

Space-efficiency and the Geometry of Interaction

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Project *Pro.Platz* at LMU Munich

[Hofmann, Johannsen, Schwichtenberg, S]

Programming language aspects of sublinear space complexity classes (L, Polylog-space, NL, ...)

Programming languages capturing logarithmic space

Find a convenient programming language capturing FL.

Existing work

- Function algebra (explicit resource bounds) [Lind 1974]
- Function algebra with unary numbers [Bellantoni 1992]
- Tail recursive readonly programs [Jones 1999]
- **Function algebra** BC_{ϵ}^{-} [Møller-Neergaard & Mairson 2004]

A model for space-efficient computation

We propose to use a version of the Geometry of Interaction as a flexible semantic universe for space-efficient computation.

This talk

1. Function algebra BC_{ε}^{-}
2. A version of the Geometry of Interaction
 - 2.1 Interpretation of BC_{ε}^{-}
 - 2.2 Extensions of BC_{ε}^{-}
3. Towards an intrinsic model capturing FL

The function algebra BC_{ε}^{-}

Origin

- BC [Bellantoni & Cook 1992]
- BC^{-} [Murawski & Ong 2000]
- $BC^{-} \subseteq FL$ [Ong & Mairson 2003]
- $BC_{\varepsilon}^{-} = FL$ [Møller-Neergaard 2004]

Definition

BC_{ε}^{-} is a set of functions on $\mathbb{N}_2 = \{0, 1\}^*$.

$$BC_{\varepsilon}^{-} \subseteq \{f: \mathbb{N}_2^m \times \mathbb{N}_2^n \rightarrow \mathbb{N}_2 \mid m, n \in \mathbb{N}\}$$

Notation: $f(\vec{x}; \vec{y})$

(*normal* arguments \vec{x} ; *safe* arguments \vec{y})

Functions in BC^-

Base functions

- $\varepsilon(\cdot; \cdot) = \varepsilon$
- $s_0(\cdot; y) = y_0$
- $s_1(\cdot; y) = y_1$
- $p(\cdot; yi) = y$ and $p(\cdot; \varepsilon) = \varepsilon$
- $c(\cdot; y, u, v) = \begin{cases} u & \text{if } y = y'1 \\ v & \text{otherwise} \end{cases}$
- $\pi_i(\vec{x}; \vec{y}) = x_i$ and $\pi_{m+i}(\vec{x}; \vec{y}) = y_i$

Composition

Safe arguments are treated *linearly*.

$$f(g_1(x; \cdot), g_2(x; \cdot); h_1(x; y_1), h_2(x; y_2, y_3))$$

Recursion

$f = \text{rec}(g, h_0, h_1)$ satisfies

$$f(\vec{x}, \varepsilon; \vec{y}) = g(\vec{x}; \vec{y})$$

$$f(\vec{x}, xi; \vec{y}) = h_i(\vec{x}, x; f(\vec{x}, x; \vec{y}))$$

Example:

$$\text{parity}(\varepsilon; \cdot) = s_1(\varepsilon)$$

$$\text{parity}(x0; \cdot) = \text{parity}(x; \cdot)$$

$$\text{parity}(x1; \cdot) = c(\cdot; \text{parity}(x; \cdot), s_0(\varepsilon), s_1(\varepsilon))$$

Non-example:

$$f(\vec{x}, \varepsilon; \vec{y}) = g(\vec{x}; \vec{y})$$

$$f(\vec{x}, xi; \vec{y}) = c(\cdot; f(\vec{x}, x; \vec{y}), p(f(\vec{x}, x; \vec{y})), h(\vec{x}, x; f(\vec{x}, x; \vec{y})))$$

Functions in BC_{ε}^{-}

BC_{ε}^{-} extends BC^{-} by course-of-value recursion.

$f = \text{rec}(g, h_0, h_1, d_0, d_1)$ satisfies

$$f(\vec{x}, \varepsilon; \vec{y}) = g(\vec{x}; \vec{y})$$

$$f(\vec{x}, xi; \vec{y}) = h_i(\vec{x}, x; f(\vec{x}, x \gg |d_i(\vec{x}, x; \cdot)|; \vec{y}))$$

Example:

$$u\log(\varepsilon; \cdot) = \varepsilon$$

$$u\log(xi; \cdot) = s_1(u\log(x \gg |u\text{half}(x)|; \cdot))$$

Evaluating BC_{ε}^{-} in FL

By example

$$\mathit{shift}(\varepsilon; y) = y$$

$$\mathit{shift}(xi; y) = p(\cdot; \mathit{shift}(x; y))$$

Naive call-by-value evaluation uses linear space.

FL-evaluation of BC_{ε}^{-} proceeds bit by bit.

Evaluating BC_{ε}^{-} in FL

$$\mathit{shift}(\varepsilon; y) = y$$

$$\mathit{shift}(xi; y) = p(\cdot; \mathit{shift}(x; y))$$

Bit(0)? — $\mathit{shift}(10; 1101)$

Evaluating BC_{ε}^{-} in FL

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Bit(2)? — $\mathit{shift}(\varepsilon; 1101)$

Evaluating BC_{ε}^{-} in FL

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Bit 2 of $\mathit{shift}(\varepsilon; 1101)$ is 1

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Bit 1 of $\mathit{shift}(1; 1101)$ is 1

Evaluating BC_{ε}^{-} in FL

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Evaluating BC_{ϵ}^{-} in FL

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Bit 1 of $\mathit{shift}(1; 1101)$ is 1

Bit(0)? — $\mathit{shift}(10; 1101)$

Bit 0 of $\mathit{shift}(10; 1101)$ is 1

Evaluating BC_{ϵ}^- in FL

- By linearity, recursion can be evaluated by storing only:
 - Initial question, current question
 - Recursion depth
 - Already computed bit and its depth
- All intermediate values and all questions are polynomially bounded.

$$|f(\vec{x}; \vec{y})| \leq p(|\vec{x}, \vec{y}|)$$
$$q \leq p'(q_0)$$

⇒ By iterating over the bits of the output, f can be computed in logarithmic space.

Modelling the evaluation of BC_{ε}^{-}

Question/answer dialogues \Rightarrow *Game Semantics*

Need only a special case \Rightarrow *Geometry of Interaction situation*

Geometry of Interaction

- Origin: syntax-free explanation of cut elimination for linear logic [Girard 1988]
- Connection to game semantics [Abramsky, Jagadeesan 92]
- General categorical formulation [Hyland], [Abramsky, Haghverdi, Scott 2000]
- Compilation of programming languages [Mackie 1995]
- Close connections to abstract machines, e.g. Krivine Abstract Machine [Danos, Herbelin, Regnier 1996]
- Used in complexity theory [Baillot], [Pedicini], [Dal Lago] ...

Geometry of Interaction

Objects

$$A = (A^-, A^+)$$

Example:

$$\mathbb{N}^- = \mathbb{N}$$

$$\mathbb{N}^+ = \{0, 1, *\}$$

Natural numbers are represented by functions $\mathbb{N}^- \rightarrow \mathbb{N}^+$.

Morphisms

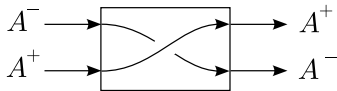
Morphism of type $f: A \rightarrow B$ is a partial function

$$f: B^- + A^+ \longrightarrow B^+ + A^-$$

Identity and Composition

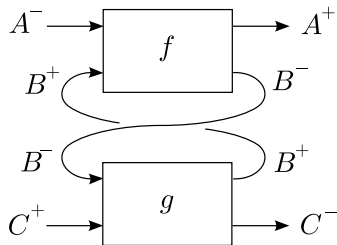
Identity

$$id: A \longrightarrow A$$



Composition

$$\frac{f: A \longrightarrow B}{g \cdot f: A \longrightarrow C}$$



Structure

- Pairs

$$A \otimes B = (A^- + B^-, A^+ + B^+)$$

- Functions

$$A \multimap B = (A^+ + B^-, A^- + B^+)$$

- Storage

$$!A = (A^- \times \mathbb{N}, A^+ \times \mathbb{N})$$

Interpreting BC_{ε}^{-}

$f(x_1, \dots, x_m; y_1, \dots, y_n)$ is interpreted as a morphism

$$\|f\|: !\mathbb{N}^m \otimes !\mathbb{N}^n \longrightarrow \mathbb{N}$$

Conditional

$\|c\|: !\mathbb{N} \otimes !\mathbb{N} \otimes !\mathbb{N} \longrightarrow \mathbb{N}$ is given by

$$\mathbb{N}^- + !\mathbb{N}^+ + !\mathbb{N}^+ + !\mathbb{N}^+ \longrightarrow \mathbb{N}^+ + !\mathbb{N}^- + !\mathbb{N}^- + !\mathbb{N}^-$$

$$in_1(q) \longmapsto in_2(0, q)$$

$$in_2(1, s) \longmapsto in_3(s, 0)$$

$$in_2(_, s) \longmapsto in_4(s, 0)$$

$$in_3(a, s) \longmapsto in_1(a)$$

$$in_4(a, s) \longmapsto in_1(a)$$

Interpreting BC_{ε}^{-}

Recursion combinator

$\text{rec}: !\mathbb{N} \otimes !(\mathbb{N} \multimap \mathbb{N}) \otimes !(\mathbb{N} \multimap \mathbb{N}) \otimes !\mathbb{N} \multimap \mathbb{N}$

$$\text{inl}(q) \mapsto \text{in}_x(0, \langle q, q, 0, -1, -1 \rangle)$$

$$\text{in}_x(*, s) \mapsto \text{in}_g(s.q, s)$$

$$\text{in}_x(i, s) \mapsto \text{in}_{h_i}(s.q, s)$$

$$\text{in}_g(a, s) \mapsto \begin{cases} \text{inr}(a) & \text{if } s_3 = 0 \\ \text{in}_x(q_0, \langle s_1, s_1, 0, s_3, a \rangle) & \text{otherwise} \end{cases}$$

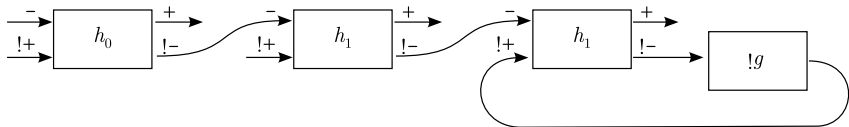
$$\text{in}_{h_i}(a, s) \mapsto \text{in}_g(a, s)$$

$$\text{in}_{r_i}((q, l), s) \mapsto \begin{cases} \text{in}_{r_i}((s_5, l), s) & \text{if } s_3 + 1 = s_4 \\ \text{in}_x(s_3 + 1, \langle s_1, q, s_3 + 1, s_4, s_5 \rangle) & \text{otherwise} \end{cases}$$

Interpreting BC_{ε}^{-}

Recursion combinator

rec: $!N \otimes (!N \multimap N) \otimes (!N \multimap N) \otimes !N \multimap N$



Interpreting BC_{ε}^{-} in Gol

$f(x_1, \dots, x_m; y_1, \dots, y_n)$ in BC_{ε}^{-} is interpreted as

$$\|f\|: !\mathbb{N}^{\otimes m} \otimes !\mathbb{N}^{\otimes n} \longrightarrow \mathbb{N}.$$

There exist $k \in \mathbb{N}$ and a polynomial p , such that:

1. If $\langle \vec{x}, \vec{y} \rangle \in \text{Space}(b(z))$ then

$$\|f\| \cdot !\langle \vec{x}, \vec{y} \rangle \in \text{Space}(k \cdot (z + \log |\vec{x}, \vec{y}|) + b(k \cdot (z + \log |\vec{x}, \vec{y}|)))$$

2. For all $\langle \vec{x}, \vec{y} \rangle$ and all initial questions q_0 , at most one question (q, s) may be sent to each safe argument y_i .

$$q \leq q_0 + p(|\vec{x}, \vec{y}|)$$

What do we gain from the interpretation?

Direct consequences for BC_{ε}^{-}

- Simple compilation of the language
- Function types
- **Recursively defined functions**
- General framework for modelling data types

More generally

- Gol captures the recomputation pattern often used in FL-computation
- **Gol-Realizability for FL**

Recursively defined functions

Example

Addition is naturally defined by recursion with result type $\mathbb{N} \rightarrow \mathbb{N} \rightarrow \mathbb{N}$.

$$add(\varepsilon) = \lambda y. \lambda c. \text{if } c \text{ then } inc(y) \text{ else } y$$

$$add(xi) = \lambda y. \lambda c. s_{(i+y_0+c_0) \bmod 2}(add(x) p(y) \lfloor (i + y_0 + c_0)/2 \rfloor))$$

Simplest case

$$g: \mathbb{N} \multimap \mathbb{N}$$

$$f = \text{rec}(g, h_0, h_1)$$

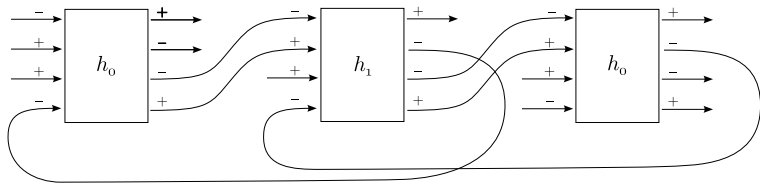
$$h_i: (\mathbb{N} \multimap \mathbb{N}) \multimap (\mathbb{N} \multimap \mathbb{N})$$

$$f \varepsilon = g$$

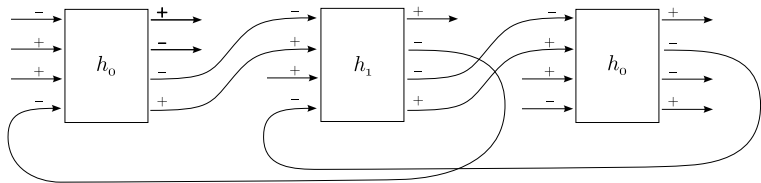
$$f: \mathbb{N} \rightarrow \mathbb{N} \multimap \mathbb{N}$$

$$f xi = h_i (f x)$$

Recursively defined functions



Recursively defined functions

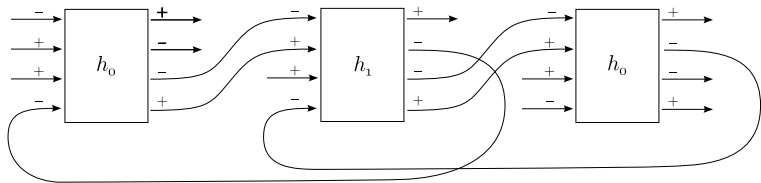


Exploit *linearity* of h_0 and h_1 [e.g. Hofmann 1997].

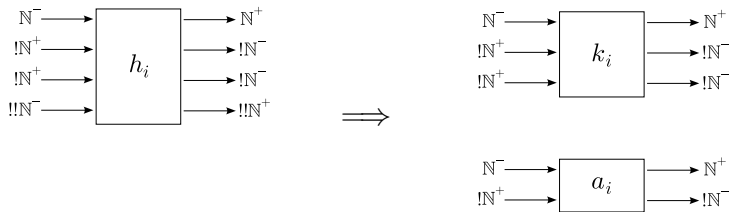
A linear function $h_i: (!\mathbb{N} \multimap \mathbb{N}) \multimap (!\mathbb{N} \multimap \mathbb{N})$ decomposes in $k_i: !\mathbb{N} \multimap !\mathbb{N} \multimap \mathbb{N}$ and $a_i: !\mathbb{N} \multimap \mathbb{N}$.

$$(h_i f) n = k_i n (f (a_i n))$$

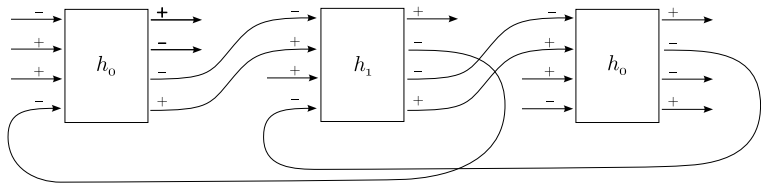
Recursively defined functions



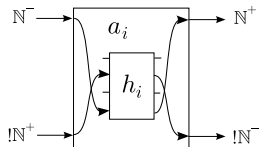
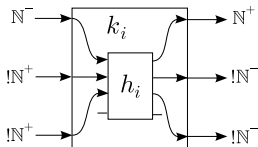
A linear function $h_i: !(N \multimap N) \multimap !(N \multimap N)$ decomposes in $k_i: !N \multimap !N \multimap N$ and $a_i: !N \multimap N$.



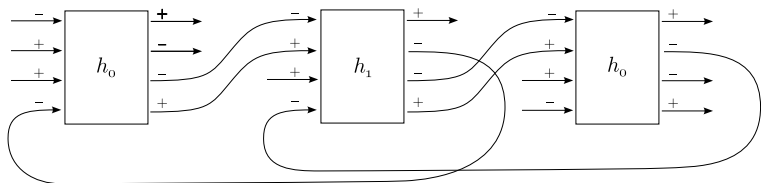
Recursively defined functions



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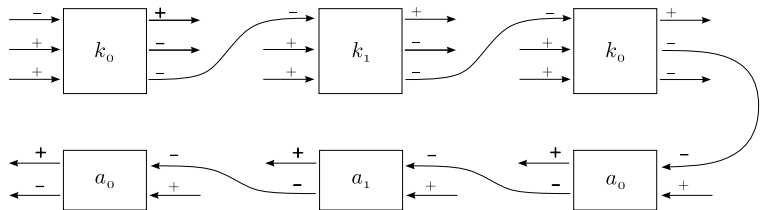


Recursively defined functions



A linear function $h_i: !(\mathbb{N} \multimap \mathbb{N}) \multimap (\mathbb{N} \multimap \mathbb{N})$ decomposes in $k_i: ! \mathbb{N} \multimap ! \mathbb{N} \multimap \mathbb{N}$ and $a_i: ! \mathbb{N} \multimap \mathbb{N}$.

\Rightarrow Recursion decomposes in two nested recursions on \mathbb{N}



Recursively defined functions — Example

Write

$$f(\varepsilon) = \lambda y. \varepsilon$$
$$f(xi) = \lambda y. \text{ if } y \text{ then } s_i(f(x) 0) \text{ else } (f(x) 1)$$

as $f(x) = \lambda y. f'(x, \varepsilon; y)$.

$$a_i(\varepsilon; y) = y$$
$$a_i(x_r i; y) = \text{ if } a_i(x_r; y) \text{ then } 0 \text{ else } 1$$

$$f'_i(\varepsilon, x_r; y) = \varepsilon$$
$$f'_i(xi, x_r; y) = \text{ if } a_i(x_r; y) \text{ then } s_i(f(x, ix_r; y)) \text{ else } (f(x, ix_r; y))$$

Towards an intrinsic model for FL

Instead of establishing resource bounds afterwards,
we want a model that captures FL intrinsically.

Size-restricted Geometry of Interaction

Restrict to morphisms $f: B^- + A^+ \longrightarrow B^+ + A^-$ that are

- non-size-increasing and
- computable in linear space.

Realizability

Restrict to functions that are realised by size-restricted
Gol-morphisms.

Realizability

Objects

Set $|A|$, size-restricted Gol object $\|A\|$, realizability relation \Vdash_A

$$\langle i, l, k \rangle, e \Vdash_A a \quad \begin{cases} a \in |A| \\ e: \|A\|^- \rightarrow \|A\|^+ \\ i, l, k \in \mathbb{N} \end{cases}$$

Example: Natural numbers

$$|\mathbb{N}| = \mathbb{N} \quad \|\mathbb{N}\| = (\mathbf{L}(\mathbf{B}) \otimes \mathbf{L}(\diamond), \{*, 0, 1\} \otimes \mathbf{L}(\diamond))$$

$\langle i, l, k \rangle, e \Vdash n$ iff

- $l \geq |n|$
- On question $\langle b, \diamond^{k \cdot \log l} \rangle$, the function e returns Bit b of n and gives back the memory

Realizability

Morphisms

Morphism $f: A \rightarrow B$ is a function $f: |A| \rightarrow |B|$, for which there exist $r: !\|A\| \rightarrow \|B\|$ and φ , such that

$$\alpha, e \Vdash x \implies \alpha + \varphi, r \cdot !e \Vdash f(x)$$

holds.

(plus a condition restricting the use of the !-modality)

Proposition. The underlying function of every morphism $f: \mathbb{N} \rightarrow \mathbb{N}$ is FL-computable.

Realizability — Work in progress

Structure and constructions

- Monoidal closure: \otimes, \multimap
- Question-linearity and modality \Box
- Interpretation of BC_{ε}^{-}

Programming language for FL on this basis

- Resource type \diamond for size-control
- Modality \Box to control question-linearity