between

- Algorithmic complexity, and
- Descriptive complexity

**is still widely open !**

Typically, we have

- $ESO = NP$  and also  $SO = PH$  (the Polynomial Hierarchy beyond NP)
- but know no similar equality for the class FO (the class of problems defined in First-Order logic) or MSO