

# Complexity Analysis by Polymorphic Sized Type Inference and Constraint Solving.

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# Motivation

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- worst-case **time-complexity** analysis of **functional programs**
- analysis should be **intensionally strong**, **precise**, amendable to **automation** and **modular**



## Example

---

$f :: \text{List Int} \rightarrow \text{List Int} \rightarrow \text{List (Int} \times \text{Int)}$

$f \ ms \ ns = \text{filter } (/=) \ (\text{product } ms \ ns)$

$\text{product} :: \forall \alpha \beta. \text{List } \alpha \rightarrow \text{List } \beta \rightarrow \text{List } (\alpha \times \beta)$

$\text{product } ms \ ns = \text{foldr } (\lambda \ m \ ps. \text{foldr } (\lambda \ n. \text{Cons } (n, m)) \ ps \ ns) \ \text{Nil } ms$

$\text{filter} :: \forall \alpha. (\alpha \rightarrow \text{Bool}) \rightarrow \text{List } \alpha \rightarrow \text{List } \alpha$

$\text{filter } p \ \text{Nil} = \text{Nil}$

$\text{filter } p \ (\text{Cons } x \ xs) = \text{if } p \ x$   
                                  then  $\text{Cons } x \ (\text{filter } p \ xs)$   
                                  else  $\text{filter } p \ xs$

$\text{foldr} :: \forall \alpha \beta. (\alpha \rightarrow \beta \rightarrow \beta) \rightarrow \beta \rightarrow \text{List } \alpha \rightarrow \beta$

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## Higher-order combinators are hard to analyse...

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`foldr`  $(\circ) b [e_1, e_2, \dots, e_n] = e_1 \circ (e_2 \circ (\dots (e_n \circ b) \dots))$

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complexity depends very much on how (`o`) uses its arguments

1. `foldr append Nil` [`e`<sub>1</sub>, `e`<sub>2</sub>, ..., `e`<sub>*n*</sub>]

⇒ complexity  $O(n \cdot m)$ , where  $m$  binds length of `e`<sub>*i*</sub>'s



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3. `foldr` ( $\lambda e.$ `Cons` (`append xs e`)) `Nil` [`e`<sub>1</sub>, `e`<sub>2</sub>, ..., `e`<sub>*n*</sub>]  
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size analysis crucial step in runtime analysis  
complexity depends not only on arguments, but also  
on the environment

# Sized-types

## 1. annotate datatypes with sizes

$\text{List}_1 \alpha, \text{List}_2 \alpha, \text{List}_3 \alpha, \dots$

## 2. extended type system that enables reasoning about sizes

$\text{append} :: \forall ij. \text{List}_i \alpha \rightarrow \text{List}_j \alpha \rightarrow \text{List}_{i+j} \alpha$

## 3. inference generates set of constraints, solved by external tool (e.g. SMT solver)

### Proving the Correctness of Reactive Systems Using Sized Types

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#### Abstract

We have designed and implemented a type-based analysis for proving state-logic properties of reactive systems. The analysis introduces rich type expressions that reason about the size of externally defined data structures. Sized types are useful for detecting deadlocks, non-termination, and other errors in embedded programs. To establish the soundness of the analysis we have developed an appropriate semantic model of sized types.

#### 1 Embedded Functional Program

In a reactive system, the control software must continuously react to inputs from the environment. We abstract such a reactive system into the embedded functional program. This class of programs appears to be large enough for many purposes [2] and is the core of many current frameworks that model reactive architectures, including *react*.

The foundational criterion for the correctness of programs embedded in reactive systems is safety. Before considering the properties of the output, we want to ensure that there is no output at the first place; the program must continuously react to the input stream by producing elements on the output stream. This latter property may fail in various ways:

- the computation of a stream element may depend on itself creating a “black hole”;
- the computation of one of the output streams may depend on elements from some later element in different streams; this may happen;
- the computation of a stream element may require the physical resources of the machine to vary diverge.

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Reactive systems are typically written in C++ or Java. The analysis is implemented in Haskell. The analysis is available as a library on the Haskell package manager Hackage. For more information, see the project page at <http://www.chalmers.se/~juhu>.

To support the use of high-level functional languages in embedded systems we have developed an analysis that checks the fundamental correctness properties of an embedded functional program, i.e. that the computations of each stream element terminate. The main component of our analysis is a (non-standard) type system that can reason formally on the size of reactive data structures. Experience with the implementation indicates that the system works reasonably well for small but realistic programs.

The next section motivates the use of sized types for reasoning about reactive systems. Section 3 motivates the design and semantics of a small functional language with sized types. The next two sections present the type inference rules, establish their soundness with respect to our semantic model of types, and give some examples that illustrate some of their strengths and weaknesses. Section 5 is a deal with the details of the implementation and our experience in using it. Before concluding we mention related work.

#### 2 Sized Types

Various basic properties of reactive systems can be established using a notion of “sized types”. We laterally motivate this notion and focus on reasoning about stream computation using sized types.

#### 2.1 Productivity

In a conventional high-level functional language, the datatype of streams of natural numbers would be defined as

```
data Stream = Nil | Cons !Nat !Stream
```

The declaration introduces a new constructor *Nil* which gives a natural number and a stream point to a new stream, i.e., a list type  $\text{Nat} \times \text{Stream}$  or  $\text{Nat} \times \text{Stream}$ . From simple program that use this datatype we can

```
head (MkStream n) = n  
tail (MkStream n) = s  
-- type Stream = Nat  
-- type Stream = Stream
```

A naive inverting program is

```
inverted (MkStream n) = MkStream (tail (MkStream n))
```

which computes an infinite stream of 0's. Its first element, which may contain another *s*, is never for its result.

# From sized-types to time complexity

---

idea: instrument program to compute complexity

$$\langle \tau \rightarrow \rho \rangle \Rightarrow \langle \tau \rangle \rightarrow \mathbf{N} \rightarrow (\langle \rho \rangle \times \mathbf{N});$$



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$$\langle \tau \rightarrow \rho \rangle \Rightarrow \langle \tau \rangle \rightarrow \mathbf{N} \rightarrow (\langle \rho \rangle \times \mathbf{N});$$

$\text{foldr}_3 :: \forall \alpha \beta. \langle \alpha \rightarrow \beta \rightarrow \beta \rangle \rightarrow \langle \beta \rangle \rightarrow \langle \text{List } \alpha \rangle \rightarrow \mathbf{N} \rightarrow (\langle \beta \rangle \times \mathbf{N})$

$\text{foldr}_3 f b \text{ Nil} \quad t = (b, \text{Succ } t)$

$\text{foldr}_3 f b (\text{Cons } x \text{ xs}) t = \text{let } (e_1, t_1) = \text{foldr}_3 f b \text{ xs } t$

$\text{in let } (e_2, t_2) = f \ x \ t_1$

$\text{in let } (e_3, t_3) = e_2 \ e_1 \ t_2$

$\text{in } (e_3, \text{Succ } t_3)$

$\text{foldr}_1 :: \forall \alpha \beta. \langle \alpha \rightarrow \beta \rightarrow \beta \rangle \rightarrow \mathbf{N} \rightarrow (\langle \beta \rightarrow \text{List } \alpha \rightarrow \beta \rangle \times \mathbf{N})$

$\text{foldr}_1 f t = (\text{foldr}_2 f, t)$

$\text{foldr}_2 :: \forall \alpha \beta. \langle \alpha \rightarrow \beta \rightarrow \beta \rangle \rightarrow \langle \beta \rangle \rightarrow \mathbf{N} \rightarrow (\langle \text{List } \alpha \rightarrow \beta \rangle \times \mathbf{N})$

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## Practical sized-type analysis (i)

- consider reversal of lists:

$\text{rev} :: \forall \alpha. \text{List } \alpha \rightarrow \text{List } \alpha \rightarrow \text{List } \alpha$

$\text{rev Nil} \quad ys = ys$

$\text{rev (Cons } x \text{ xs)} \quad ys = \text{rev xs (Cons } x \text{ ys)}$

- usual let-polymorphism requires that recursive call is typed under monotype, ...
- in sized-type setting, types of e.g. second argument changes from  $\text{List}_i \alpha$  to  $\text{List}_{i+1} \alpha$

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**extension ①:** type recursive calls with type polymorphic in size indices

## Practical sized-type analysis (ii)

---

- consider higher-order combinator `twice`:

`twice` ::  $\forall \alpha. (\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha$

`twice`  $f x = f (f x)$

- term `twice Succ`, where `Succ` ::  $\forall i. \mathbf{N}_i \rightarrow \mathbf{N}_{i+1}$ , cannot be typed





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**extension ②: arbitrary-rank index polymorphic**

$$\text{twice} :: \forall i. (\forall j. \mathbf{N}_j \rightarrow \mathbf{N}_{j+1}) \rightarrow \mathbf{N}_i \rightarrow \mathbf{N}_{i+2}$$
$$\text{foldr} :: \forall klm. (\forall ij. \mathbf{N}_i \rightarrow \mathbf{L}_j \rightarrow \mathbf{L}_{j+k}) \rightarrow \mathbf{L}_l \rightarrow \mathbf{L}_m \rightarrow \mathbf{L}_{k \cdot m + l}$$

# Sized-types revisited

## Computational model

(simple types)	$\tau, \rho ::= \mathbf{B}$   $\tau \times \rho$   $\tau \rightarrow \rho$	<i>base type</i> <i>pair type</i> <i>function type</i>
(expressions)	$s, t ::= x^\tau$   $\mathbf{f}^\tau$   $\mathbf{c}^\tau$   $(s^{\tau \rightarrow \rho} t^\tau)^\rho$   $(s^{\tau_1}, t^{\tau_2})^{\tau_1 \times \tau_2}$   $(\text{let } s^{\tau_1 \times \tau_2} \text{ be } (x^{\tau_1}, y^{\tau_2}) \text{ in } t^\rho)^\rho$	<i>variable</i> <i>function</i> <i>constructor</i> <i>application</i> <i>pair</i> <i>pair destructor</i>
(patterns)	$p ::= x^\tau \mid (\mathbf{c}^{\tau_1 \rightarrow \dots \rightarrow \tau_n \rightarrow \mathbf{B}} p_1^{\tau_1} \dots p_n^{\tau_n})^\mathbf{B}$	
(equations)	$e ::= (\mathbf{f} p_1 \dots p_n)^\tau = s^\tau$	

- **program** P is set of non-overlapping, left-linear equations

# Sized-types revisited

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## *computational model*

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- call-by-value reduction semantics
- plain simple types, e.g. **NatList** instead of **List N**, for simplicity
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# Sized-types revisited

## *computational model*

- call-by-value reduction semantics
- plain simple types, e.g. **NatList** instead of **List N**, for simplicity
  - extension to polymorphic setting straight forward
- no conditionals, case-expressions,  $\lambda$ -abstractions ...
  - does not improve expressiveness of our language
  - again straight forward to incorporate



# Sized-types revisited

## *ingredients*

(type)

$$\begin{aligned} \tau, \rho ::= & B_a \\ & | \tau \times \rho \\ & | \sigma \rightarrow \tau \end{aligned}$$

*indexed base type*

*pair type*

*function type*

(schema)

$$\sigma ::= B_a \mid \forall \vec{i}. \sigma \rightarrow \tau$$





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(size index)	$a, b ::= i$   $f(a_1, \dots, a_k)$	<i>index variable</i> <i>function application</i>

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- quantification to the right of arrow does not add in strength
- meaning to index functions  $f$  given by a **weakly monotonic** interpretation  $\llbracket f \rrbracket : \mathbb{N}^k \rightarrow \mathbb{N}$

# Type-checking

## *auxiliary notions*

- each **function f declared** by one or more closed schemas  $\sigma$ , in notation  $f :: \sigma$ , obeying to the following restrictions:

1. datatypes to the left of arrow annotated by variables

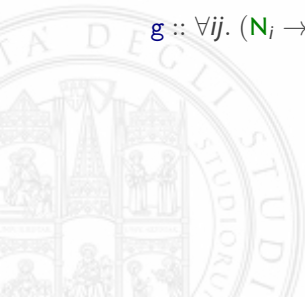
$$\mathbf{half} :: \forall i. \mathbf{N}_{2 \cdot i} \rightarrow \mathbf{N}_i \quad \Rightarrow \quad \mathbf{half} :: \forall i. \mathbf{N}_i \rightarrow \mathbf{N}_{i/2}$$

2. all these variables must be pairwise distinct

$$\mathbf{f} :: \forall i. \mathbf{N}_i \rightarrow \mathbf{N}_i \rightarrow \tau \quad \Rightarrow \quad \mathbf{f} :: \forall ij. \mathbf{N}_i \rightarrow \mathbf{N}_j \rightarrow \tau'$$

3. schema closes over all variables occurring in negative position

$$\mathbf{g} :: \forall ij. (\mathbf{N}_i \rightarrow \mathbf{N}_{i+j}) \rightarrow \tau \quad \Rightarrow \quad \mathbf{g} :: \forall j. (\forall i. \mathbf{N}_i \rightarrow \mathbf{N}_{i+j}) \rightarrow \tau$$



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- typing judgement** are of the form

$$x_1 : \sigma_1, \dots, x_n : \sigma_n \vdash s : \tau$$

# Type-checking

*excerpt*

$$\frac{[[a]] \leq [[b]]}{B_a \sqsubseteq B_b} \quad \frac{\sigma_2 \sqsubseteq \sigma_1 \quad \tau_1 \sqsubseteq \tau_2}{\sigma_1 \rightarrow \tau_1 \sqsubseteq \sigma_2 \rightarrow \tau_2} \quad \frac{\tau_1 \sqsubseteq \tau_2\{\vec{a}/\vec{j}\} \quad \vec{i} \notin \text{FV}(\forall \vec{j}. \tau_2)}{\forall \vec{i}. \tau_1 \sqsubseteq \forall \vec{j}. \tau_2}$$

Figure: subtyping.

$$\frac{\Gamma(x) = \forall \vec{i}. \tau}{\Gamma \vdash x : \tau\{\vec{a}/\vec{i}\}} \quad \frac{\mathbf{f} :: \forall \vec{i}. \tau}{\Gamma \vdash \mathbf{f} : \tau\{\vec{a}/\vec{i}\}}$$
$$\frac{\Gamma \vdash s : (\forall \vec{i}. \rho) \rightarrow \tau \quad \Gamma \vdash t : \rho \quad \vec{i} \notin \text{FV}(\Gamma)}{\Gamma \vdash s t : \tau} \quad \frac{\Gamma \vdash s : \rho \quad \rho \sqsubseteq \tau}{\Gamma \vdash s : \tau}$$

Figure: type-checking.



# Subject reduction

## Definition

A program  $P$  is **well-typed** if for all equations  $f\ p_1 \cdots p_n = r$  of  $P$ ,

$$\Gamma \vdash_{\text{FP}} f\ p_1 \cdots p_n : \tau \implies \Gamma \vdash r : \tau,$$

holds for all contexts  $\Gamma$  and types  $\tau$ .



# Subject reduction

## Definition

A program  $P$  is **well-typed** if for all equations  $f\ p_1 \cdots p_n = r$  of  $P$ ,

$$\Gamma \vdash_{\text{FP}} f\ p_1 \cdots p_n : \tau \implies \Gamma \vdash r : \tau,$$

holds for all contexts  $\Gamma$  and types  $\tau$ .

- the **footprint** judgement assigns to terms “most general” type, e.g.,

$$x : \mathbf{N}, xs : \mathbf{L}_i, ys : \mathbf{L}_j \vdash_{\text{FP}} \text{append} (\text{Cons } x\ xs)\ ys : \mathbf{L}_{(i+1)+j}$$

where  $\text{append} :: \forall ij. \mathbf{L}_i \rightarrow \mathbf{L}_j \rightarrow \mathbf{L}_{i+j}$

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## Theorem (Subject reduction)

Suppose  $P$  is well-typed. If  $\vdash s : \tau$  and  $s \rightarrow_P t$  then  $\vdash t : \tau$ .

# Inference

---

## *overview*

- index language extended with **second-order** index variables **A**

$$a ::= i \mid f(a_1, \dots, a_k) \mid \mathbf{A}$$

- second-order index variable **A** represents index term



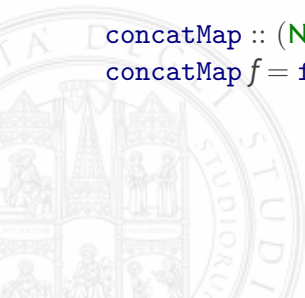
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concatMap :: (N → L) → L → L    lam :: (N → L) → N → L → L
concatMap f = foldr (lam f) Nil    lam f x = append (f x)
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- outputs**
  - size-annotated type declarations
  - semantic interpretation functions  $\llbracket \cdot \rrbracket$

# Inference

## step ①: annotation

decorate simple types with uninterpreted indices

**append** ::  $\forall ij. \mathbf{L}_i \rightarrow \mathbf{L}_j \rightarrow \mathbf{L}_{\text{apd}(i,j)}$

**lam** ::  $\forall jkl. (\forall i. \mathbf{N}_i \rightarrow \mathbf{L}_{f(i,j)}) \rightarrow \mathbf{N}_k \rightarrow \mathbf{L}_l \rightarrow \mathbf{L}_{lm(j,k,l)}$

**foldr** ::  $\forall klm. (\forall ij. \mathbf{N}_i \rightarrow \mathbf{L}_j \rightarrow \mathbf{L}_{g(i,j,k)}) \rightarrow \mathbf{L}_l \rightarrow \mathbf{L}_m \rightarrow \mathbf{L}_{fld(k,l,m)}$





# Inference

---

## *step ②: constraint generation*

for all equations in P, generate **two sets of constraints**, e.g. for

`lam f x = append (f x)`

as follows



# Inference

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$$\text{footprint}(\text{lam } f\ x) = (\underbrace{\{f : \forall i. \mathbf{N}_i \rightarrow \mathbf{L}_{f(i,j)}, x : \mathbf{N}_k\}}_{:=\Gamma}, \underbrace{\mathbf{L}_l \rightarrow \mathbf{L}_{lm(j,k,l)}}_{:=\tau})$$



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2. **inference**  $\text{infer}(\Gamma, r)$  on right-hand side  $r$  generates template for  $r$  and first set of constraints

$$\text{infer}(\Gamma, \text{append } (f\ x)) = (\mathbf{L}_{A_3} \rightarrow \mathbf{L}_{\text{apd}(A_2, A_3)}, \{f(A_1, j) \leq A_2, k \leq A_1\})$$

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3. **well-typedness** condition enforced by second set of constraints

$$\text{subtypeOf}(\mathbf{L}_{A_3} \rightarrow \mathbf{L}_{\text{apd}(A_1, A_2)}, \tau) = \{l \leq A_3, \text{apd}(A_1, A_2) \leq lm(j, k, l)\}$$

# Inference

## step ②: constraint generation

$$\frac{\{a \leq b\} \vdash_{\text{ST}} B_a \sqsubseteq B_b}{\frac{C_1 \vdash_{\text{ST}} \sigma_2 \sqsubseteq \sigma_1 \quad C_2 \vdash_{\text{ST}} \tau_1 \sqsubseteq \tau_2}{C_1 \cup C_2 \vdash_{\text{ST}} \sigma_1 \rightarrow \tau_1 \sqsubseteq \sigma_2 \rightarrow \tau_2}} \quad \frac{C \vdash_{\text{ST}} \tau_1 \sqsubseteq \tau_2 \{\vec{a}/\vec{j}\} \quad \vec{i} \notin \text{FV}(\forall \vec{j}. \tau_2)}{C \vdash_{\text{ST}} \forall \vec{i}. \tau_1 \sqsubseteq \forall \vec{j}. \tau_2}$$

Figure: subtyping.

$$\frac{\frac{\Gamma(x) = \forall \vec{i}. \tau}{\emptyset; \Gamma \vdash_1 x : \tau \{\vec{a}/\vec{i}\}} \quad \frac{\mathbf{f} :: \forall \vec{i}. \tau}{\emptyset; \Gamma \vdash_1 \mathbf{f} : \tau \{\vec{a}/\vec{i}\}}}{\frac{C_1; \Gamma \vdash_1 s : (\forall \vec{i}. \rho) \rightarrow \tau \quad C_2; \Gamma \vdash_1 t : \rho' \quad C_3 \vdash_{\text{ST}} \rho' \sqsubseteq \rho \quad \vec{i} \notin \text{FV}(\Gamma)}{C_1, C_2, C_3; \Gamma \vdash_1 s t : \tau}}$$

Figure: type inference.

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# Inference

## step ③: *constraint solving*

- find a model  $(\vartheta, \llbracket \cdot \rrbracket)$  for collected constraints  $C$  consisting of
  - $\vartheta$  assigns index terms to second-order variables
  - $\llbracket \cdot \rrbracket$  assigns meaning to index functions

$$(\vartheta, \llbracket \cdot \rrbracket) \models C \quad :\Leftrightarrow \quad \begin{cases} \llbracket l \vartheta \rrbracket \leq \llbracket r \vartheta \rrbracket & \text{for all } l \leq r \in C \\ i \notin \text{FV}(\vartheta(A)) & \text{for all } (i \notin A) \in C \end{cases}$$



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### 1. eliminate second-order variables by **skolemization**

$$\begin{array}{l} f(A_1, j) \leq A_2 \\ k \leq A_1 \\ l \leq A_3 \\ \text{apd}(A_1, A_2) \leq \text{lm}(j, k, l) \\ \dots \end{array} \quad \Rightarrow \quad \begin{array}{l} f(\text{sk}_1(k), j) \leq \text{sk}_2(k, j) \\ k \leq \text{sk}_1(k) \\ l \leq \text{sk}_3(l) \\ \text{apd}(\text{sk}_1(k), \text{sk}_2(k, j)) \leq \text{lm}(j, k, l) \\ \dots \end{array}$$

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- first-order constraints solvable with our tool GUBS

# Soundness and relative completeness

Theorem (Soundness and Completeness)

*Program  $P$  is well-typed if and only if  $(\vartheta, \llbracket \cdot \rrbracket) \models C$  for some  $(\vartheta, \llbracket \cdot \rrbracket)$  and constraints  $C$  generated as explained before.*



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Essential proof steps.

1.  $C \vdash_{\text{ST}} \tau \sqsubseteq \rho \iff \tau\vartheta \sqsubseteq \rho\vartheta$ , e.g.,

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□

# Conclusion

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- **ticking transformation** reduces runtime-complexity to size analysis



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- currently, whole program analysis, but ...
  - each (mutual) recursive definition gives rise to an SCC
  - bottom-up per **SCC-analysis** implemented