

Asymptotic Density of Properties in Cellular Automata

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Density of Properties in Cellular Automata

Cellular Automata

- Introduction

- Limit sets

- Simulations and universality

- Syntactically defined subfamilies

Density of properties

- Context

- Our framework

- Densities among CA

- Link with Kolmogorov complexity

- Densities among subclasses

- Perspectives

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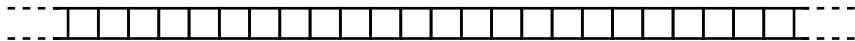
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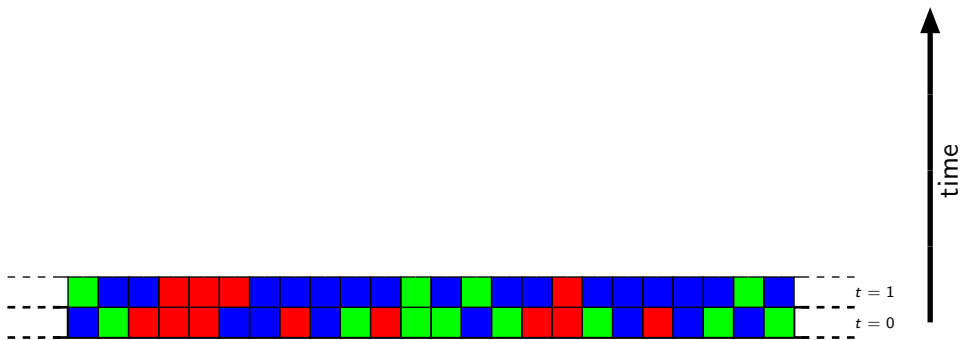
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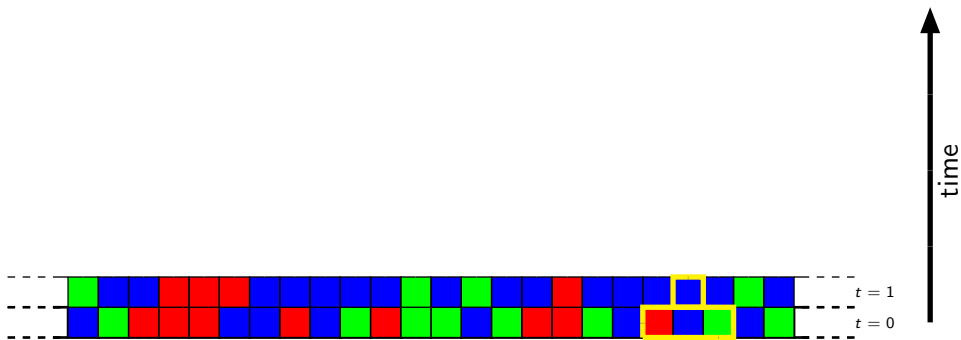
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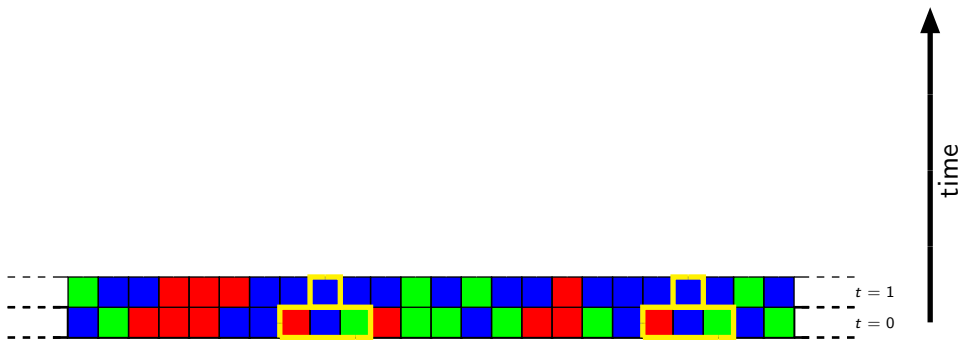
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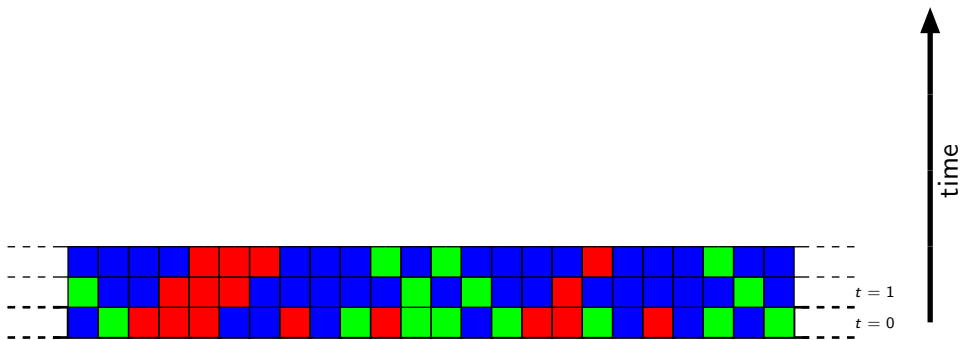
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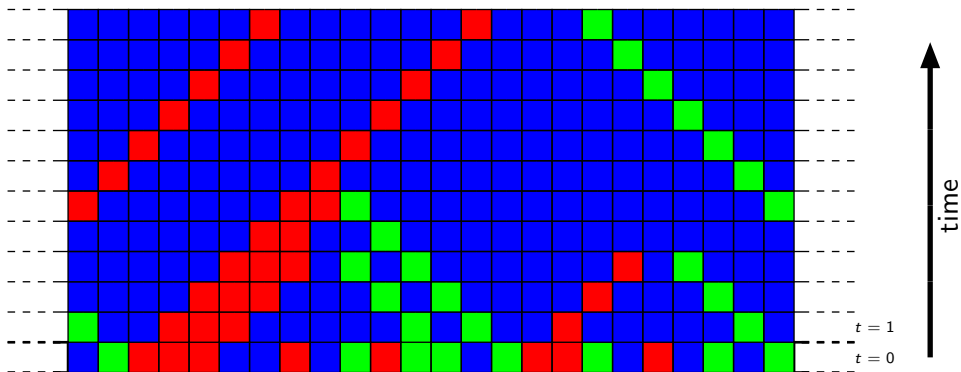
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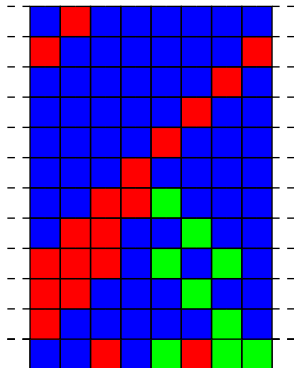
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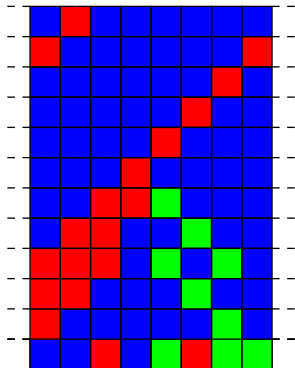


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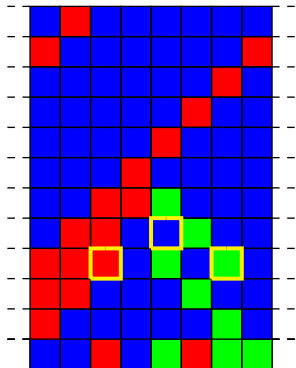
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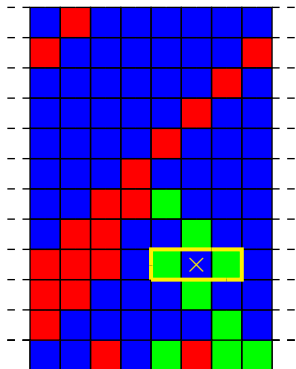
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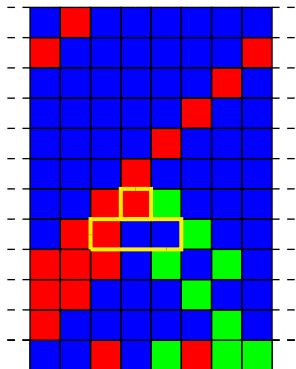


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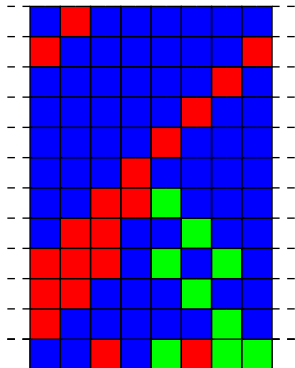
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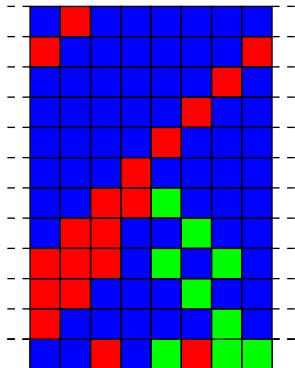
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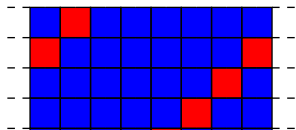
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**Simple (finite)
description** \leftrightarrow

**Complex
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Some examples (1/2)

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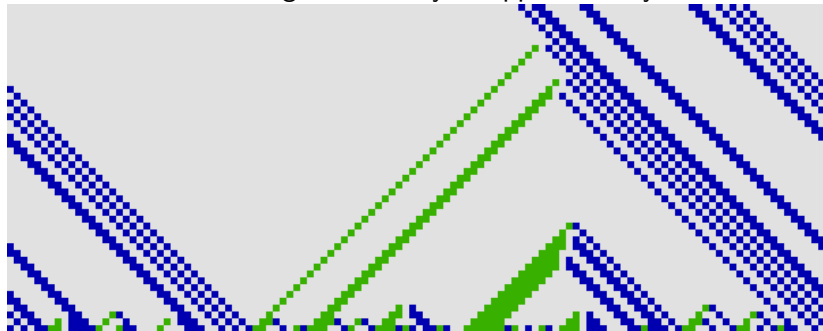


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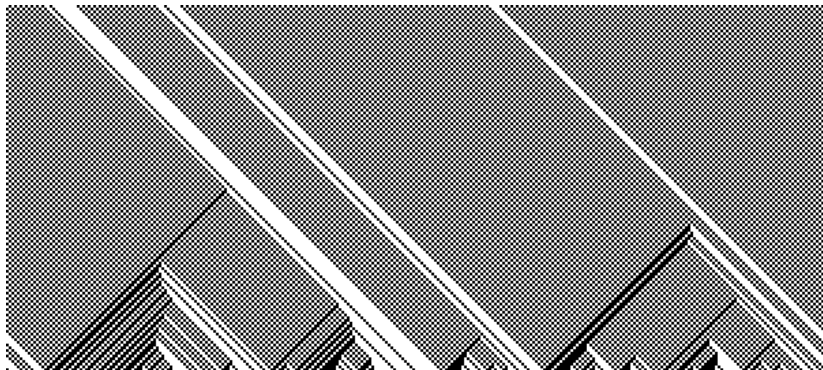


► JustGliders is $(\{L, \emptyset, R\}, \{-1, 0, 1\}, \delta_{JG})$ with δ_{JG} s.t. L moves left, R moves right, and they disappear if they collide :



Some examples (2/2)

► 184 is $(\{0, 1\}, \{-1, 0, 1\}, \delta_{184})$ with $\delta_{184} :$

$$\left\{ \begin{array}{l} 10? \mapsto 1 \\ ?10 \mapsto 0 \\ ?11 \mapsto 1 \\ 00? \mapsto 0 \end{array} \right.$$


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Definition (Limit set)

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Definition (Nilpotency)

$$\mathcal{A} \in \text{Nil} \iff \Omega_{\mathcal{A}} = \{c\}$$

"The CA always converges to this single configuration."

Intrinsic simulation (1/2)

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restriction of the local rule to a stable subset of Q

Example : in JustGliders: $\{L, \emptyset\}$ defines a sub-automaton, $\{L, R\}$ doesn't.

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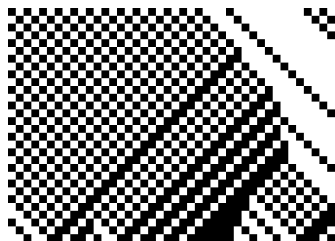
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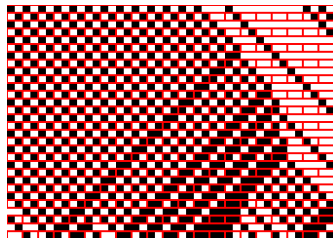
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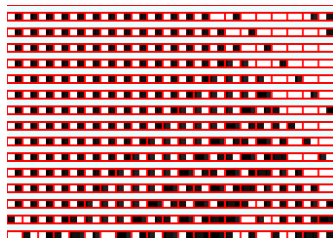
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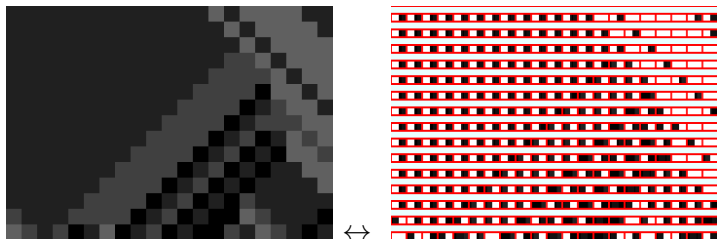
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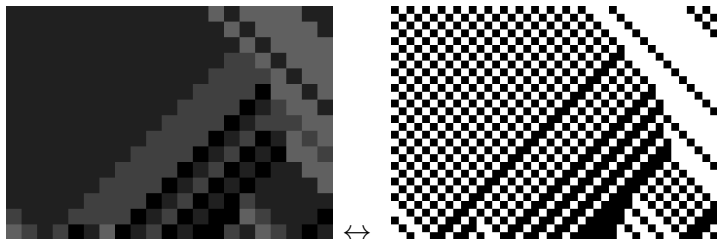
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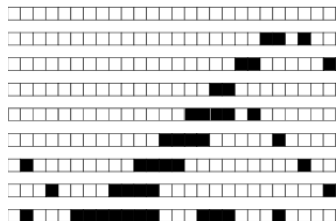
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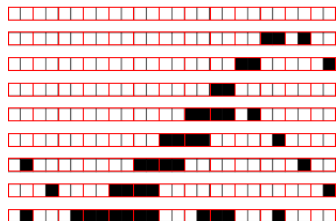


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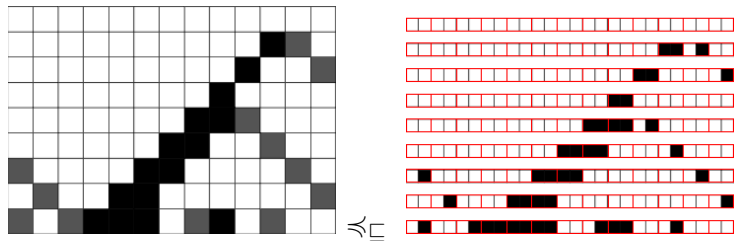


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Remarks :

- ▶ Central notion in CA litterature,
- ▶ Stronger than Turing universality in CA,
- ▶ Elements of **Univ** are maximal elements in the preorder induced by \preceq_{\sqsubseteq} .

Subfamilies of CA (example 1)

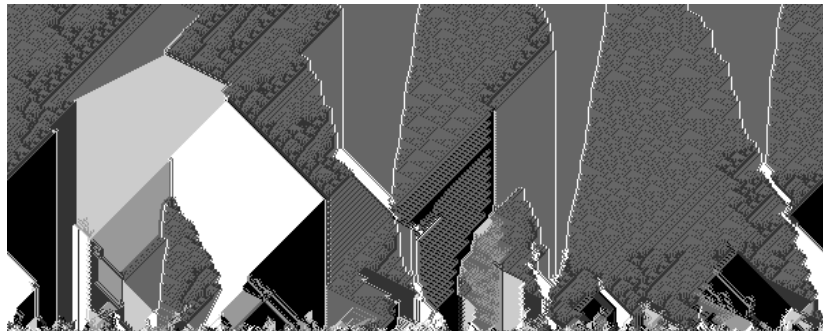
Subfamilies of CA (example 1)

► Captive CA

Definition (Captive CA)

$$\mathcal{A} \in \mathcal{K} \stackrel{\text{def}}{\iff} \forall x_1, x_2, \dots, x_k \in Q, \\ \delta_{\mathcal{A}}(x_1, x_2, \dots, x_k) \in \{x_1, x_2, \dots, x_k\}$$

- Introduced by G. Theyssier (2004),
- under some conditions most captive CA are universal (2005).



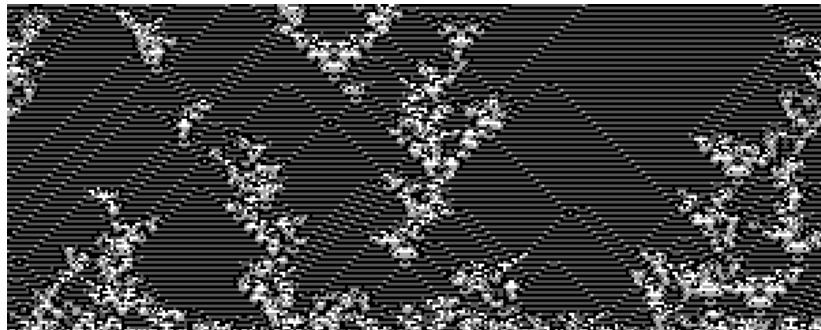
Subfamilies of CA (example 2)

► Multiset CA

Definition (Multiset CA)

$\mathcal{A} \in \mathcal{MS} \stackrel{\text{def}}{\iff}$ for all permutation $\pi : \{1, \dots, k\} \rightarrow \{1, \dots, k\}$,
 $\delta_{\mathcal{A}}(x_1, x_2, \dots, x_k) = \delta_{\mathcal{A}}(x_{\pi(1)}, x_{\pi(2)}, \dots, x_{\pi(k)})$

- Captures the idea of *isotropy*.
- Other interesting properties (*rescalings...*).



Cellular Automata

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Link with Kolmogorov complexity

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Perspectives

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- ▶ *Dubacq, Durand, Formenti – 2001*
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► **Our contribution :**

- ▶ a *unified framework* to study density among CA or subfamilies,
- ▶ various results.

Objects and properties

- ▶ **What objects ?**

Objects and properties

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We consider the set **CA** of triplets (Q_n, V_k, δ) for $n, k \in \mathbb{N}$, with

- $Q_n = \{0, 1, \dots, n-1\}$
- V_k *centered and connected* neighbourhood of size k
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► Which properties ?

Any subset $\mathcal{P} \subseteq \mathbf{CA}$.

Enumeration

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- and consider the proportions

$$D_{n,k}(\mathcal{C}, \mathcal{P}) \stackrel{\text{def}}{=} \frac{\#(\mathcal{C}_{n,k} \cap \mathcal{P})}{\#(\mathcal{C}_{n,k})}$$

$\mathcal{C}_{n,k}$ elements of size (n, k) of the family \mathcal{C} ,
 \mathcal{P} a property.

Paths among sizes

$D_{n,k}(\mathcal{C}, \mathcal{P})$ has no canonical limit,

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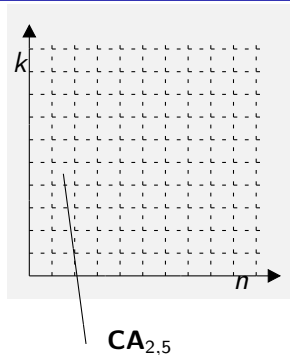
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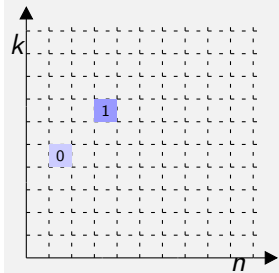
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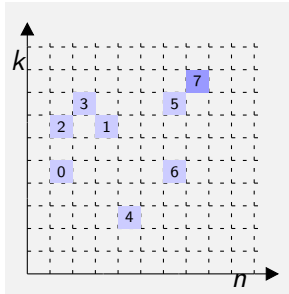
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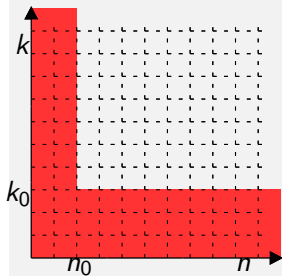
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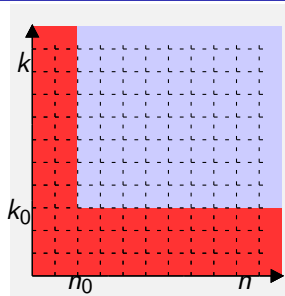
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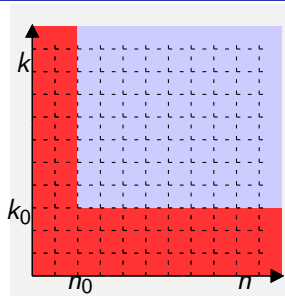
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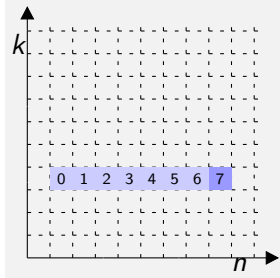
► **We may consider**

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► or particular paths

e.g. if $\rho_n = \pi_1 \circ \rho$ or $\rho_k = \pi_2 \circ \rho$ is upperbounded)

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Definition (Density of \mathcal{P} among \mathcal{C} following ρ :)

$$d_\rho(\mathcal{C}, \mathcal{P}) \stackrel{\text{def}}{=} \lim_{i \rightarrow \infty} \frac{\#(\mathcal{C}_{\rho(i)} \cap \mathcal{P})}{\#(\mathcal{C}_{\rho(i)})} \quad \text{if the limit exists.}$$

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Density is path-independent in the surjective case.

One example

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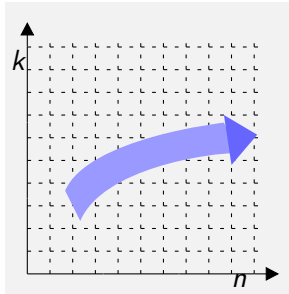
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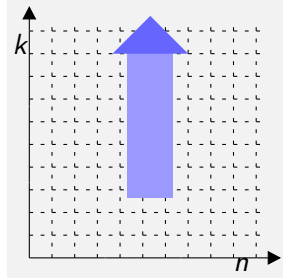


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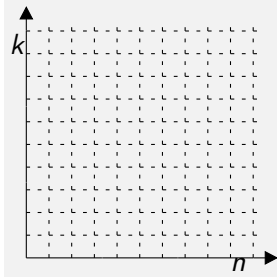
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Density of nilpotency

Theorem

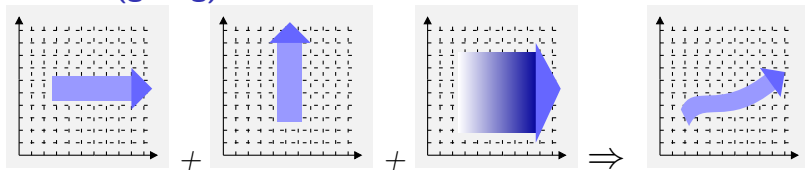
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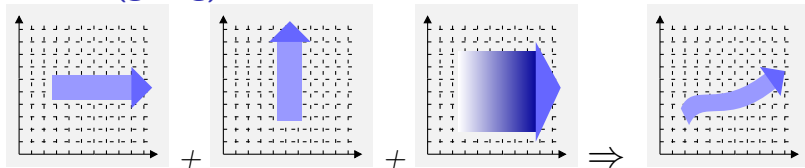


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+ specific combinatorial arguments for *each* case.

Intuitions (1/2): Fixed neighbourhood

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- ▶ Consider the *graph of uniform configurations* $(Q_n, G_{\mathcal{A}})$:
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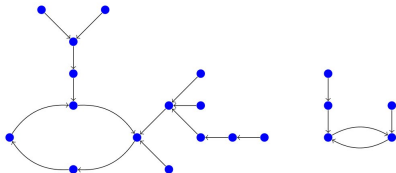
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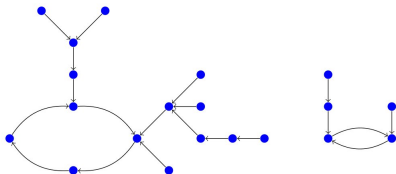
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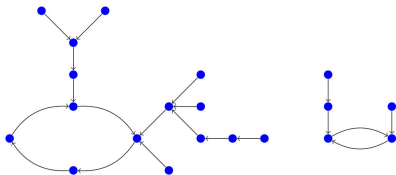
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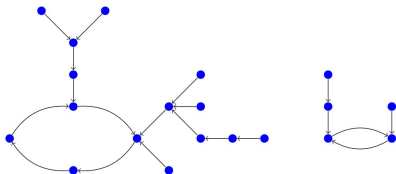


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- ▶ “trees are asymptotically negligible among functional graphs” ...

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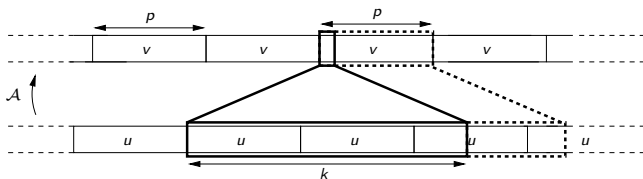
Periodic subshifts: $\forall u \in Q_n^, \Sigma_u \stackrel{\text{def}}{\iff} \omega_u \omega$*

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► $\mathcal{A} \in \mathbf{Nil} \implies \mathcal{A}(\Sigma_u) \not\subseteq \Sigma_u$



- Transitions $u^* \mapsto x$ are *constrained*,
- Combining those constraints makes it possible to conclude..

Link with Kolmogorov Complexity

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► Gives a procedure to prove negligibility:

"Describe shortly CA from \mathcal{P} ."

CA having a sub-automaton

Proposition

The set of CA having a non-trivial sub-automaton is negligible among any $(1, 3)$ -path.

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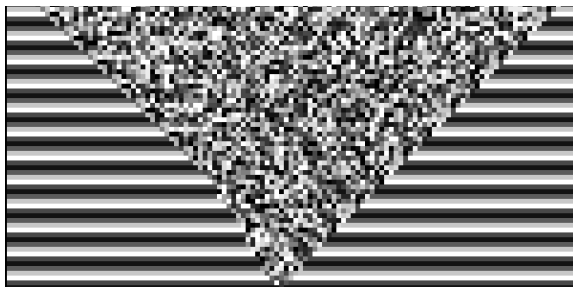
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- ▶ The gain tends to infinity (...).

Propagation of information

“Propagation of a state at maximal speed on a uniform background.”

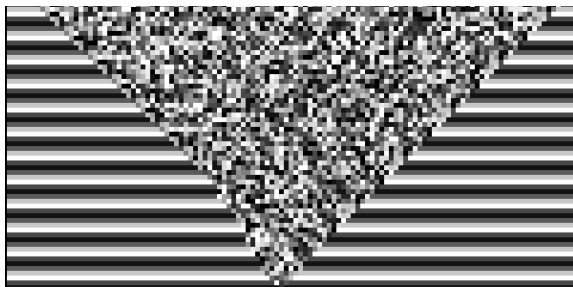
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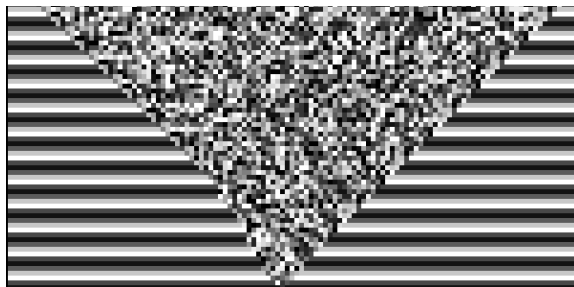
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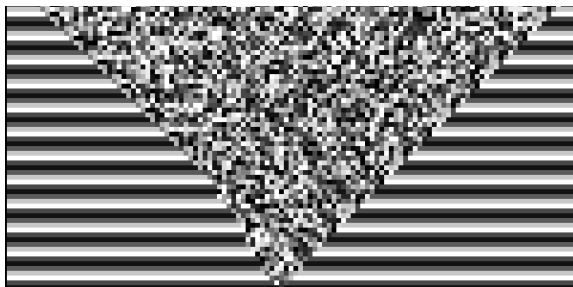
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- ▶ Mind the cycle of uniform configurations.

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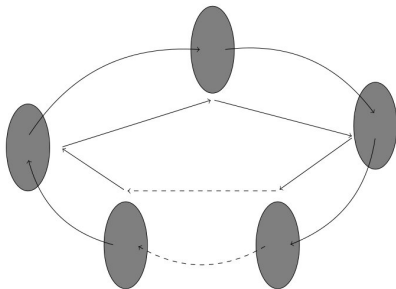
Let X be a cycle on the *graph of uniform configurations*.

Propagation of information

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► Consider the functional graphs $(Q_n \times X, G_A)$ such that:

► $((x, y), (z, t)) \in G_A \stackrel{\text{def}}{\iff} [\delta_A(x \cdot y^{k_A-1}) = z \text{ and } \delta_A(y^{k_A}) = t]$

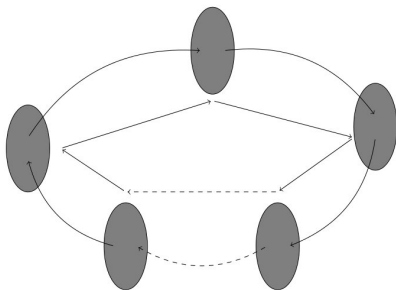


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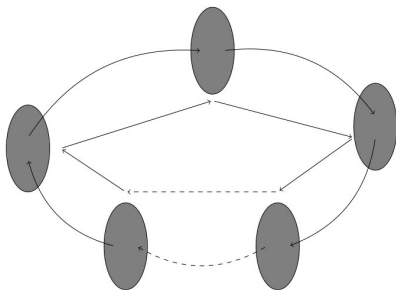
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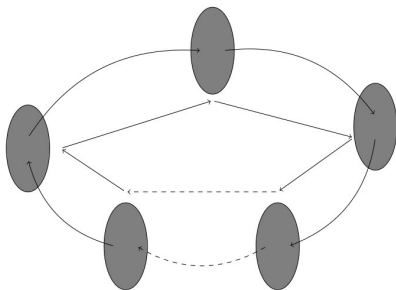
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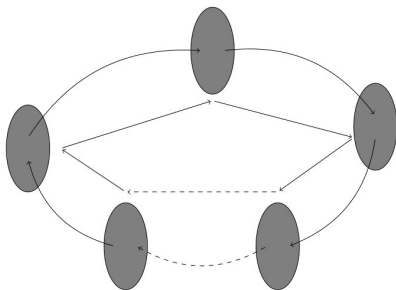
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► In *random functional graphs*, the number of cycles is increasing with the number of states.

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NB: *2 classes out of 4 from Kurka's classification are negligible.*

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Two necessary steps for each family :

- ▶ Point out a universal CA in \mathcal{C} ,
- ▶ Find possible simulation subshifts,
 - ▶ in increasing number along the considered paths,
 - ▶ on which the *simulating probability* is not too small,
 - ▶ which are *independents*.

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- ▶ Universality is not as *algorithmic* as we thought before.

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▶ In both cases, precise the information :

- ▶ *Convergence speed* of limit densities,
- ▶ Precise *finite proportions*.