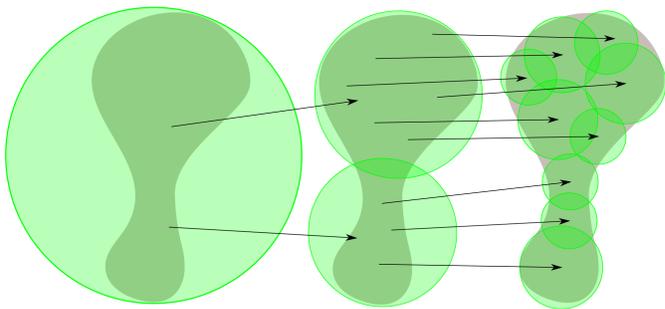


## I. General Problem

**Hierarchical representations** provide a way to describe geometric shapes by a set of simple primitives at different scales. They are useful for collision detection [5]. To obtain a hierarchical representation from an input shape, different methods already exist [1, 7]. However these methods only consider the geometric error of the output and do not take into account topological aspects. Our aim is to define and compute a hierarchical representation with both **geometric** and **topological guarantees**.



## II. Shape approximation at a given scale by union of balls

In order to generate a hierarchical representation, the shape first has to be approximated by the chosen primitives. For this, we formalize the problem with notions derived from mathematical morphology.

Let  $S$  be an open bounded set in an Euclidean space  $\mathbb{E}$  and  $\varepsilon > 0$ . The erosion and dilation of  $S$  by parameter  $\varepsilon$  are respectively

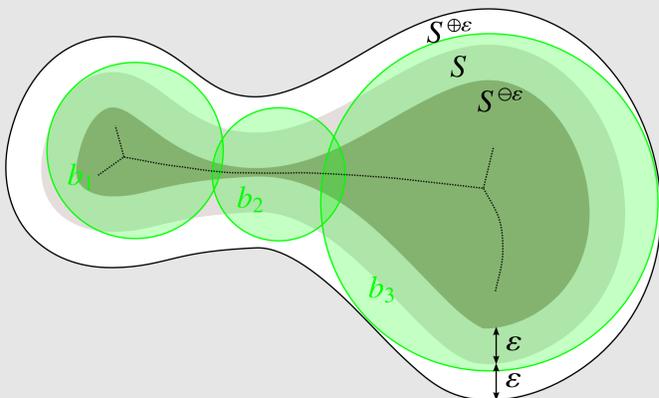
$$S^{\ominus\varepsilon} = \{e \in \mathbb{E} \mid b(e, \varepsilon) \subseteq S\}$$

and

$$S^{\oplus\varepsilon} = \{e \in \mathbb{E} \mid \exists s \in S, e \in b(s, \varepsilon)\} = \bigcup_{s \in S} b(s, \varepsilon)$$

where  $b(e, r)$  denotes the open ball of center  $e$  and radius  $r$ .

Let  $\mathcal{B}$  be a collection of balls of  $\mathbb{E}$ . We say that  $\mathcal{B}$  is an  $\varepsilon$ -covering of  $S$  iff  $S^{\ominus\varepsilon} \subseteq \bigcup \mathcal{B} \subseteq S^{\oplus\varepsilon}$ , where  $\bigcup \mathcal{B} = \bigcup_{b \in \mathcal{B}} b$ .



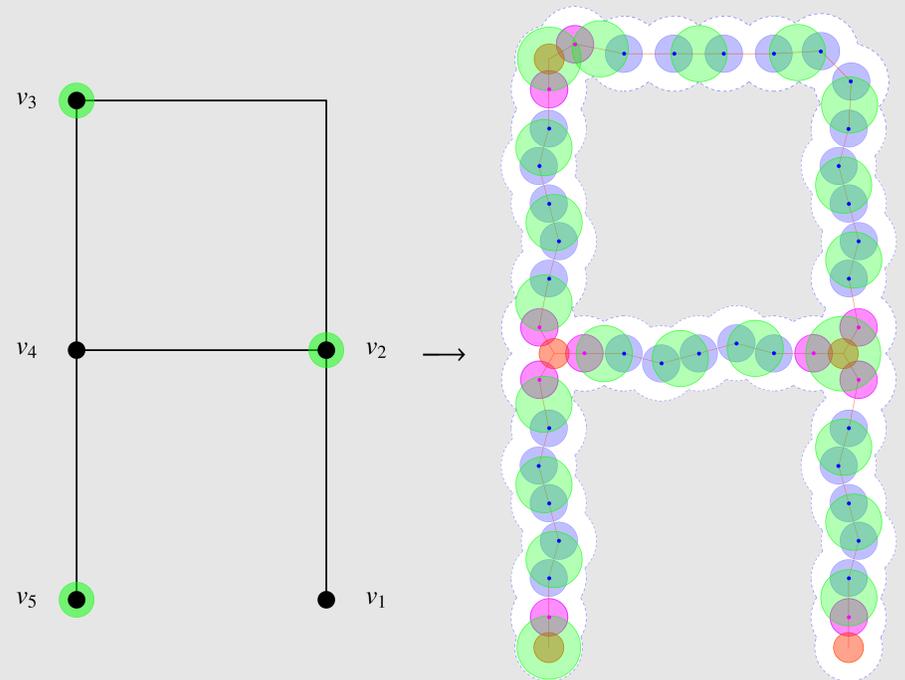
The collection  $\{b_1, b_2, b_3\}$  is an  $\varepsilon$ -covering of  $S$ .

For  $\varepsilon$  sufficiently small,  $\varepsilon$ -coverings have good geometric and topological properties. Specifically, there is a universal constant  $C$  such that if  $\varepsilon < C \times \text{reach}(S)$ , then the **Hausdorff distance** between  $S$  and  $\bigcup \mathcal{B}$  satisfies  $d_H(S, \bigcup \mathcal{B}) < \varepsilon$ , and  $\bigcup \mathcal{B}$  has the same **homotopy type** as  $S$ . We want to approximate  $S$  with  $\varepsilon$ -coverings.

## III. $\varepsilon$ -covering is NP-complete

If the set  $S$  is bounded, then it admits an  $\varepsilon$ -covering  $\mathcal{B}$  of finite cardinal, i.e.  $|\mathcal{B}| < +\infty$ . In particular we are interested in **optimal**  $\varepsilon$ -coverings that achieve minimum cardinality.

When input shapes are restricted to finite unions of balls, computing an optimal  $\varepsilon$ -covering is an **NP-complete** problem. The NP property can be verified using arrangements of circles [4, 2]. The hardness property can be proved by reduction from the vertex cover problem.



Conversion of a graph into an adequate input shape

## IV. Future works

- Develop an approximation algorithm to find good  $\varepsilon$ -coverings [3].
- Provide guarantees on the cardinal of the output with respect to the optimal.
- Generate a hierarchical representation from approximations at different scales.

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