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ParetoLib: A Python Library for Parameter Synthesis

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CONTEXT

Context



CYBER-PHYSICAL SYSTEMS

■ Cyber-Physical Systems:

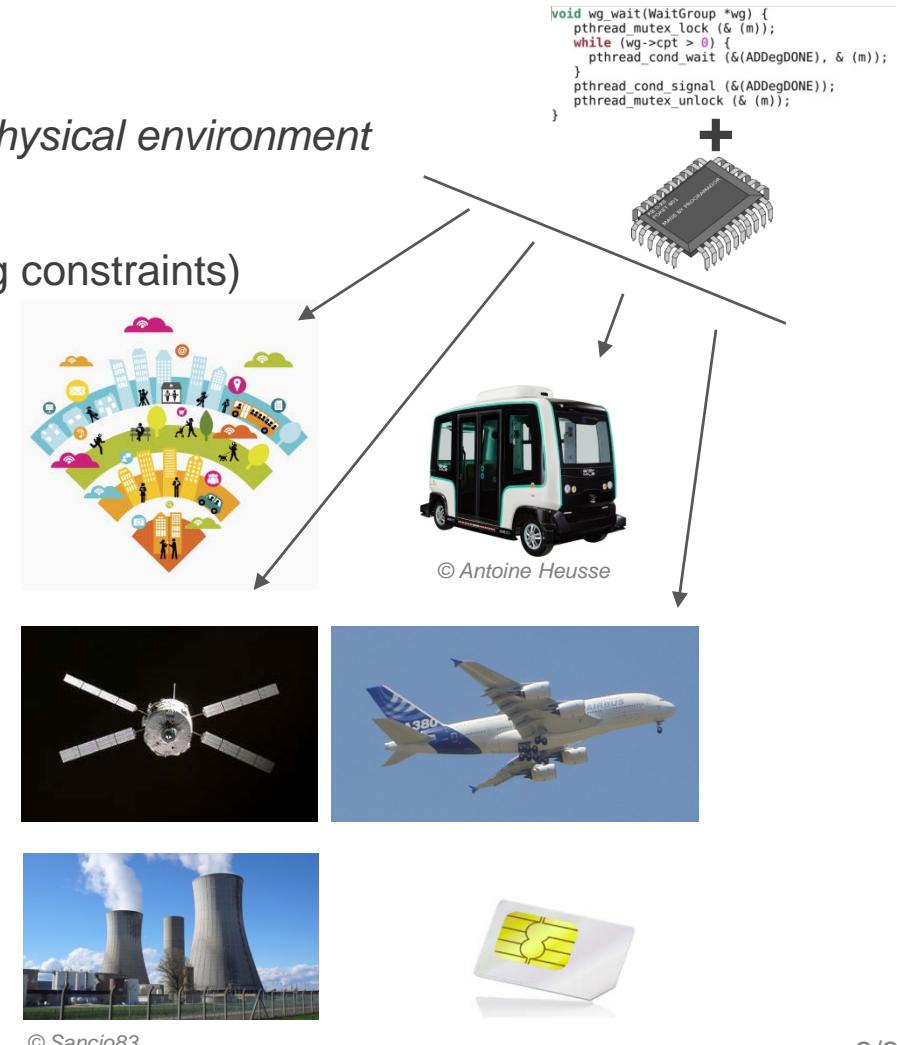
- ▶ hardware/software interacting with the physical environment
- ▶ computerized control systems
- ▶ uncertain / changing environment (timing constraints)
- ▶ large scale, distributed / networked

■ Criticality:

- ▶ safety (absence of errors)
- ▶ security (resistance to attacks)
- ▶ certification

■ Validation & Verification:

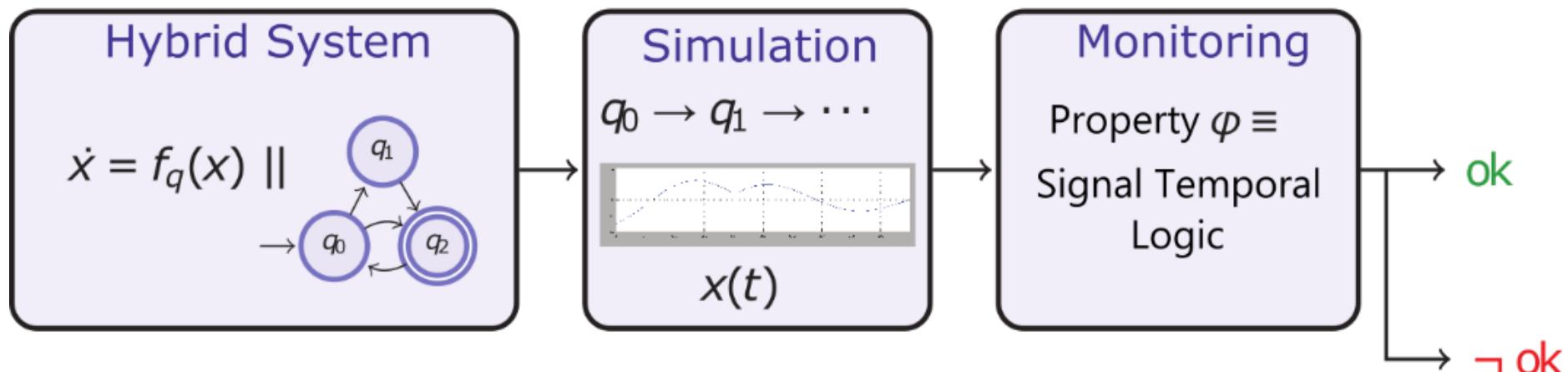
- ▶ hybrid: discrete + real-time systems





MONITORING

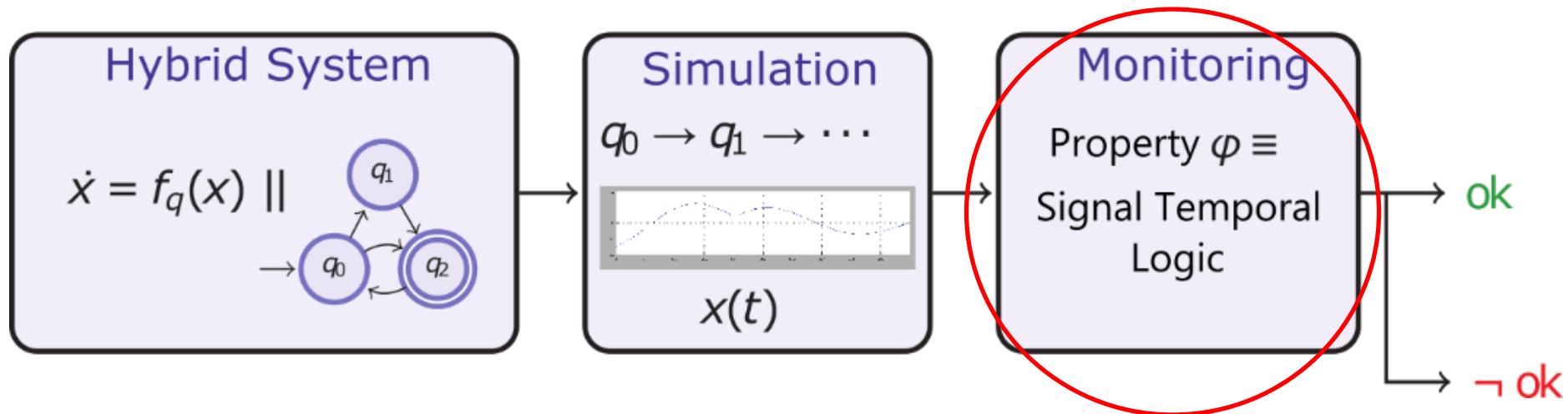
- Models are generally hybrid systems producing hybrid **traces**
- Runtime verification (aka monitoring) analyses a **single** behavior at a time





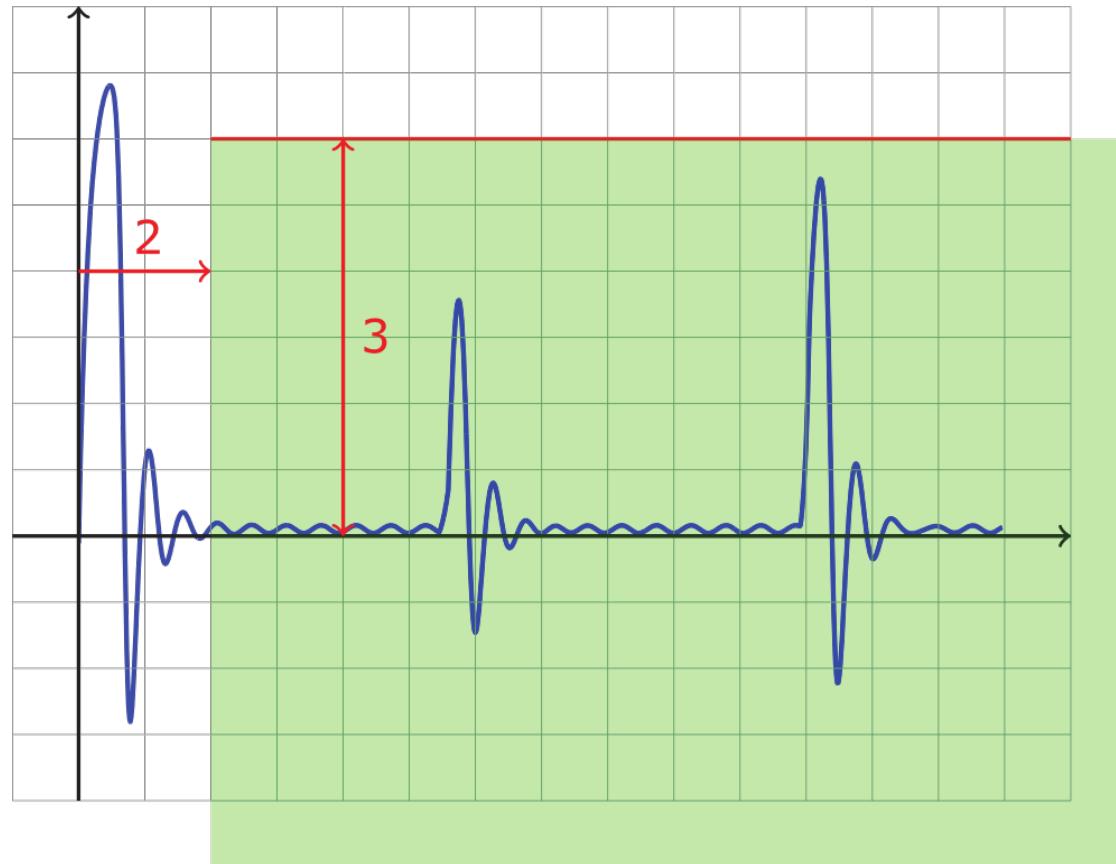
MONITORING

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- Runtime verification (aka monitoring) analyses a **single** behavior at a time



MOTIVATION

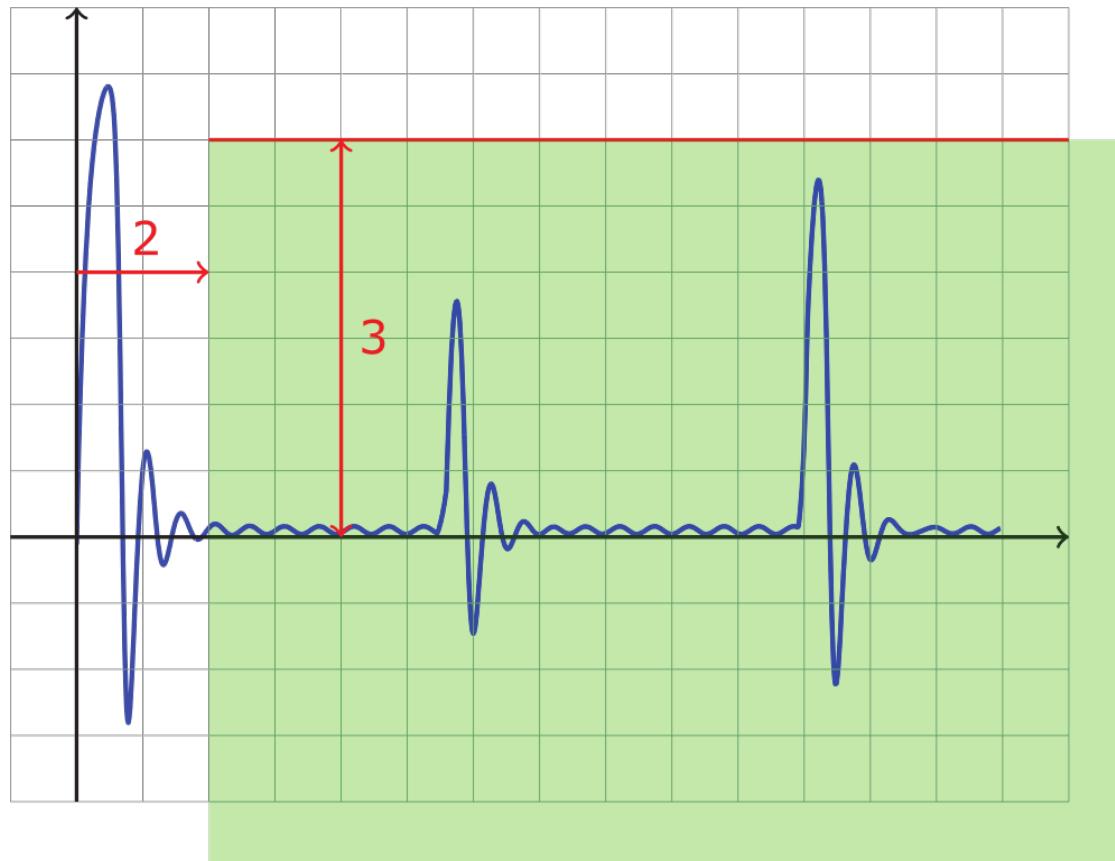
After 2s, the signal is never above 3



STL EXAMPLE

After 2s, the signal is never above 3

$$\varphi := \mathsf{F}_{[2,\infty]} (x[t] < 3)$$





PROBLEM

Parameter Synthesis



PARAMETER SYNTHESIS

Given a Parametric STL formula

$$\varphi(p_1, \dots, p_n)$$

identify the valuations $v(p_i)$ such that

$$x \models \varphi(v(p_1), \dots, v(p_n))$$

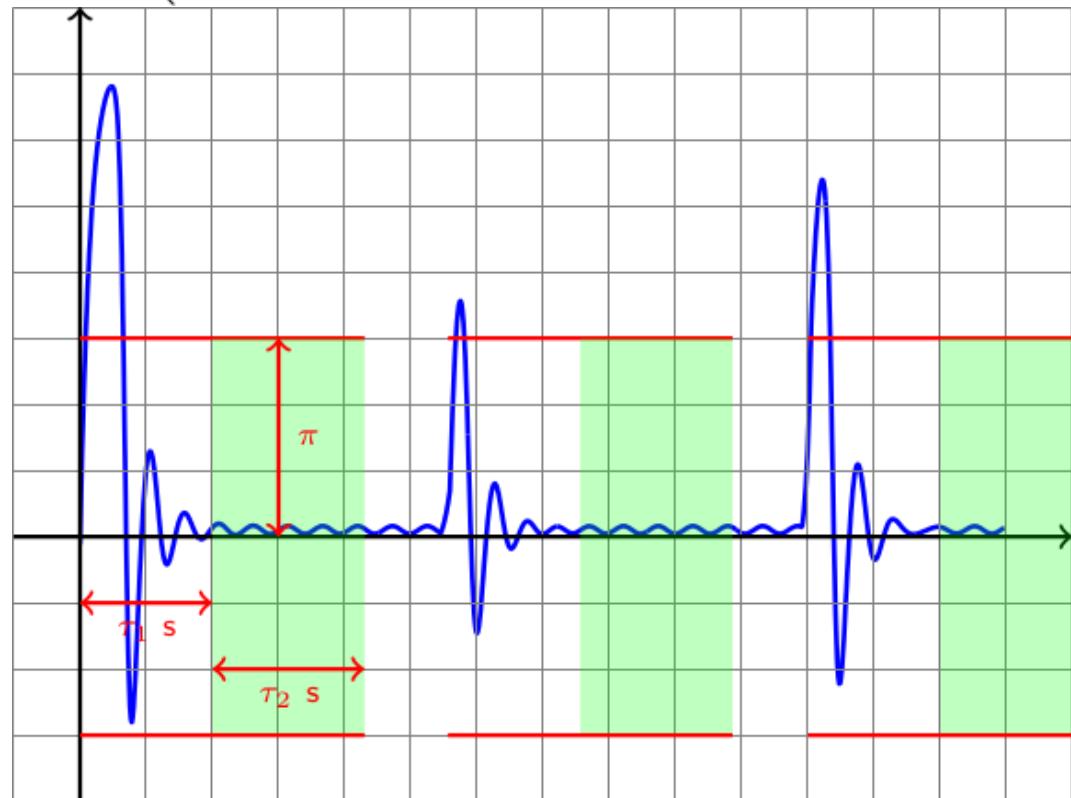
for each parameter p_i



SIGNAL STABILIZATION

Always $|x| > \underline{\quad}$ then after $\underline{\quad}$ s, $|x|$ settles under $\underline{\quad}$ for $\underline{\quad}$ s

$$\varphi := G(x[t] > \pi \rightarrow F_{[0, \tau_1]} (G_{[0, \tau_2]} x[t] < \pi))$$

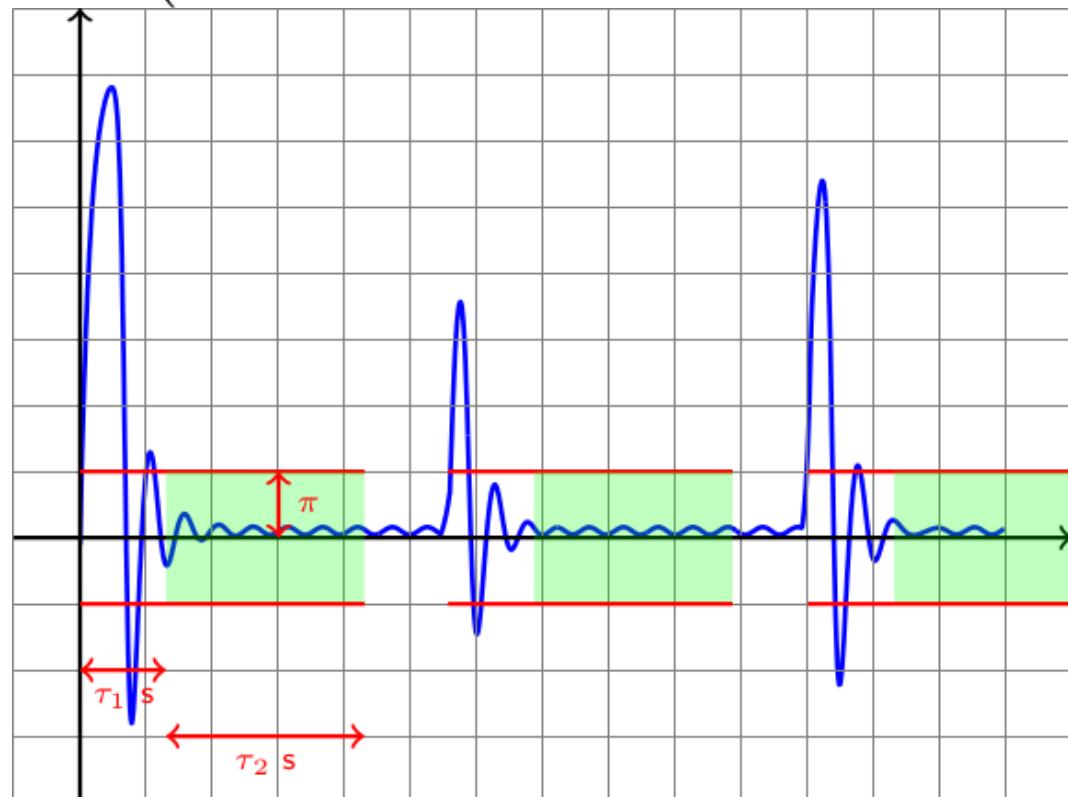




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PARAMETER SYNTHESIS

■ Challenges

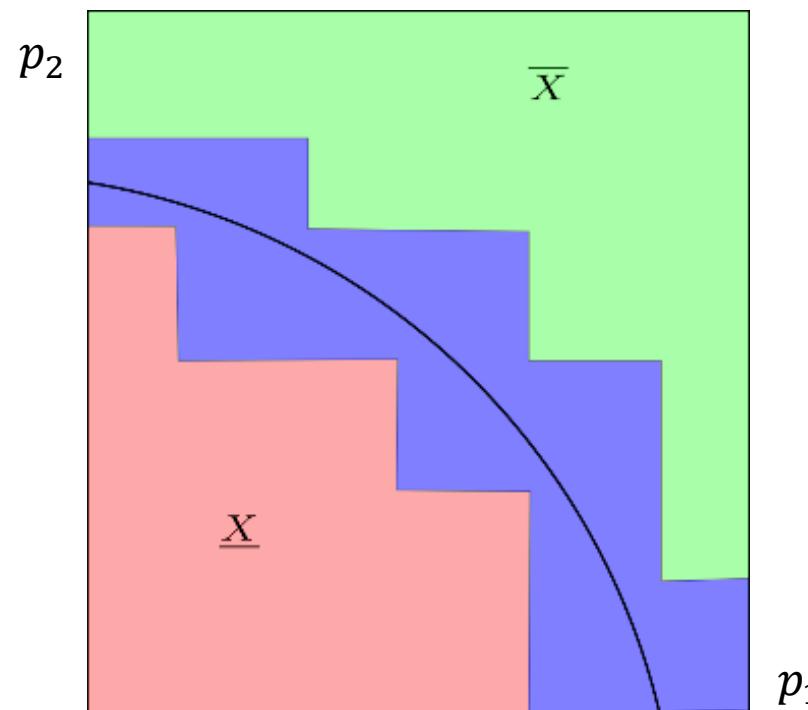
- ▶ Multiple solutions: which one to chose?
- ▶ Tightness implies to “optimize” the valuation $v(p_i)$ for each parameter p_i

■ The multi-criteria optimization problem can be greatly simplified if the formula is monotonic in each p_i

- ▶ In case of monotonicity, the border of the validity domain has the structure of a Pareto front

VALIDITY DOMAINS

- ▶ The validity domain X of formula φ and signal x is the set of valuations $v(p_i)$ such that $x \models \varphi(v(p_1), \dots, v(p_n))$ for each parameter p_i
- ▶ In case of monotonicity, the border of the validity domain has the structure of a **Pareto front**



SIGNAL STABILIZATION

Always $|x| > 0.5$ then after 1s, $|x|$ settles under 0.5 for 1.5 s

$$\varphi := G(x[t] > .5 \rightarrow F_{[0,.6]} (G_{[0,1.5]} x[t] < 0.5))$$





PARETOLIB

ParetoLib



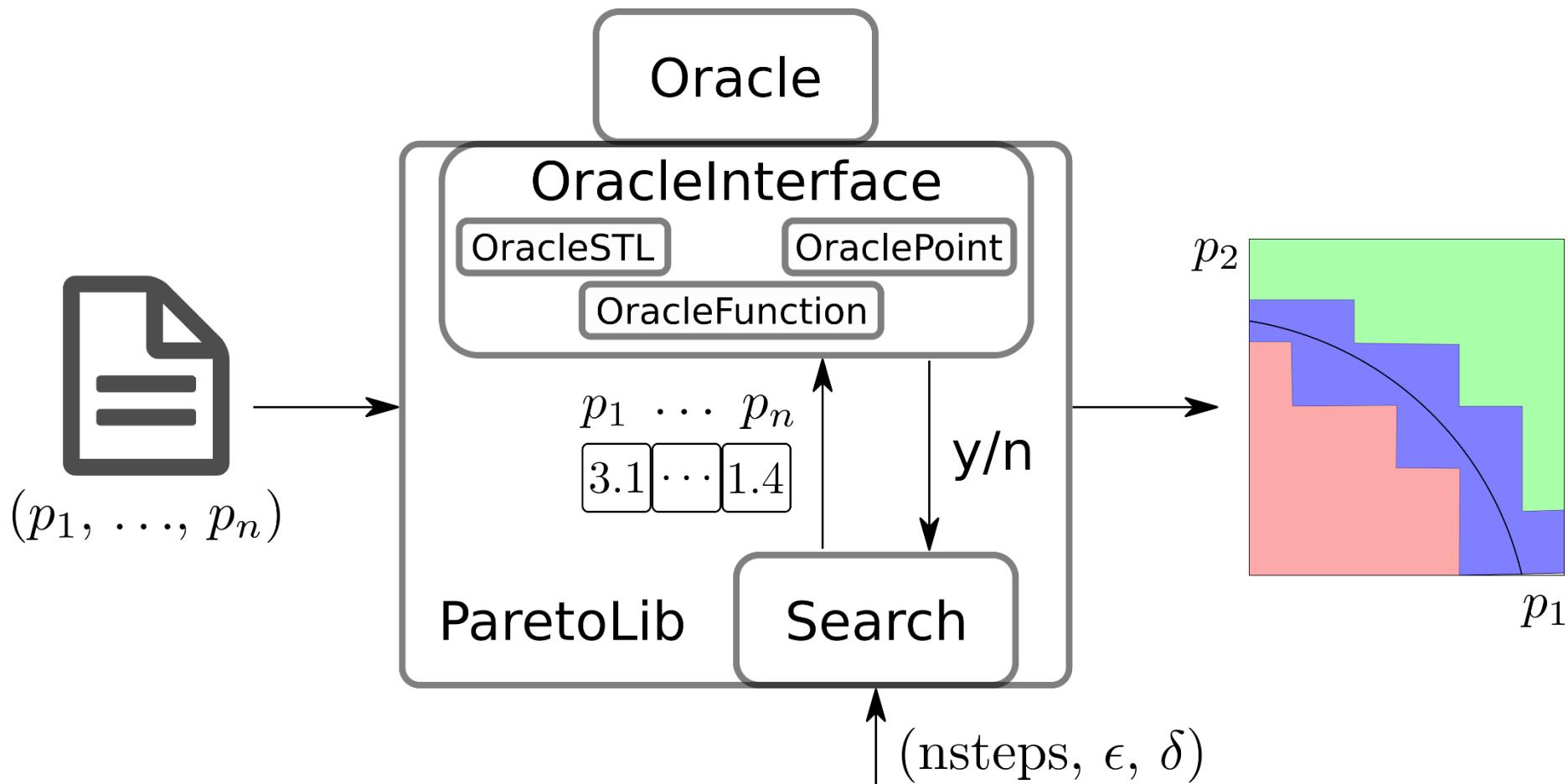
■ Python library for solving multi-criteria optimization problems:

- ▶ Faster convergence than pre-dating similar algorithms
- ▶ Parallel computation in multi-core CPU's
- ▶ Generic interface for domain-specific decision procedures (Oracle)

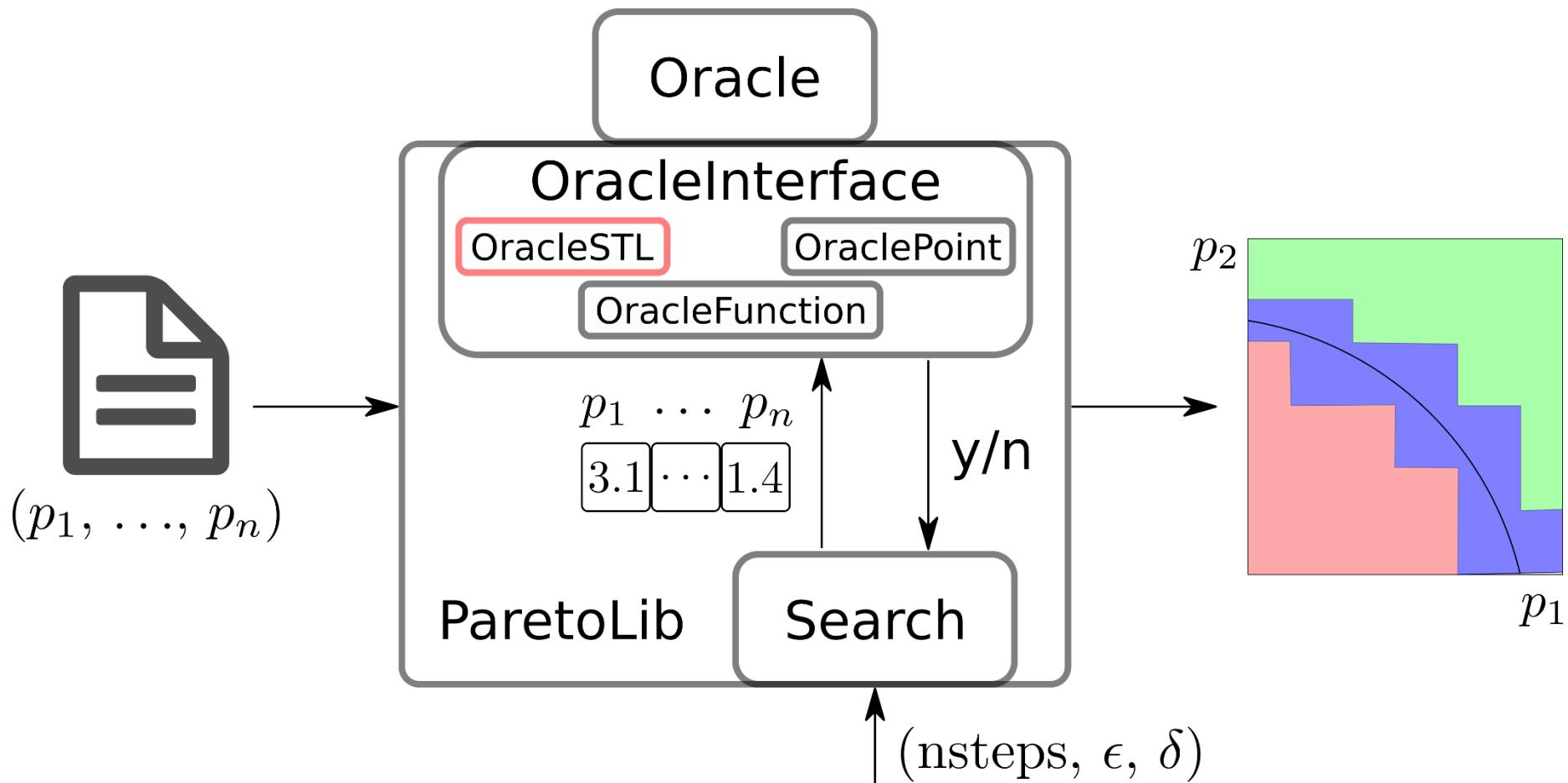
■ Application to parameter synthesis:

- ▶ Integration with Signal Temporal Logic runtime monitors
- ▶ Experiments with parametric Signal Temporal Logic specifications

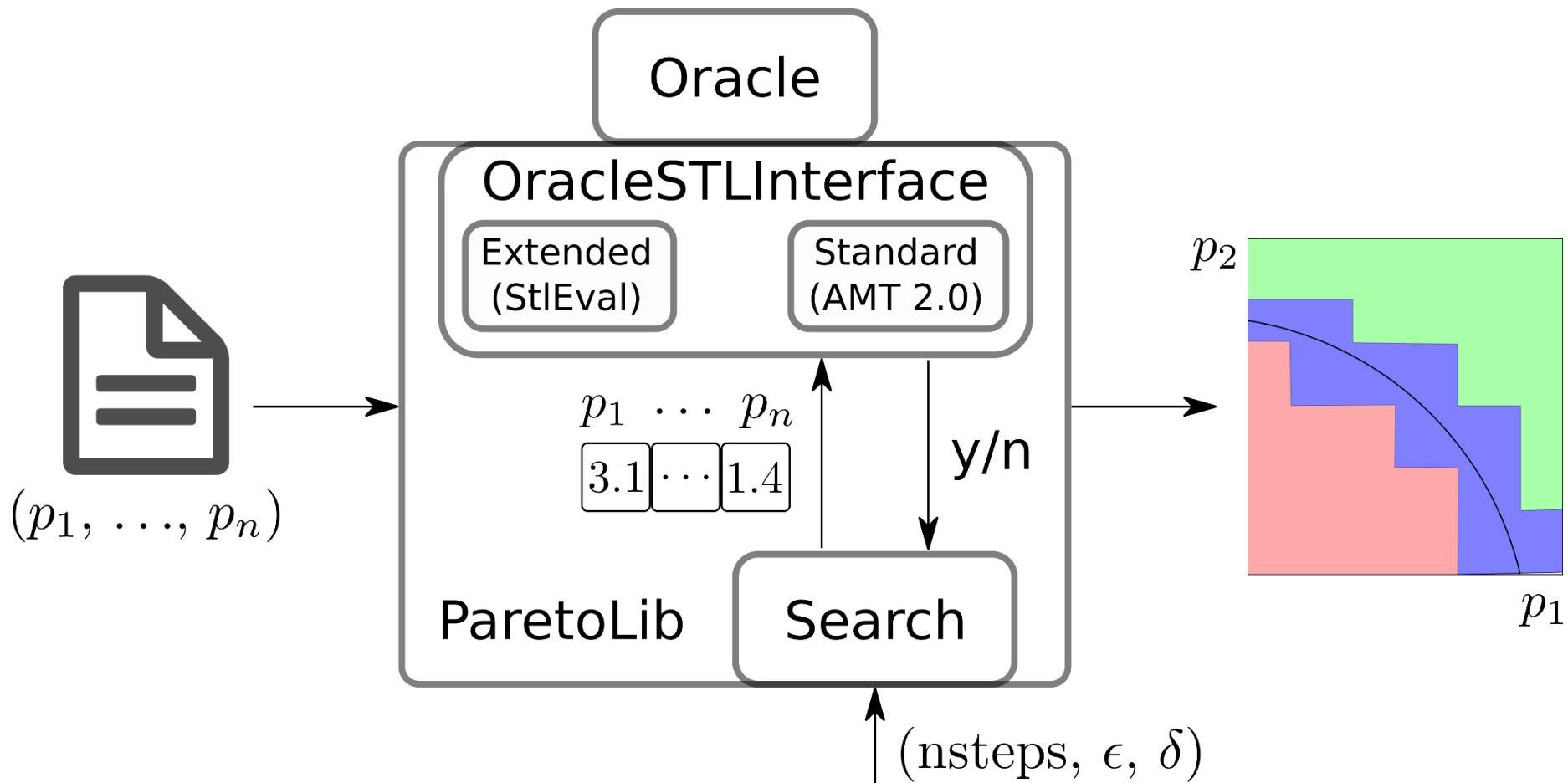
PARETOLIB LIBRARY



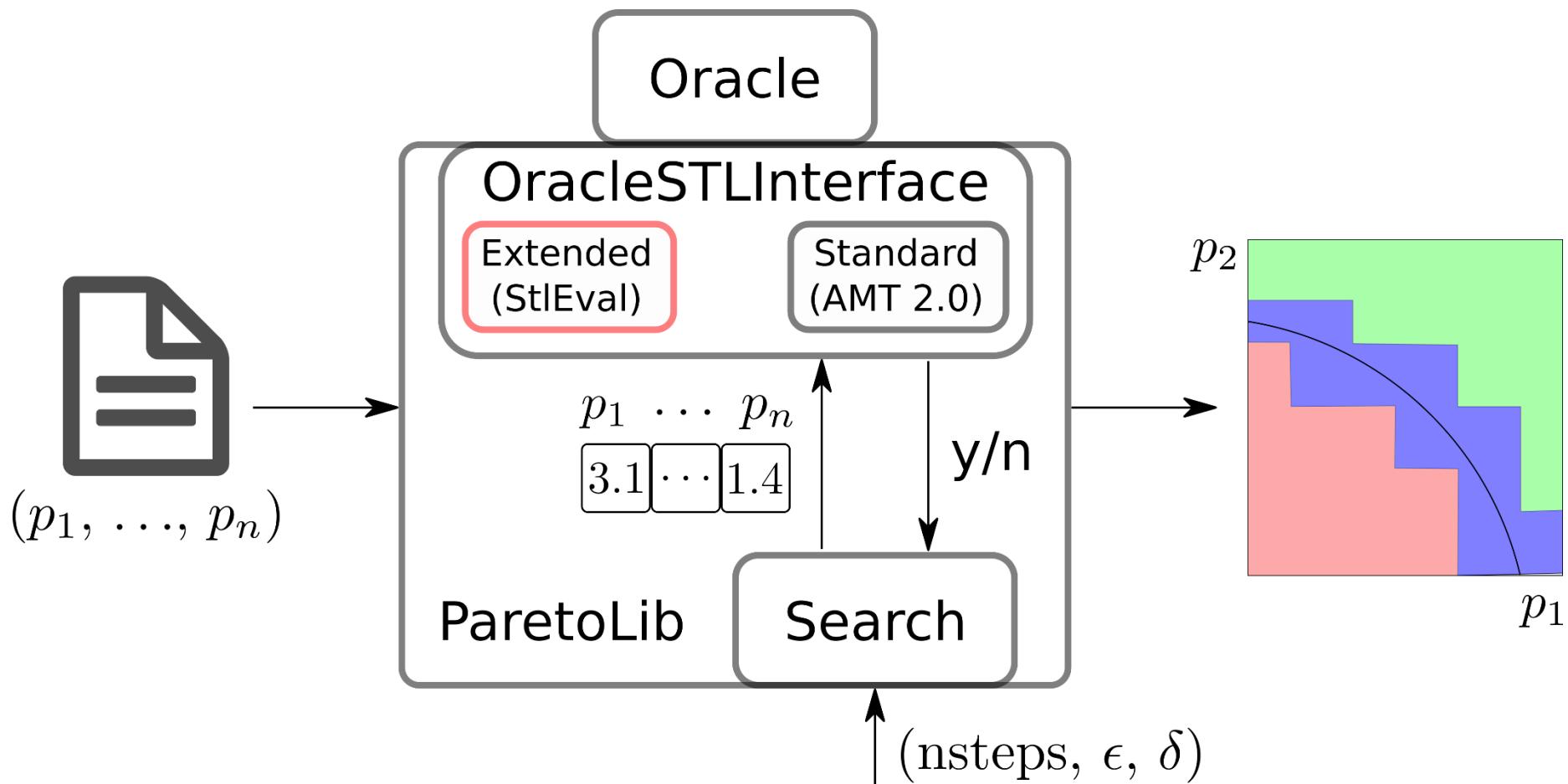
PARETOLIB LIBRARY



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PARETOLIB LIBRARY





PARETOLIB LIBRARY

```
from ParetoLib.Oracle.OracleSTLe import OracleSTLeLib
from ParetoLib.Search.Search import Search2D, EPS, DELTA, STEPS

# Definition of the n-dimensional space
min_x, min_y = (0.0, 0.0)
max_x, max_y = (300.0, 1.0)

# File containing the definition of the Oracle
nfile='Tests/Search/OracleSTLe/2D/stabilization.txt'
oracle = OracleSTLeLib()
oracle.from_file(nfile, human_readable=True)

rs=Search2D(ora=oracle,
            min_cornerx=min_x,min_cornery=min_y,
            max_cornerx=max_x,max_cornery=max_y,
            epsilon=EPS, delta=DELTA, max_step=STEPS,
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rs.fo_file("result.zip")
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p₂p₁



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OracleSTLInterface

Extended
(StlEval)

Standard
(AMT 2.0)



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```

Search

↑
(nsteps, ϵ , δ)



PARETOLIB LIBRARY

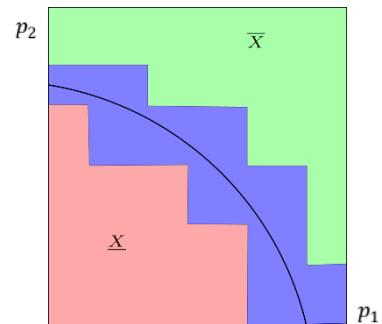
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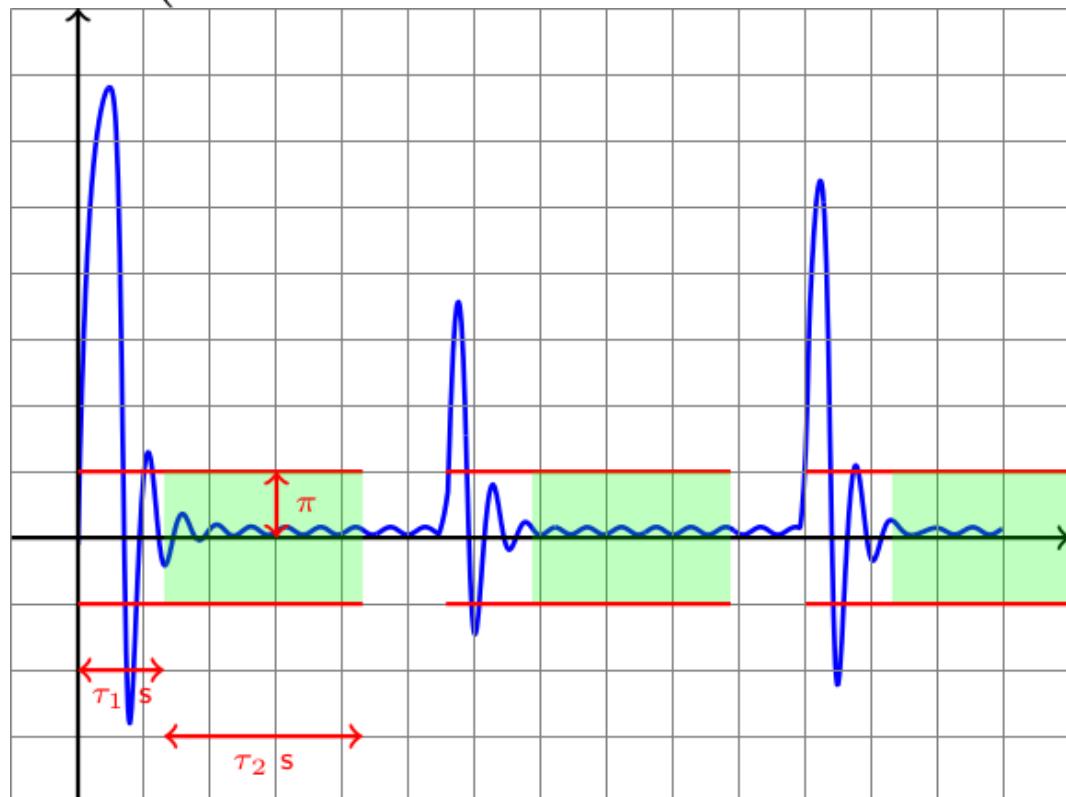
EXPERIMENTS

Experiments

EXPERIMENTS

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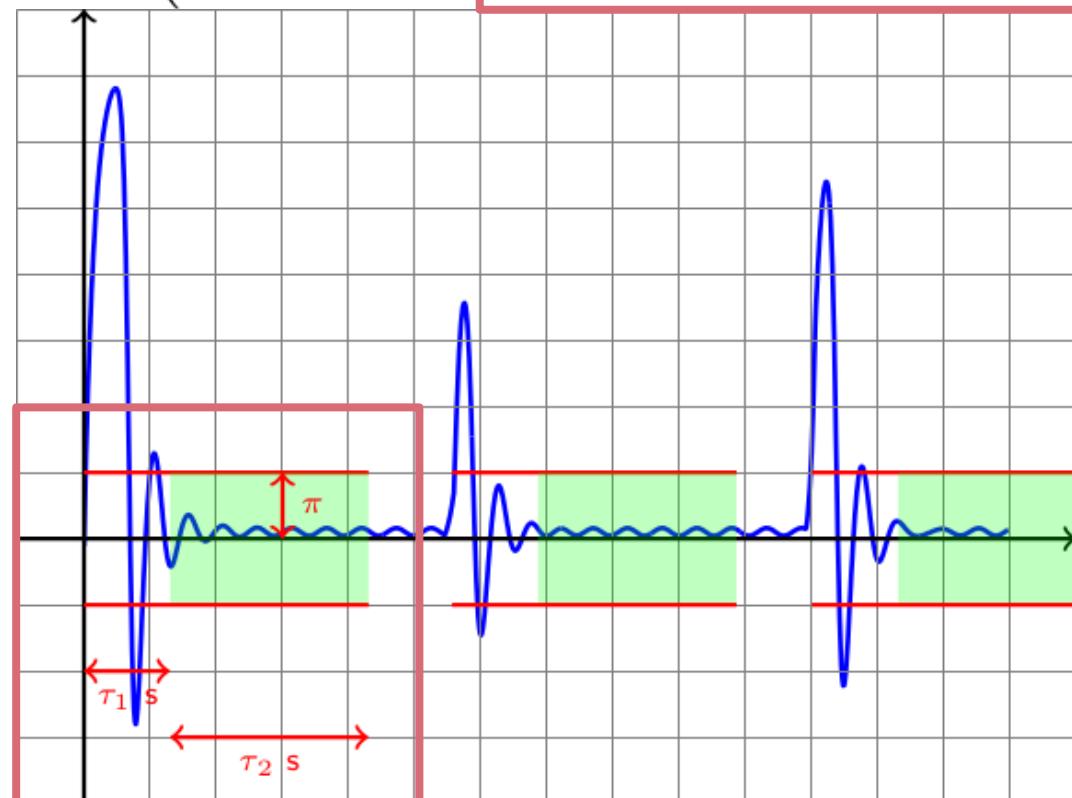
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EXPERIMENTS

Always $|x| > \underline{\quad}$ then after $\underline{\quad}$ s, $|x|$ settles under $\underline{\quad}$ for $\underline{\quad}$ s

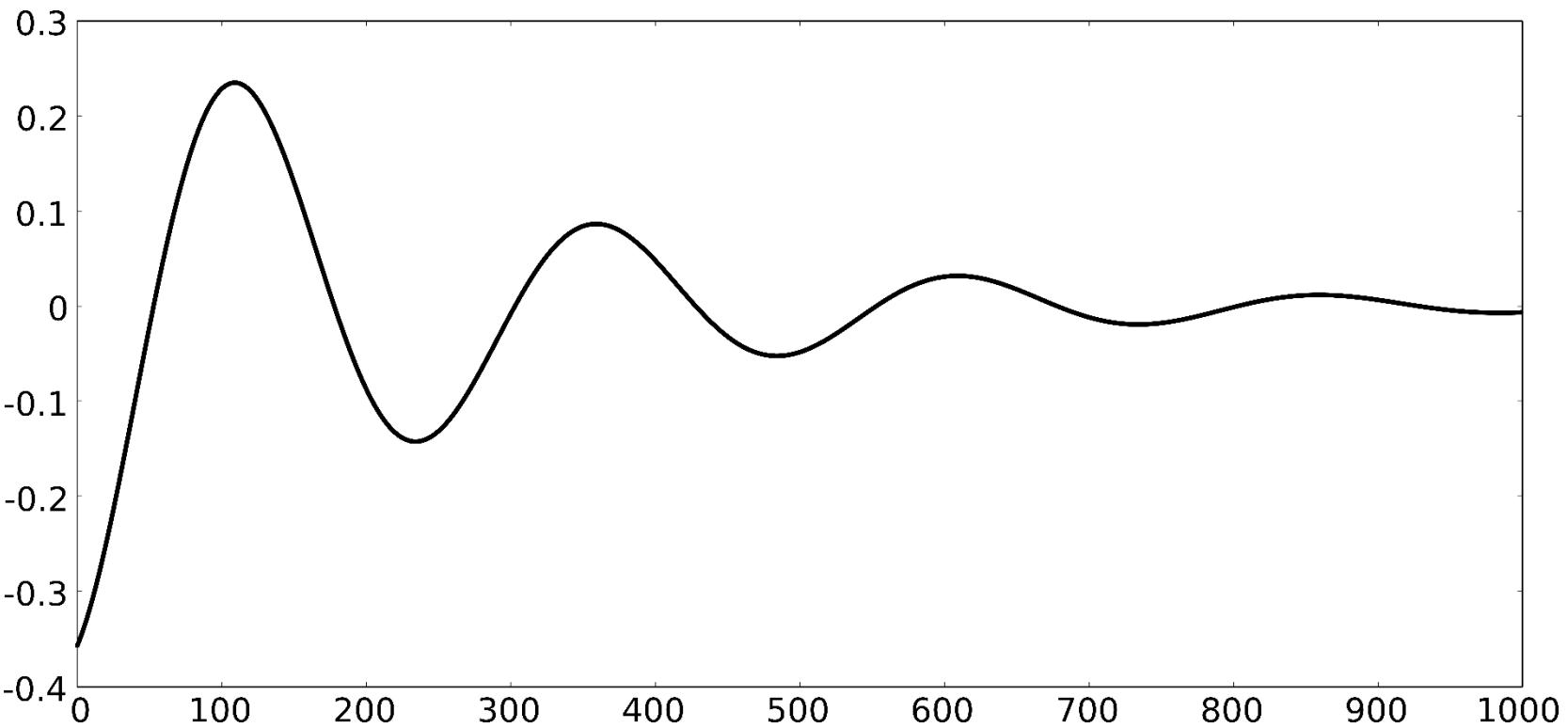
$$\varphi := G(x[t] > \pi \rightarrow F_{[0, \tau_1]} (G_{[0, \tau_2]} x[t] < \pi))$$



EXPERIMENTS

Always $|x| > p_2$ then after p_1 s, $|x|$ settles under p_2 indefinitely

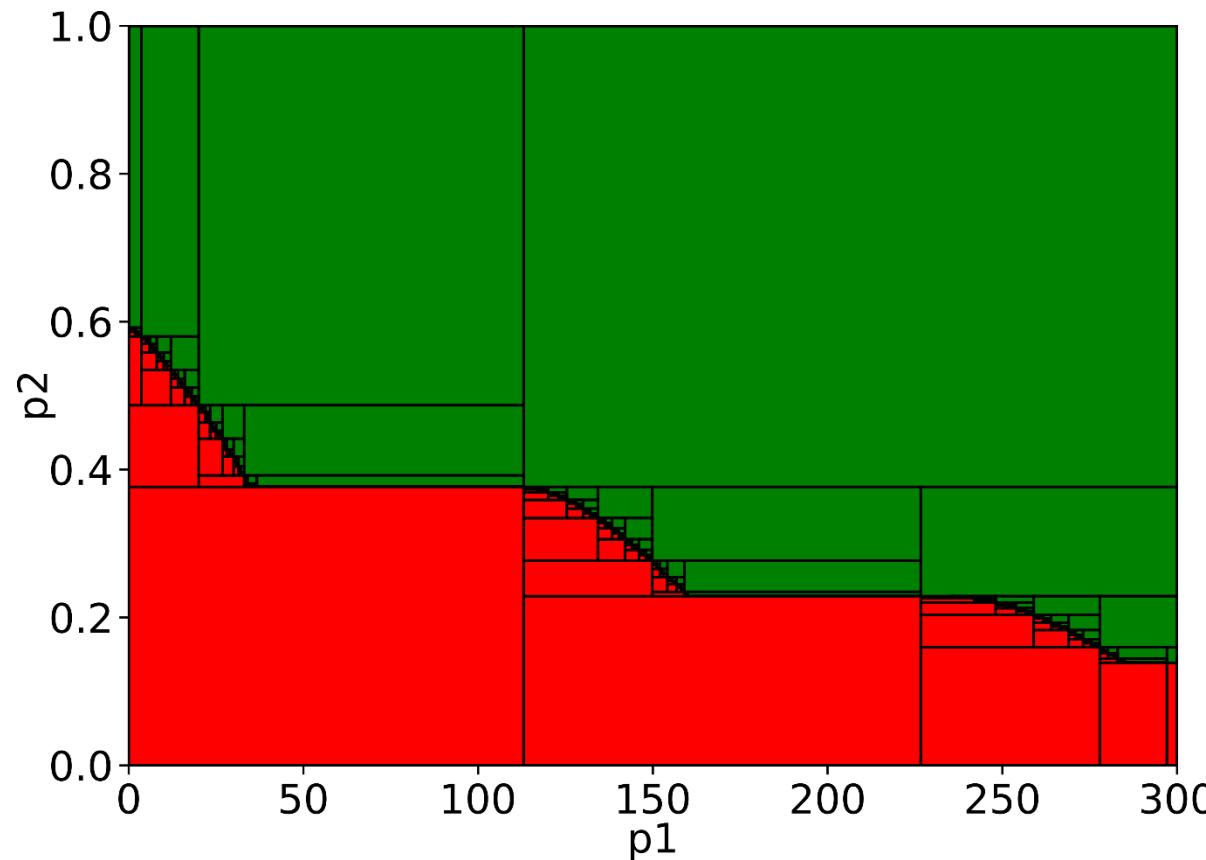
$$\varphi := F_{[0,p_1]} G_{[0,\infty]} (\text{On}_{[0,\infty]} \text{Max } x - \text{On}_{[0,\infty]} \text{Min } x) < p_2$$



EXPERIMENTS

Always $|x| > p_2$ then after p_1 s, $|x|$ settles under p_2 indefinitely

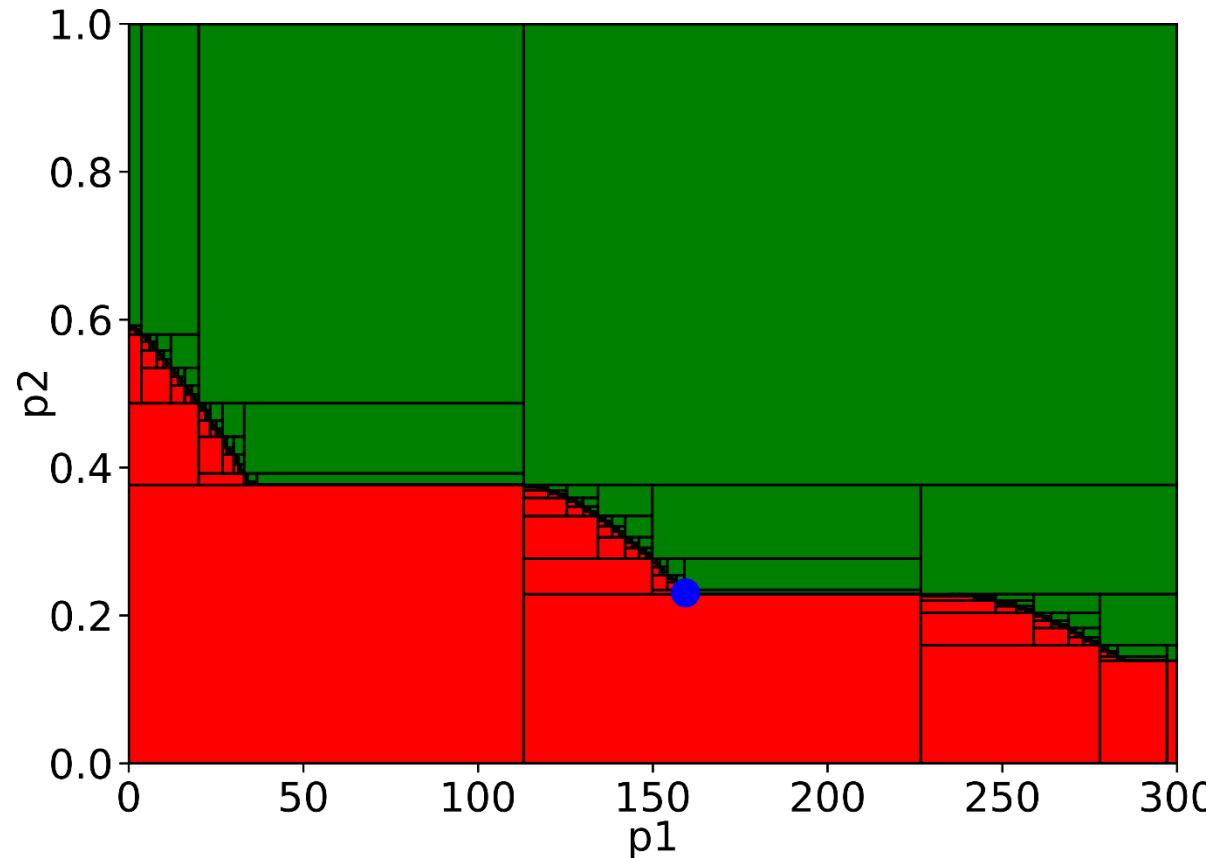
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EXPERIMENTS

Always $|x| > 0.25$ then after 155 s, $|x|$ settles under 0.25 indefinitely

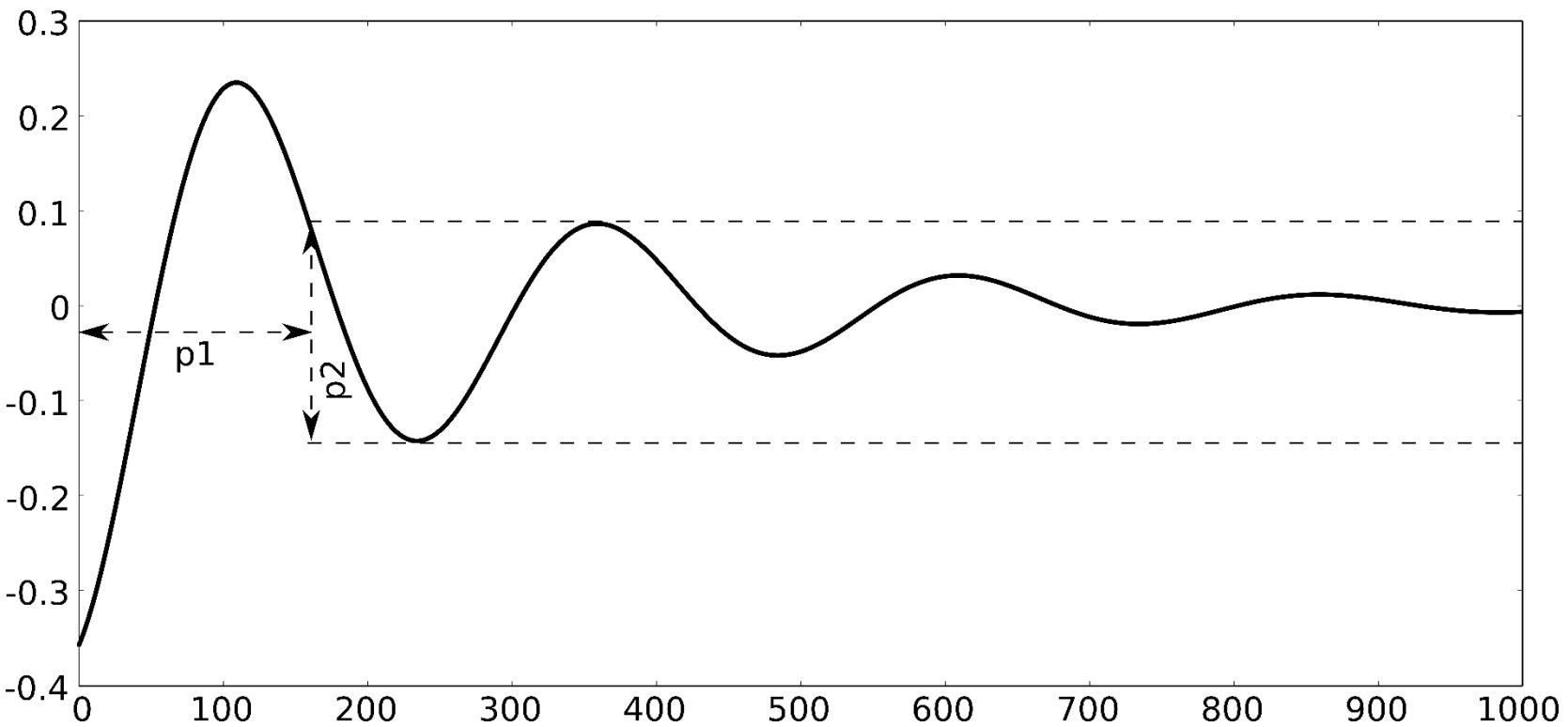
$$\varphi := F_{[0,155]} G_{[0,\infty]} (\text{On}_{[0,\infty]} \text{Max } x - \text{On}_{[0,\infty]} \text{Min } x) < 0.25$$



EXPERIMENTS

Always $|x| > 0.25$ then after 155 s, $|x|$ settles under 0.25 indefinitely

$$\varphi := F_{[0,155]} G_{[0,\infty]} (\text{On}_{[0,\infty]} \text{Max } x - \text{On}_{[0,\infty]} \text{Min } x) < 0.25$$





CONCLUSIONS

Conclusions



CONCLUSIONS

- **Python library for solving multi-criteria optimization problems:**
 - ▶ Faster convergence than pre-dating similar algorithms
 - ▶ Parallel computation in multi-core CPU's
 - ▶ Generic interface for domain-specific decision procedures (Oracle)
- **Application to parameter synthesis:**
 - ▶ Integration with Signal Temporal Logic runtime monitors
 - ▶ Experiments with parametric Signal Temporal Logic specifications

FUTURE WORK

■ Python library for solving multi-criteria optimization problems:

- ▶ Keep on improving the tool performance
- ▶ Introduction of new features

■ Application to parameter synthesis:

- ▶ Integration with new temporal logics



THE END

